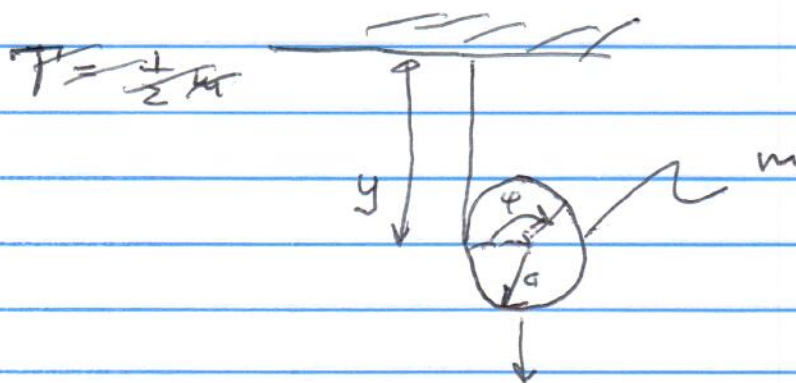


LAGRANGIAN EXAMPLE w/ CONSTRAINT

EXAMPLE OF HOW TO USE THE EULER-LAGRANGE EQN w/ CONSTRAINTS.

$$\frac{\partial L}{\partial \dot{\theta}_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}_i} + \sum \lambda_j \frac{\partial g_j}{\partial \theta_i} = 0$$

A YO-YO HAS A STRING AROUND IT ATTACHED TO A FIXED SUPPORT. YO-YO IS DROPPED AND STRING UNWINDS. FIND EQUATIONS OF MOTION AND FORCES OF CONSTRAINT.



$$T = \frac{m}{2} \dot{y}^2 + \frac{1}{2} I \dot{\phi}^2, \quad I = \frac{1}{2} ma^2 \text{ FOR DISC}$$
$$= \frac{m}{2} \dot{y}^2 + \frac{1}{4} ma^2 \dot{\phi}^2$$

$$U = -mgy \quad (+y \text{ DIRECTION DOWNWARD})$$

$$L = T - U = \frac{1}{2} m \dot{y}^2 + \frac{1}{4} ma^2 \dot{\phi}^2 + mgy \quad (0)$$

$y_0 - y_0 \text{ II}$

EQUATION OF CONSTRAINT

$$g(y, \varphi) = y - a\varphi = 0 \quad (0.5)$$

y & φ ARE GENERALIZED COORDINATES
AWAY WE GO:

$$\frac{\partial L}{\partial y} - \frac{d}{dt} \frac{\partial L}{\partial \dot{y}} + \lambda \frac{\partial g}{\partial y} = 0 \quad (1)$$

$$\frac{\partial L}{\partial \varphi} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\varphi}} + \lambda \frac{\partial g}{\partial \varphi} = 0 \quad (2)$$

FROM EQUATION (1) ABOVE

$$\frac{\partial L}{\partial y} = mg$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{y}} \right) = \frac{d}{dt} [m\dot{y}] = m\dot{y}'$$

$$\lambda \frac{\partial g}{\partial y} = \lambda$$

SO, (1) BECOMES

$$mg - m\dot{y}' + \lambda = 0 \quad (3)$$

FOR EQUATION (2) WE HAVE

$$\frac{\partial L}{\partial \varphi} = 0$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\varphi}} \right) = \frac{d}{dt} \left(\frac{1}{2} m a^2 \dot{\varphi}' \right) = \frac{1}{2} m a^2 \varphi''$$

$$\frac{\partial g}{\partial \varphi} = -a$$

YO-YO III

EQU (2) BECOMES

$$-\frac{1}{2} m a^2 \ddot{\varphi} - \tau a = 0 \quad (4)$$

SO, WE HAVE 3 KEY EQUATIONS,
2 FROM EULER-LAGRANGE AND 1
EQU OF CONSTRAINT

SOLVE (4) BY DIFFERENTIATING EQU (0.5):

$$\ddot{\varphi} = \ddot{y}/a \quad (5)$$

SUB INTO (4)

$$\begin{aligned} -\frac{1}{2} m a \ddot{y} &= \tau a \\ \lambda &= -\frac{1}{2} m \ddot{y} \\ \ddot{y} &= -2\lambda/m \end{aligned}$$

SUB LATTER INTO (3)

$$m g - m \ddot{y} + \tau = 0$$

$$m g + 2\tau + \tau = 0$$

$$\tau = -\frac{1}{3} m g$$

AND

SINCE $m g - m \ddot{y} + \tau = 0$

$$\ddot{y} = \frac{2}{3} g$$

ACCELERATION OF YO-YO CM

YO-YO IV

THE ANGULAR ACCELERATION $\ddot{\varphi}$ OF YO-YO IS GIVEN BY (5)

$$\ddot{\varphi} = \dot{y}/a$$

$$\boxed{\ddot{\varphi} = \frac{2}{3} g/a}$$

GENERALIZED FORCES:

$$\begin{aligned} Q_y &= \lambda \frac{\partial g}{\partial y} = \lambda = \frac{1}{3} mg \\ Q_\varphi &= \lambda \frac{\partial g}{\partial \varphi} = -\lambda a = \frac{1}{3} m g a \end{aligned}$$

Q_y IS TENSION IN STRING PULLING UP ON YO-YO. OTHERWISE IT WOULD FALL w/ ACCELERATION g .

Q_φ IS TORQUE ON YO-YO CAUSING IT TO ROTATE ABOUT ITS COM.