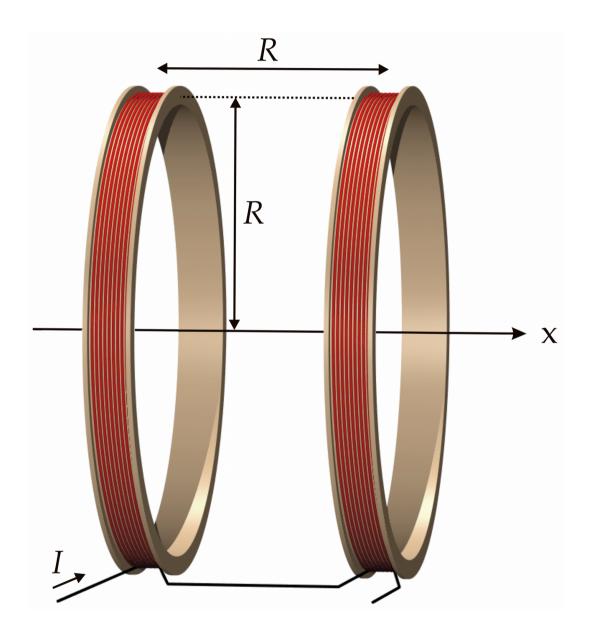
### Class Progress

Basics of Linux, gnuplot, C Visualization of numerical data Roots of nonlinear equations (Midterm 1) Solutions of systems of linear equations Solutions of systems of nonlinear equations Monte Carlo simulation Interpolation of sparse data points **Numerical integration** (Midterm 2) Solutions of ordinary differential equations

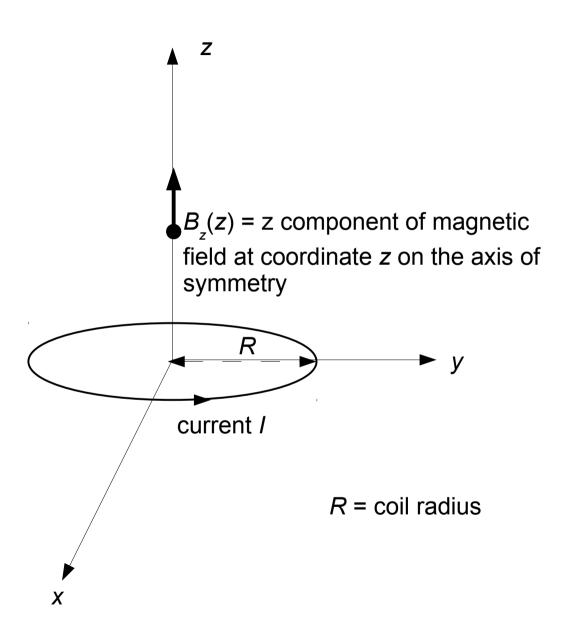


# Helmholtz Coil for Uniform Magnetic Field



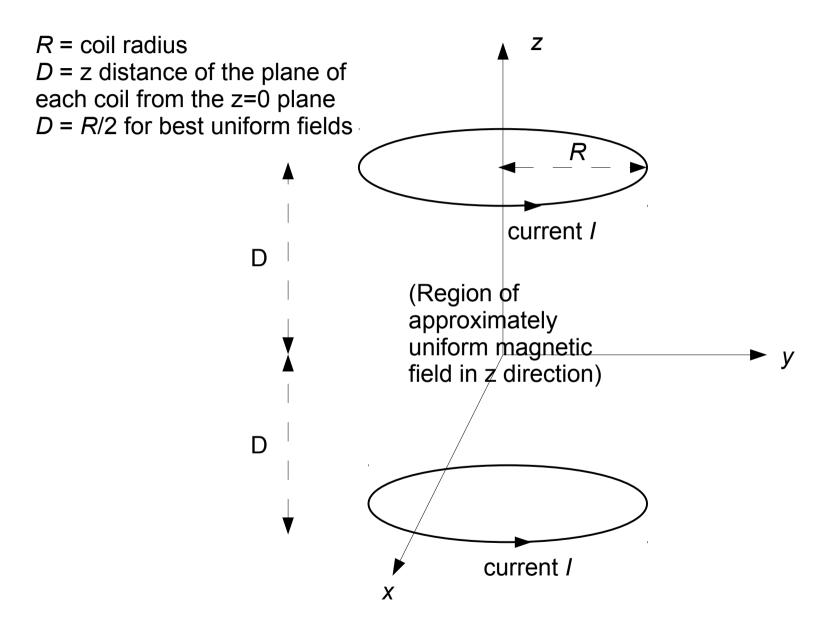


# Magnetic Field Along Axis of a Single Coil

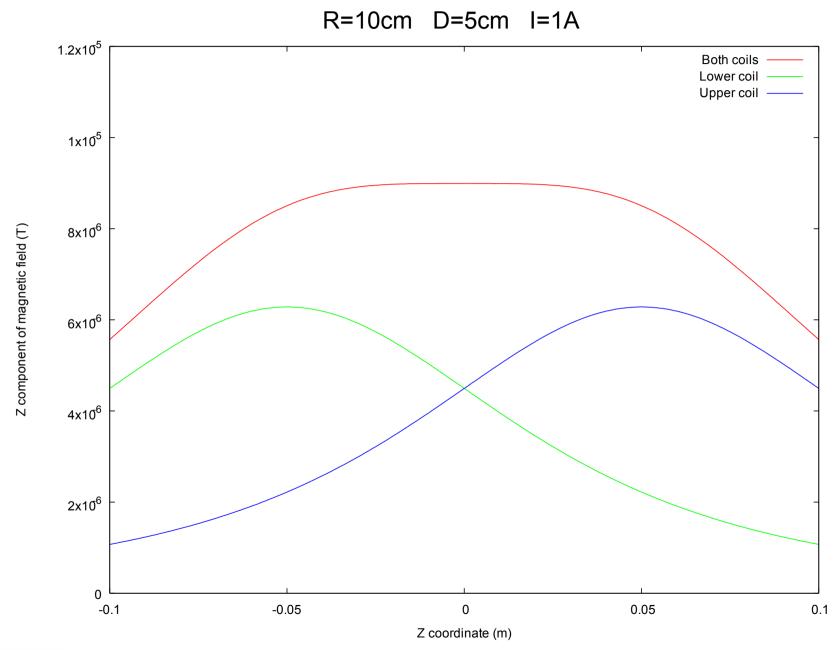


$$B_z(z) = \frac{\mu_0 I R^2}{2(R^2 + z^2)^{\frac{3}{2}}}$$

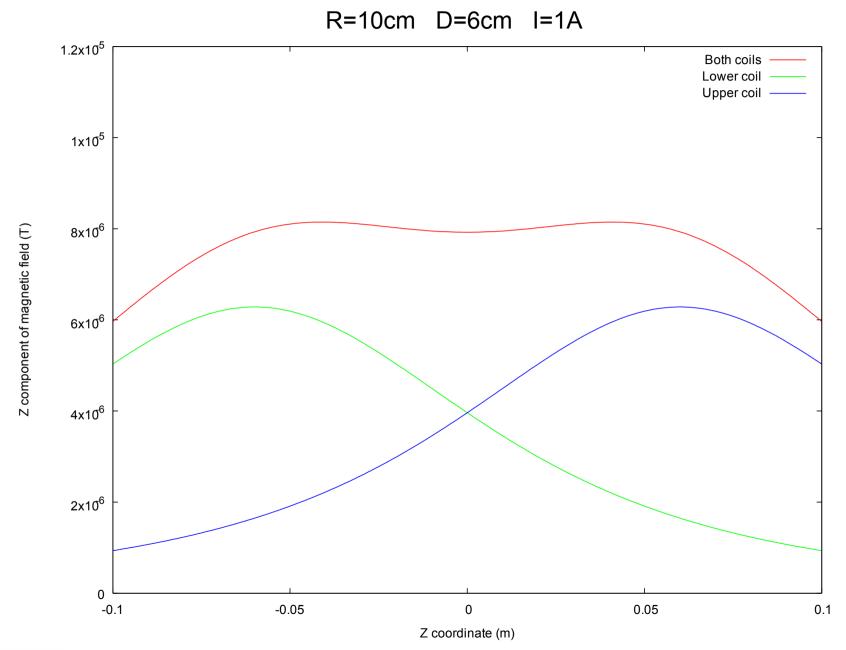




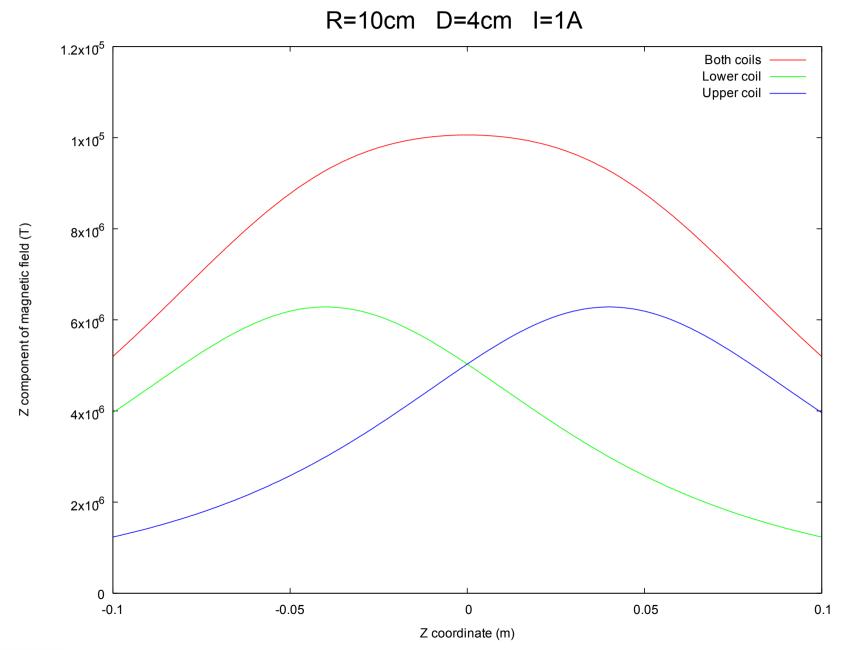






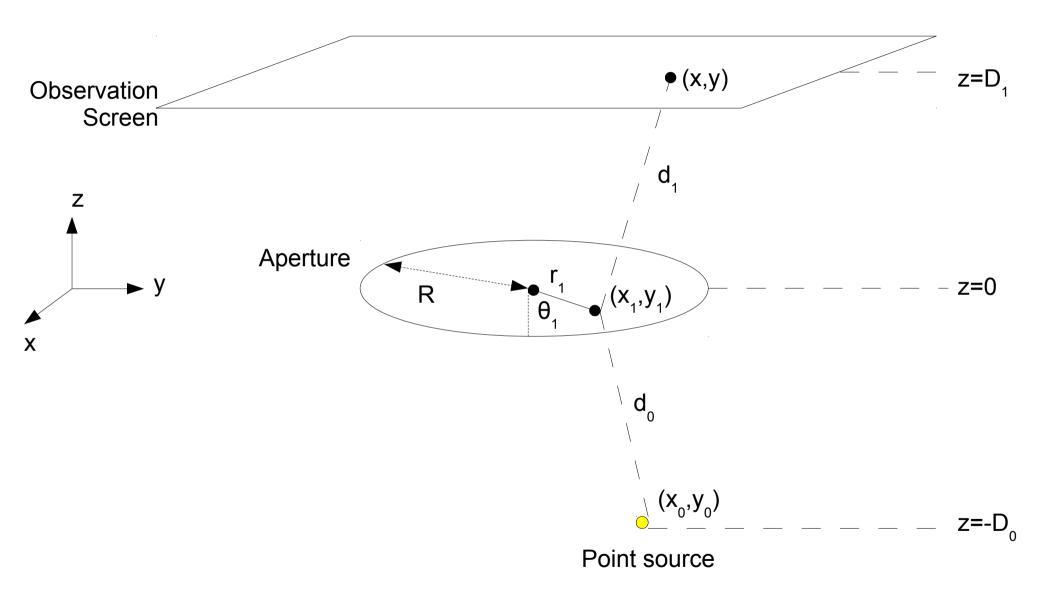








#### **Two-Dimensional Wave Diffraction Patterns**





#### Review of Phasors

Consider any physical system described by a linear second order ODE with constant coefficients, driven by a sinusoid at a fixed frequency and a reference phase:

$$\frac{dx^2}{dt^2} + a\frac{dx}{dt} + bx = ce^{i\omega t}$$

Look only for a solution in the form of a steady state sinusoid with unknown amplitude and phase. Form a prototype solution of the form:

$$x = A e^{i(\omega t - \phi)} = A e^{i\phi} e^{i\omega t}$$

Plug prototype solution back into ODE:

$$-\omega^2 A e^{i\phi} e^{i\omega t} + a i\omega A e^{i\phi} e^{i\omega t} + b A e^{i\phi} e^{i\omega t} = c e^{i\omega t}$$

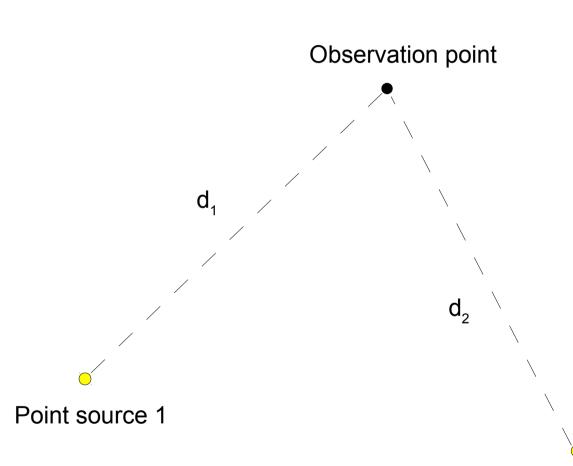
Cancel e<sup>iωt</sup> factors:

$$-\omega^2 A e^{i\phi} + a i \omega A e^{i\phi} + b A e^{i\phi} = c$$

Second order ODE has been transformed into a complex algebraic equation  $Ae^{i\Phi}$  is called the "phasor" of the solution x



#### Phasor Method for Wave Interference

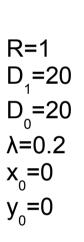


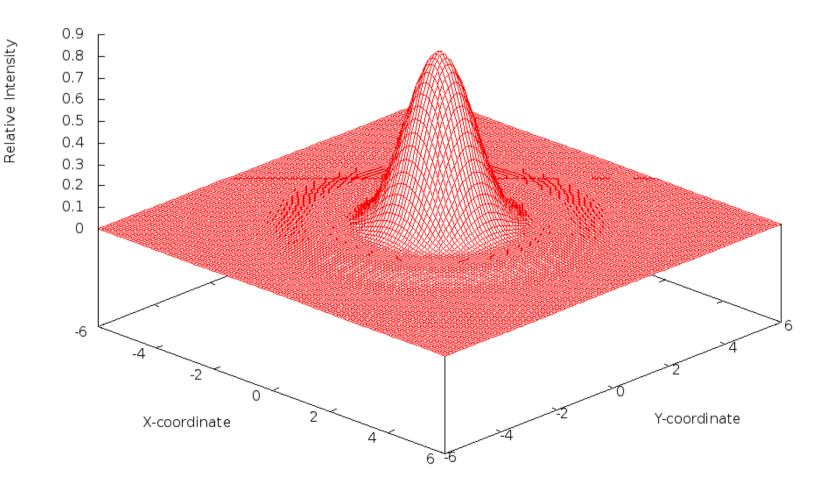
 $\vec{E}$  field at observation point  $= \sum \vec{E}_j$  from point source j Assume uniform polarization, so for instance  $\vec{E}_j = E_{jx} \vec{x}$   $E_{jx} = E_{j0} e^{i(\omega t - \phi)} = E_{j0} e^{i\phi} e^{i\omega t}$   $E_{j0} e^{i\phi}$  is the 'phasor' from source j  $\phi$  is due to path length differences

Point source 2



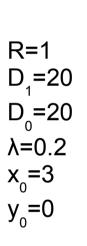
# Diffraction Pattern from Single Point Source

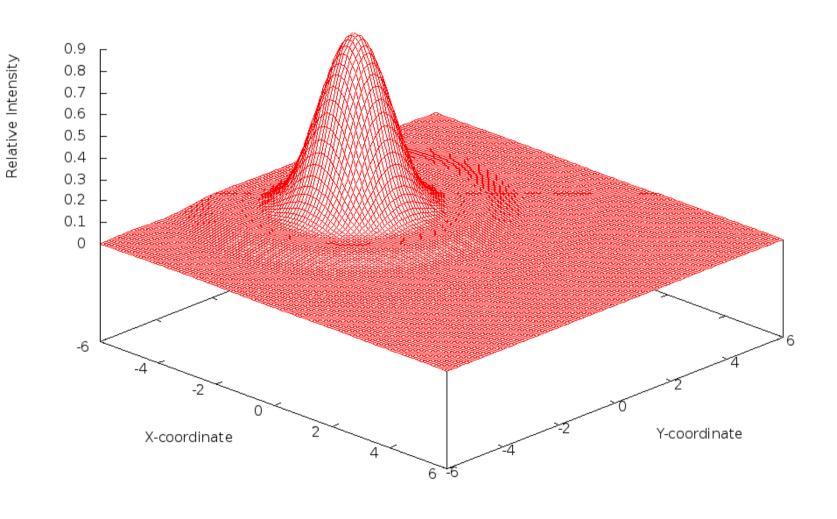






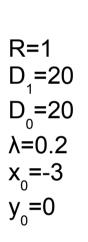
# Diffraction Pattern from Single Point Source

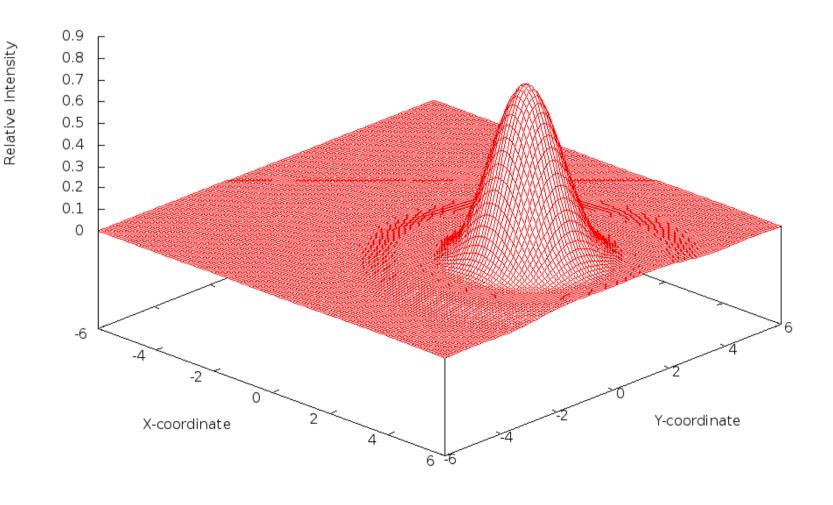






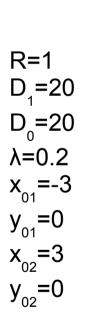
# Diffraction Pattern from Single Point Source

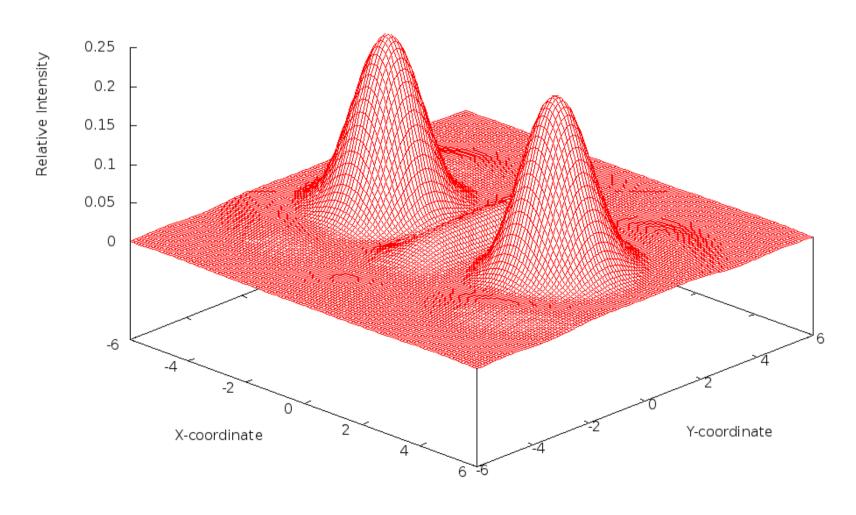






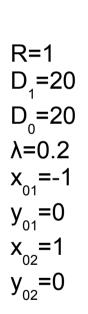
### Diffraction Pattern from Two Point Sources

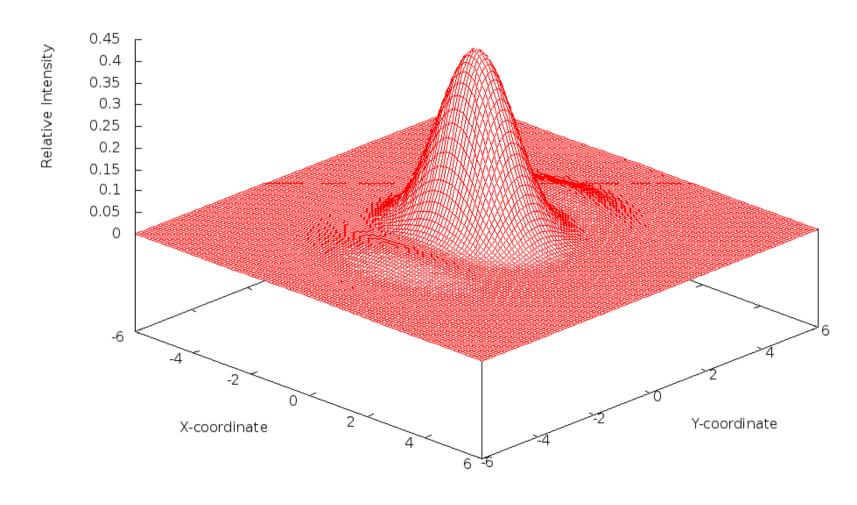






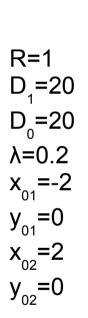
### Diffraction Pattern from Two Point Sources

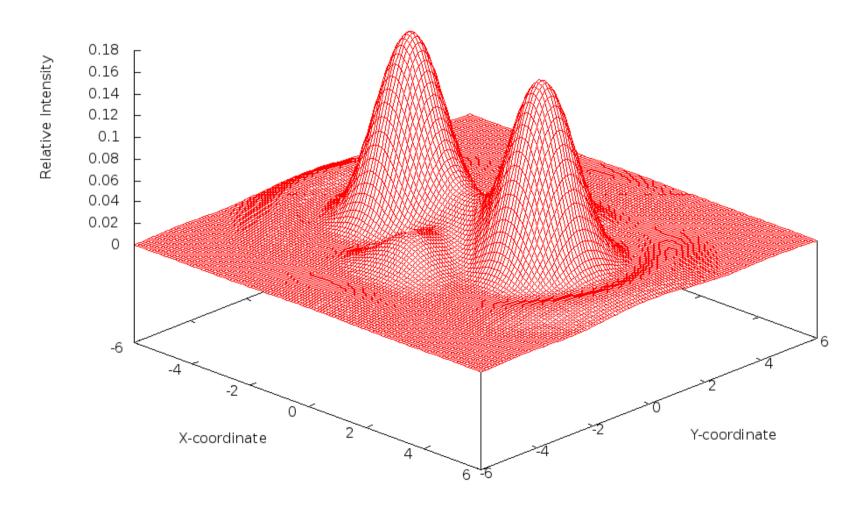






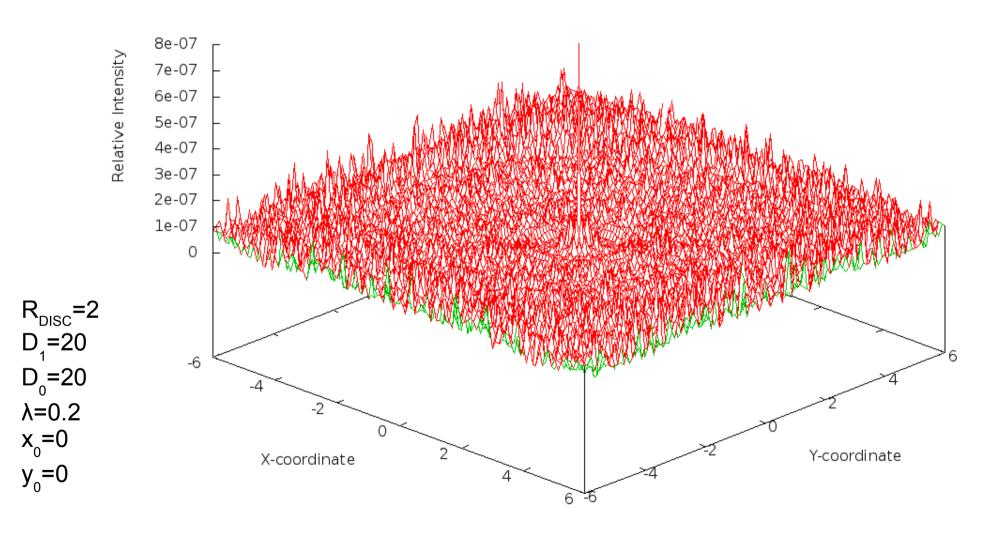
### Diffraction Pattern from Two Point Sources





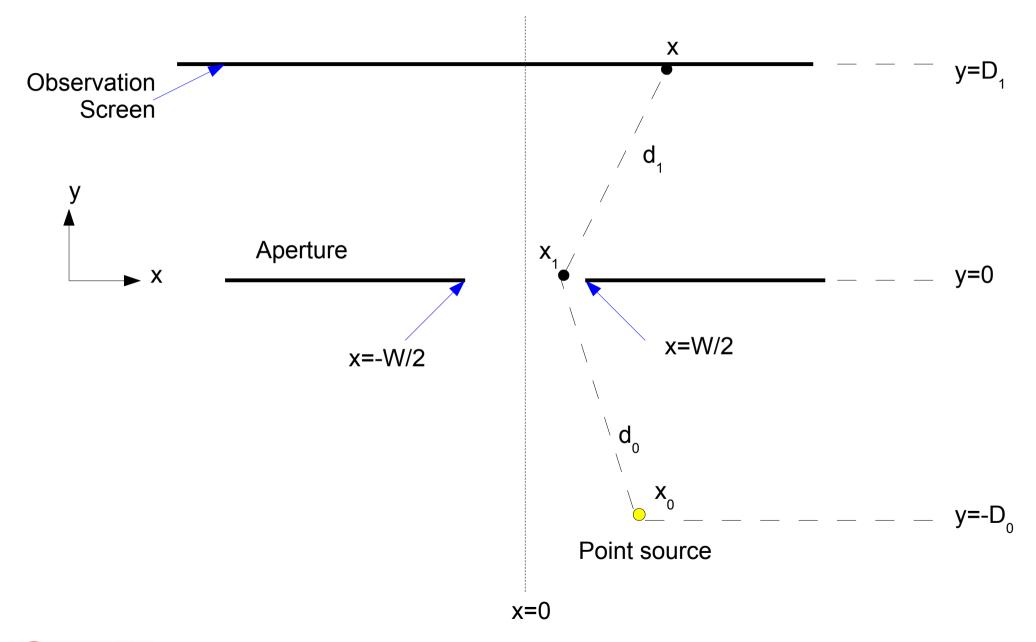


# Simulation of the Poisson Spot



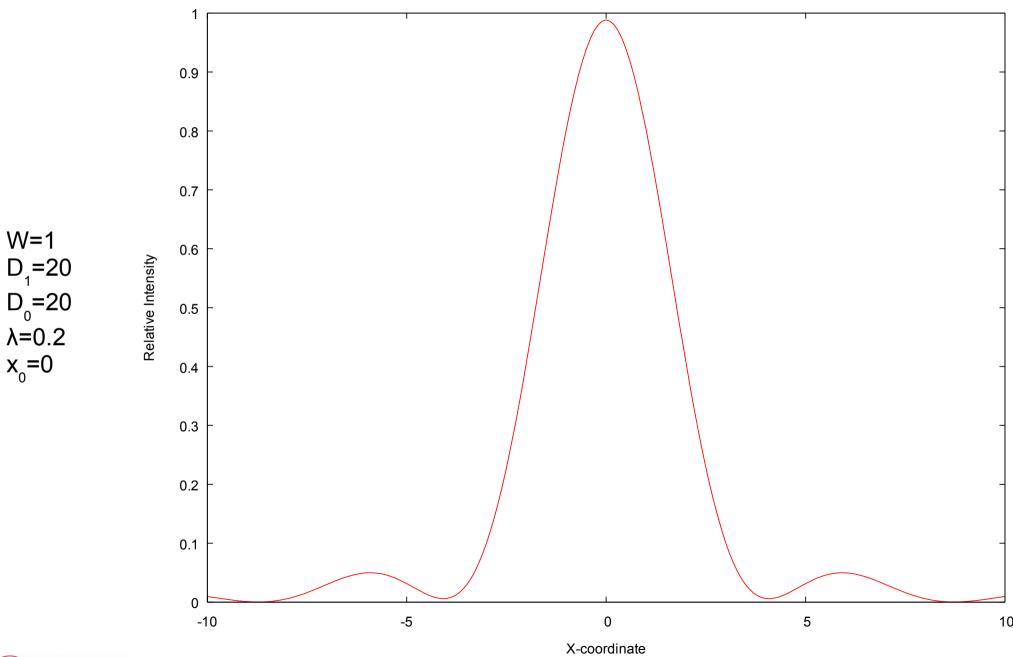


#### One-Dimensional Wave Diffraction Patterns



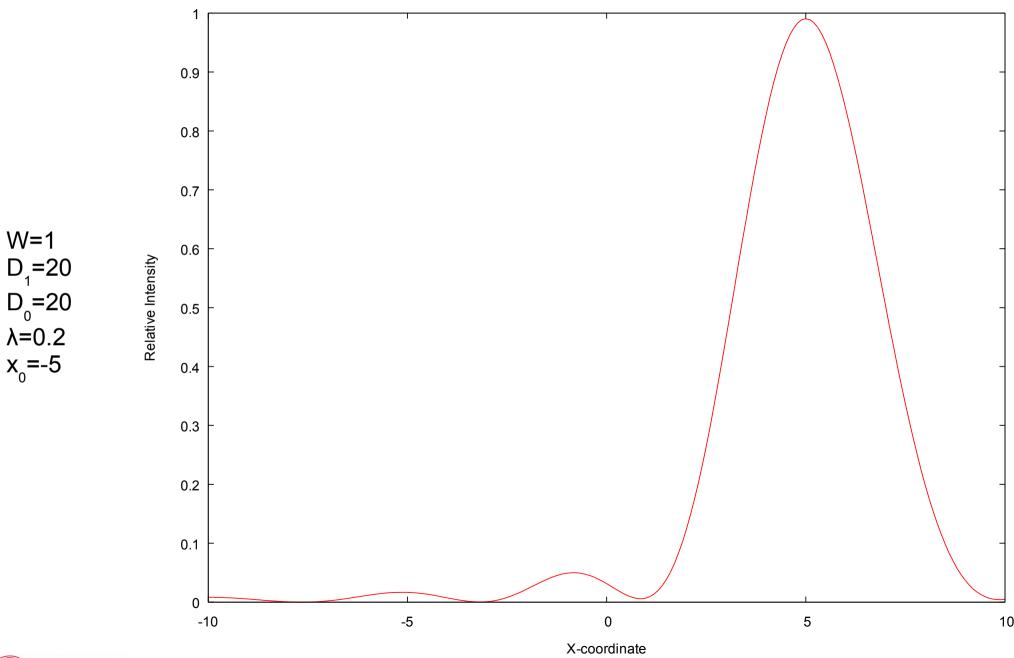


#### 1-Dimensional Diffraction Pattern from Single Point Source



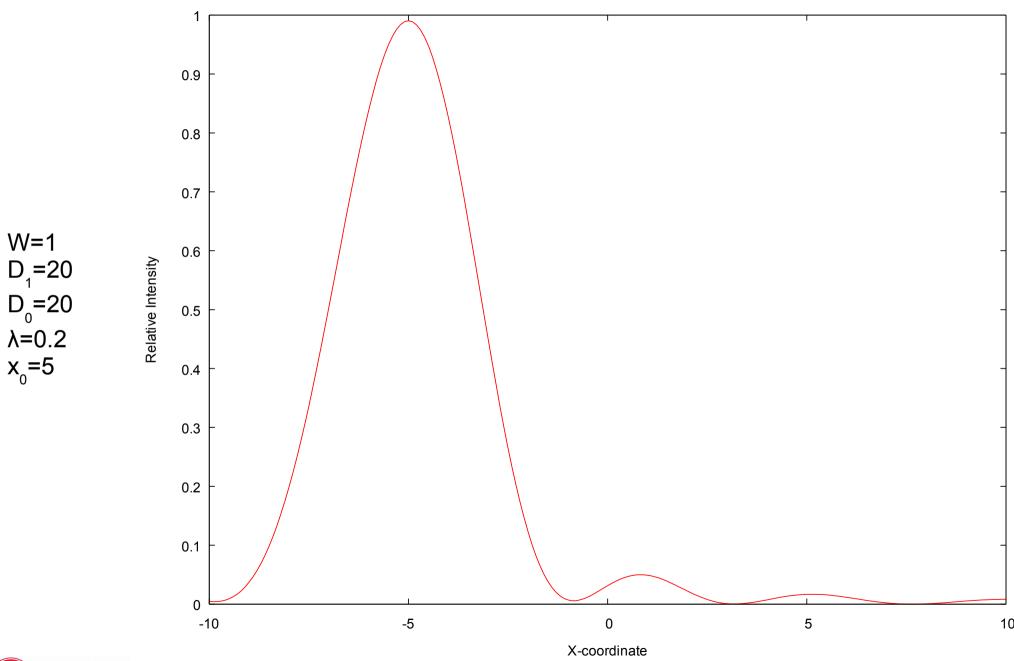


#### 1-Dimensional Diffraction Pattern from Single Point Source



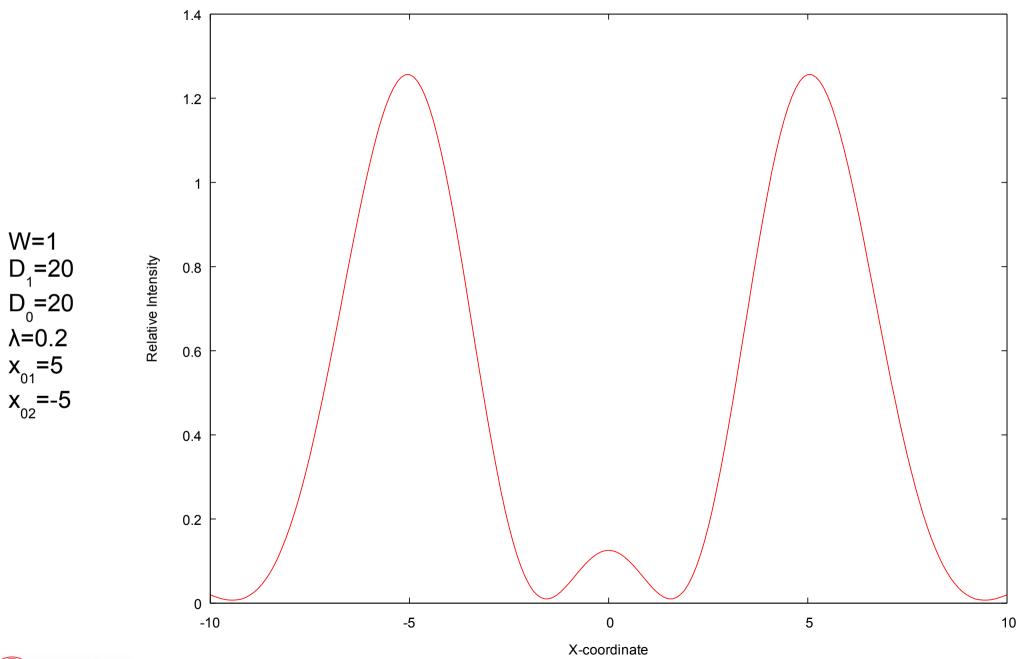


#### 1-Dimensional Diffraction Pattern from Single Point Source



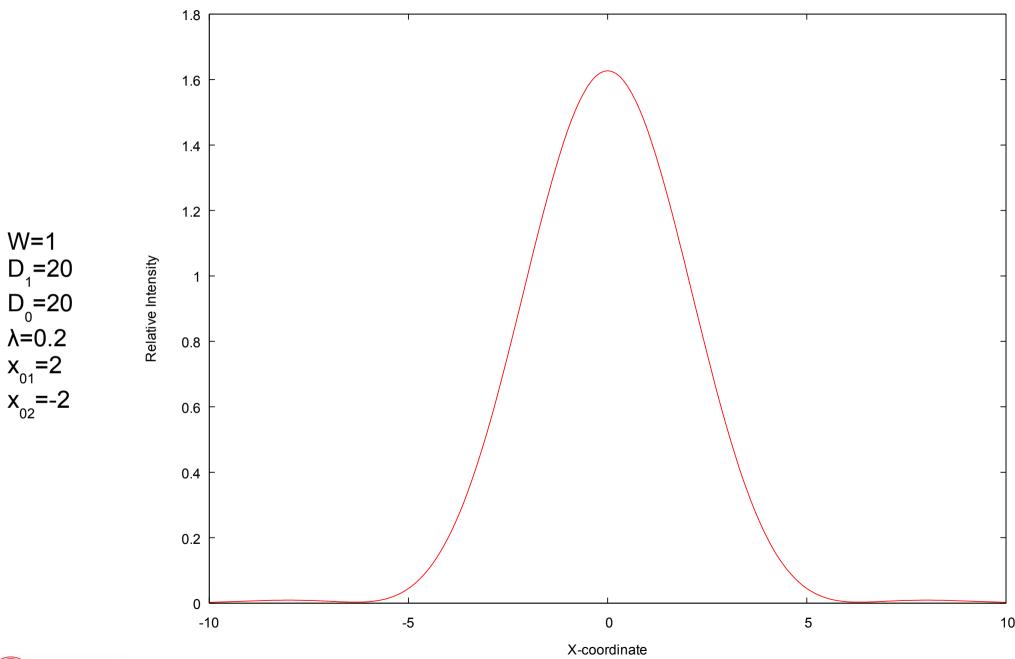


#### 1-Dimensional Diffraction Pattern from Two Point Sources



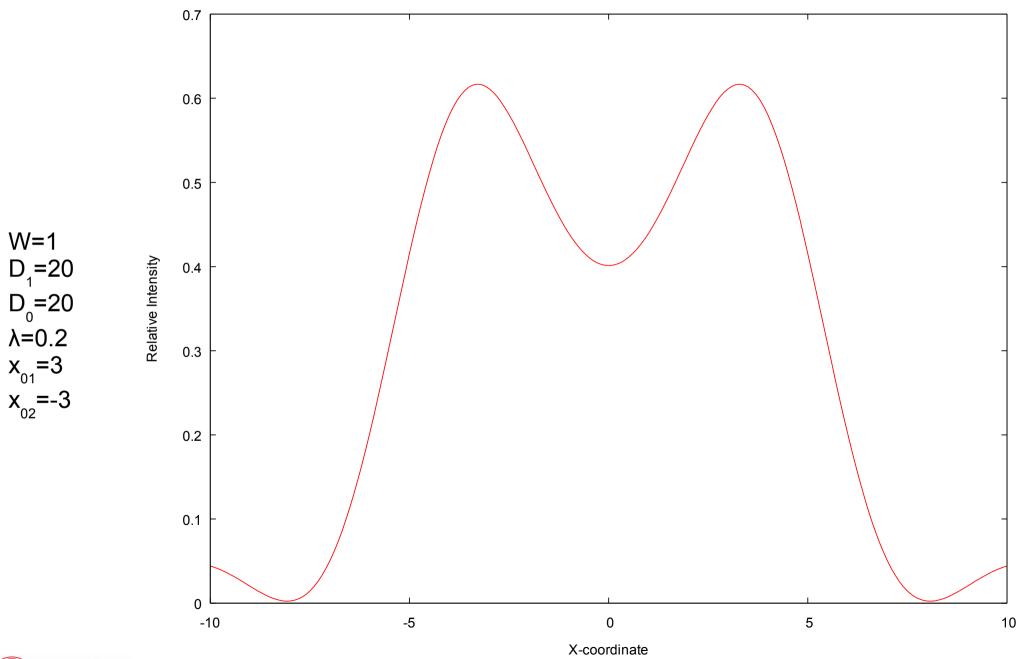


#### 1-Dimensional Diffraction Pattern from Two Point Sources





#### 1-Dimensional Diffraction Pattern from Two Point Sources





# Plotting Vectors with gnuplot

#### We have used:

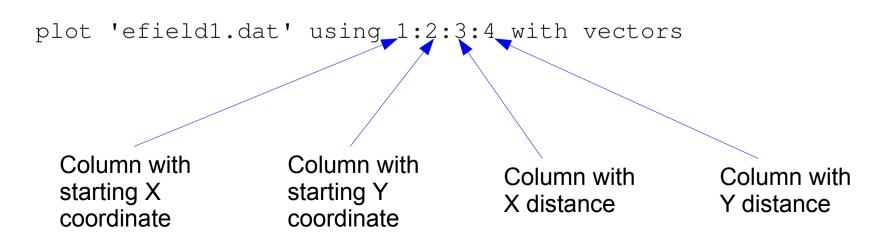
```
plot 'efield1.dat' using 1:2 with lines

plot 'efield1.dat' using 1:2 with points

Column with X coordinate

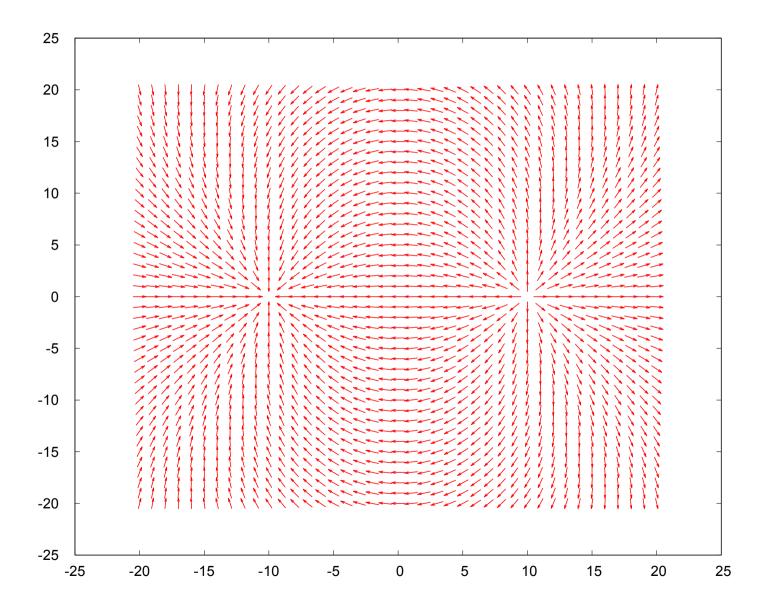
Column with Y coordinate
```

#### Another plot mode:



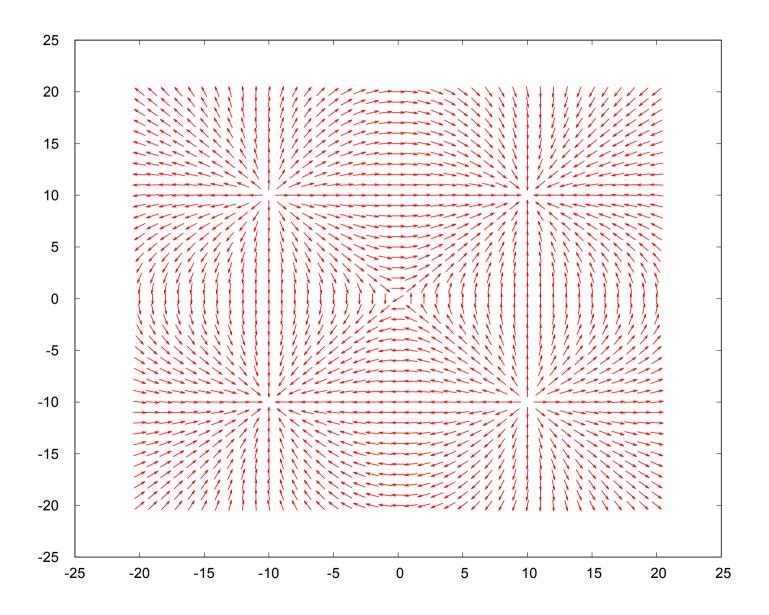


# Electric Field Vectors for Dipole



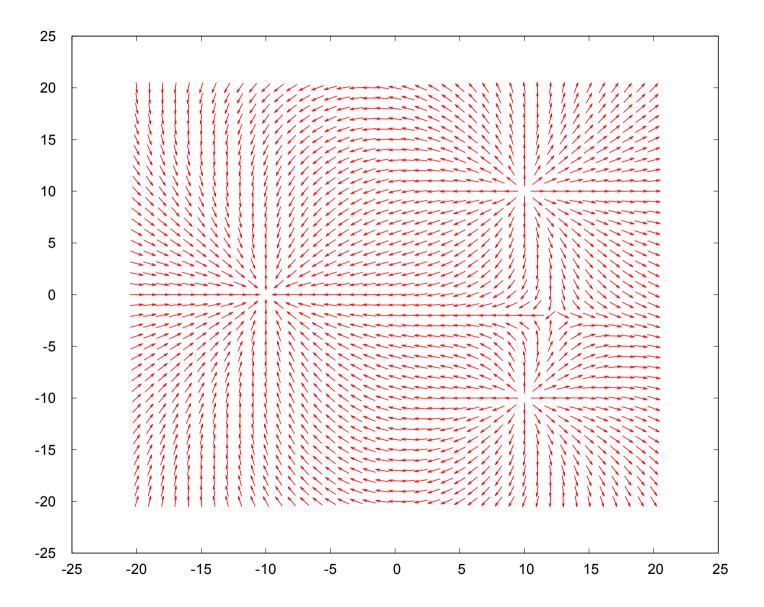


# Electric Field Vectors for Quadrapole





#### Electric Field Vectors for Example Arbitrary Charges





### C Code for Mapping Electric Field Vectors

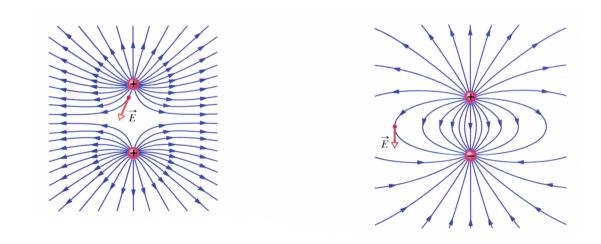
```
xstop = xstop + xinc * 0.5;
ystop = ystop + yinc * 0.5;
rtest = 1.0e-6 * (xinc*xinc + yinc*yinc);
x = xstart;
while (((xinc > 0.0) \&\& (x < xstop)) || ((xinc < 0.0) \&\& (x > xstop))) {}
  v = vstart;
  while (((yinc > 0.0) \&\& (y < ystop)) || ((yinc < 0.0) \&\& (y > ystop))) {}
    ex = 0.0;
   ey = 0.0;
    i = 0;
   while (i < n) {
      rsq = (x-xi[i])*(x-xi[i]) + (y-yi[i])*(y-yi[i]);
      if (rsq < rtest) break;
      r = sqrt(rsq);
      ex += qi[i] * (x-xi[i]) / (r * rsq);
      ey += qi[i] * (y-yi[i]) / (r * rsq);
      i++;
    if (i >= n) {
      emag = sqrt(ex*ex + ey*ey);
      vx = xinc * ex / emaq;
      vv = vinc * ev / emaq;
      printf("\%.8q \%.8q \%.8q \n",x-0.5*vx,y-0.5*vy,vx,vy);
    y = y + yinc;
 x = x + xinc;
```

Loop over n charges. double array qi[] hold each charge  $q_i$  and double arrays xi[] and yi[] hold  $x_i$  and  $y_i$  coordinates



#### Classical Electric Field Lines

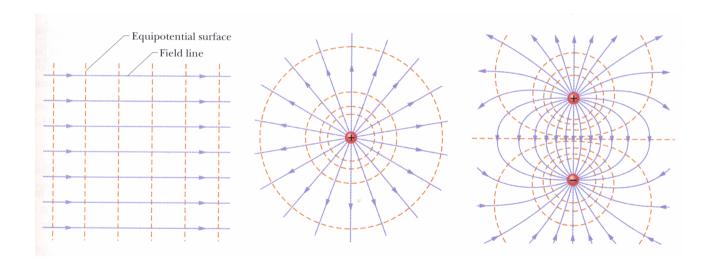
Note that the vectors plotted by this method only record the direction of the E field vector at an array of sampled points. These are not quite equivalent to the classical field lines, which convey both the direction of the field and its magnitude from the density of drawn lines.





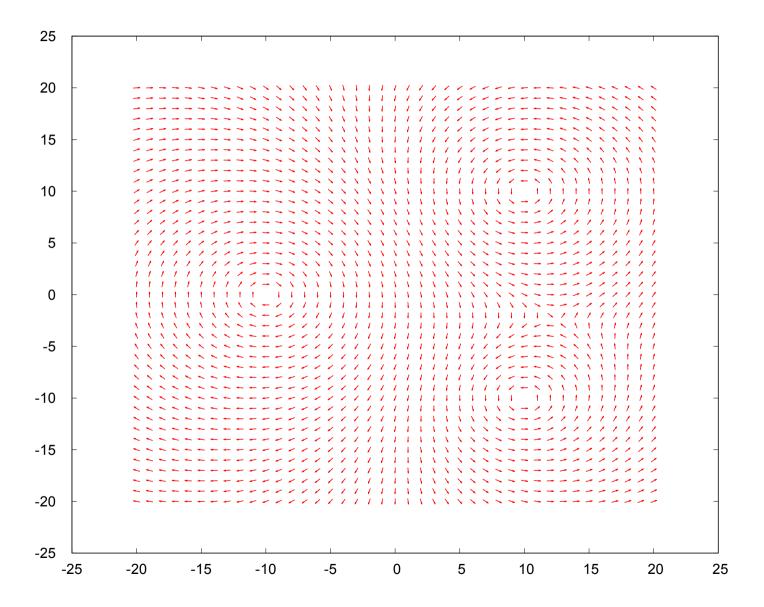
# Classical Electric Equipotential Lines

A simple modification of this algorithm can be used to plot a sampling of the direction of the electric equipotential lines. At a given point, field lines and equipotential lines will have slopes that are negative reciprocals of each other. Again, no magnitude information is present, only direction.





### Equipotential Vectors for Example Arbitrary Charges





# C Code for Mapping Equipotential Vectors

```
xstop = xstop + xinc * 0.5;
ystop = ystop + yinc * 0.5;
rtest = 1.0e-6 * (xinc*xinc + vinc*vinc);
x = xstart;
while (((xinc > 0.0) \&\& (x < xstop)) || ((xinc < 0.0) \&\& (x > xstop))) {}
  y = ystart;
  while (((yinc > 0.0) \&\& (y < ystop)) || ((yinc < 0.0) \&\& (y > ystop))) {}
    ex = 0.0;
    ev = 0.0;
    i = 0;
    while (i < n) {
      rsq = (x-xi[i])*(x-xi[i]) + (y-yi[i])*(y-yi[i]);
      if (rsq < rtest) break;
      r = sqrt(rsq);
      ex += qi[i] * (x-xi[i]) / (r * rsq);
      ey += qi[i] * (y-yi[i]) / (r * rsq);
                                                                   Only these two
      i++;
                                                                   statements change!
    if (i >= n) {
      emaq = sqrt(ex*ex + ey*ey);
      vx = -0.5 * xinc * ey / emaq;
      vy = 0.5 * yinc * ex / emaq;
      printf("%.8q %.8q %.8q %.8q\n",x-0.5*vx,y-0.5*vy,vx,vy);
    y = y + yinc;
  x = x + xinc;
```



### **Examples of Optical Glare**

Glare is the reflected room light off of an intervening plexiglass protective sheet.

Reflections occur at the interface between two materials of different refractive indices.





(Vacuum tube arithmetic unit and magnetic drum memory from the Univac 1, on display at the Deutches Museum of Technology, Munich, Germany)



# Computing Another Kind of Glare: a Rainbow



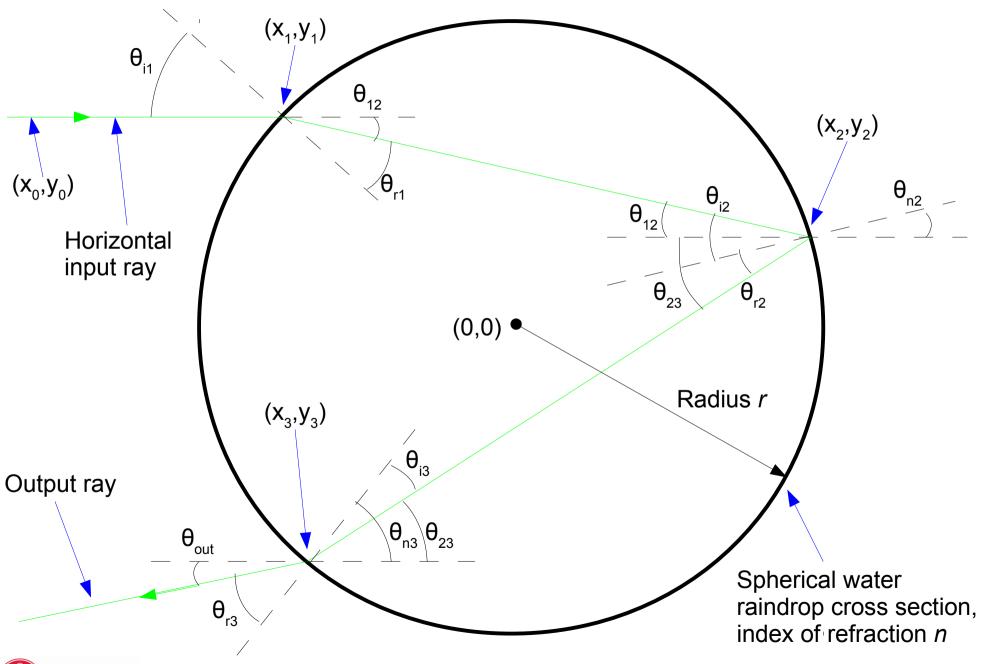


## Rene Descartes Graphical Derivation

"I took my pen and made an accurate calculation of the paths of the rays which fall on the different points of a globe of water to determine at which angles, after two refractions and one or two reflections they will come to the eye, and I then found that after one reflection and two refractions there are many more rays which can be seen at an angle of from forty-one to forty-two degrees than at any smaller angle; and that there are none which can be seen at a larger angle"



## Calculating Reflection and Refraction Angles





## Calculating Reflection and Refraction Angles

$$x_{1} = -\sqrt{r^{2} - y_{0}^{2}} \qquad y_{1} = y_{0} \qquad \theta_{ii} = \arctan\left(\frac{y_{1}}{|x_{1}|}\right)$$

$$\operatorname{Snell's law:} \ \theta_{ri} = \arcsin\left(\frac{1}{n}\sin\left(\theta_{ii}\right)\right)$$

$$\theta_{12} = \theta_{ii} - \theta_{ri} \qquad m_{12} = \tan\left(-\theta_{12}\right)$$

$$x_{2} = \frac{x_{1}(m_{12}^{2} - 1) - 2m_{12}y_{1}}{m_{12}^{2} + 1} \qquad y_{2} = y_{1} + m_{12}(x_{2} - x_{1})$$

$$\theta_{n2} = \arctan\left(\frac{y_{2}}{x_{2}}\right) \qquad \theta_{i2} = \theta_{n2} + \theta_{12} \qquad \theta_{23} = \theta_{n2} + \theta_{i2} = 2\theta_{n2} + \theta_{12} \qquad m_{23} = \tan\left(\theta_{23}\right)$$

$$x_{3} = \frac{x_{2}(m_{23}^{2} - 1) - 2m_{23}y_{2}}{m_{23}^{2} + 1} \qquad y_{3} = y_{2} + m_{23}(x_{3} - x_{2})$$

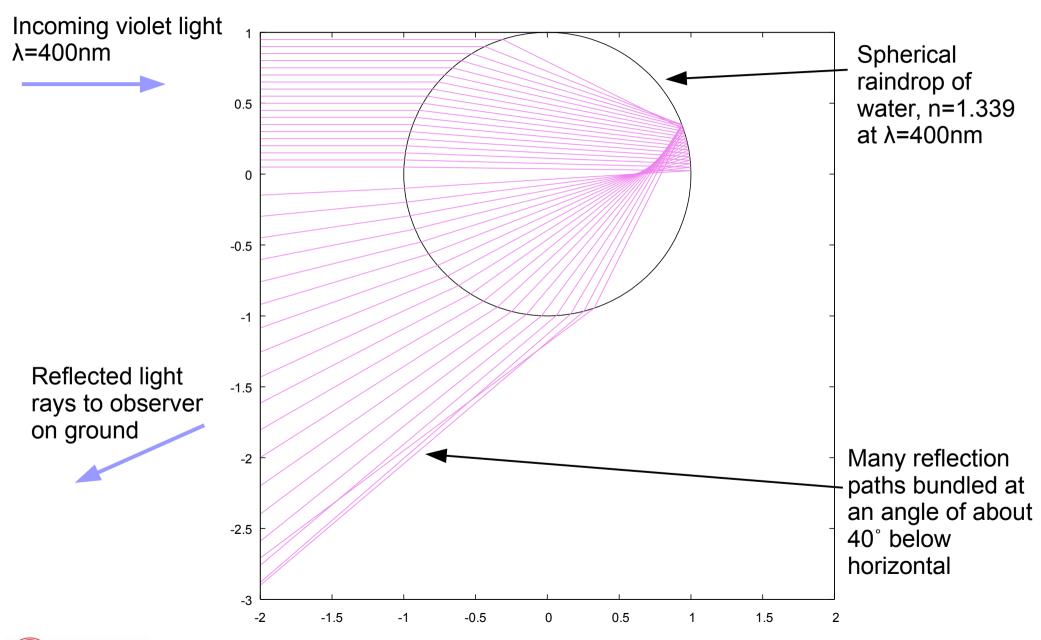
$$\theta_{n3} = \arctan\left(\frac{y_{3}}{x_{3}}\right) \qquad \theta_{i3} = \theta_{n3} - \theta_{23}$$

$$\operatorname{Snell's law:} \ \theta_{r3} = \arcsin\left(n \cdot \sin\left(\theta_{i3}\right)\right)$$

$$\theta_{out} = \theta_{n3} - \theta_{r3}$$

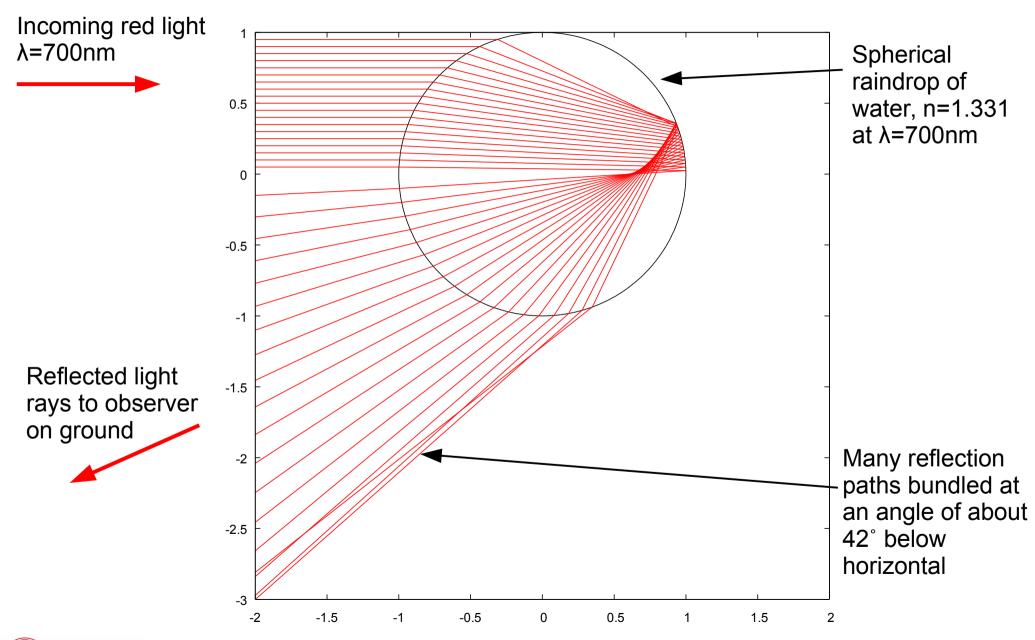


## Reflection and Refractions through a Raindrop



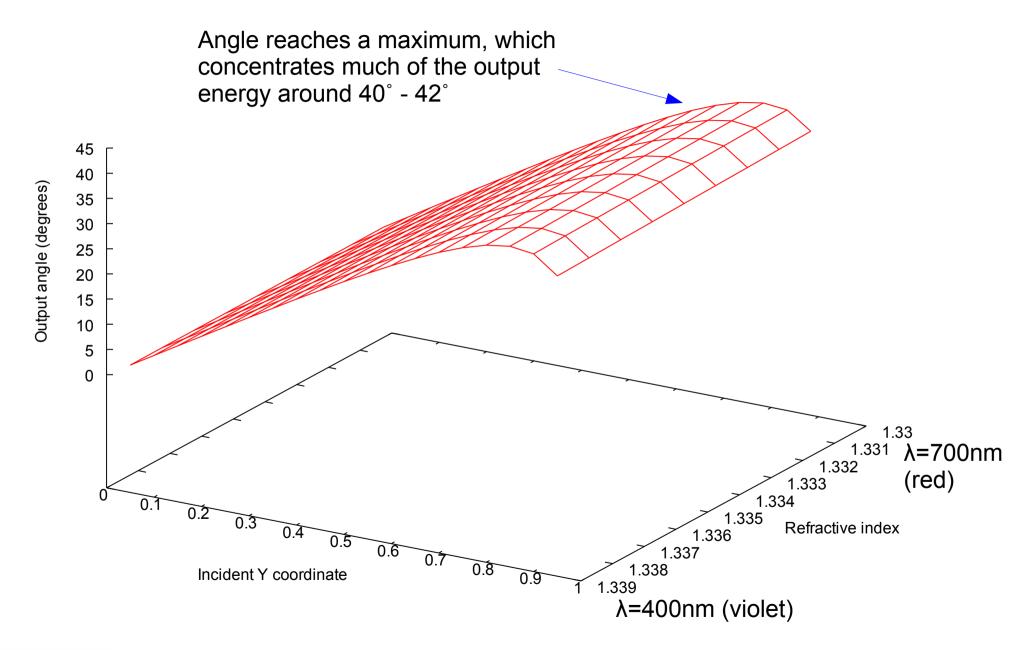


## Reflection and Refractions through a Raindrop



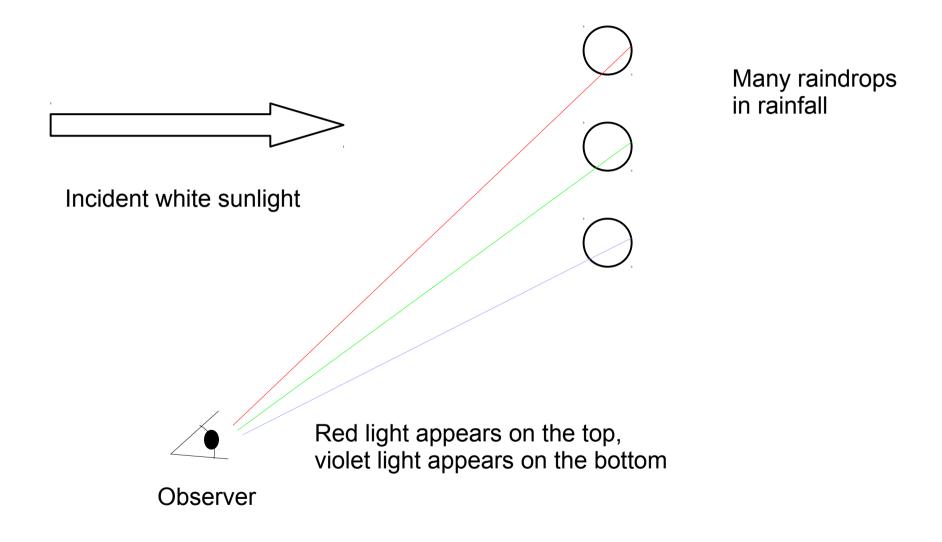


## Output Angle Relative to Horizontal





## Total Effect of Many Raindrops is a Rainbow





### Wave Packets for Quantum Mechanics

Solutions of the time-independent Schrödinger equation in one dimension

$$\frac{d^2\psi(x)}{dx^2} = -\frac{2m}{\hbar^2} \left[ E - V(x) \right] \psi(x)$$

in regions where particles are free to move and not subject to forces, or

$$V(x)=0$$
 and  $E>0$ 

are of the form

$$\psi(x) = A e^{+ikx} + B e^{-ikx}$$

which makes the complete solution including the time dependence

$$\psi(x) = A e^{+i(kx-\omega t)} + B e^{-i(kx+\omega t)}$$

where 
$$k = \frac{p}{\hbar}$$
 and  $\omega = \frac{E}{\hbar}$ 

so the relationship between  $\omega$  and k is

$$\omega = \frac{\hbar}{2m} k^2$$



#### Wave Packets for Quantum Mechanics

A single wave solution is associated with a continuous flux of particles in the positive or negative *x* direction, with momentum *p* and energy *E*.

Solutions that are linear combinations of multiple waves form wave packets that are associated with single particles.

$$\psi(x) = \sum_{k} A_{k} \psi_{k}(x)$$

Or in the continuous limit

$$\psi(x) = \int A(k) \psi_k(x) dk$$

Look at Gaussian wave packets where

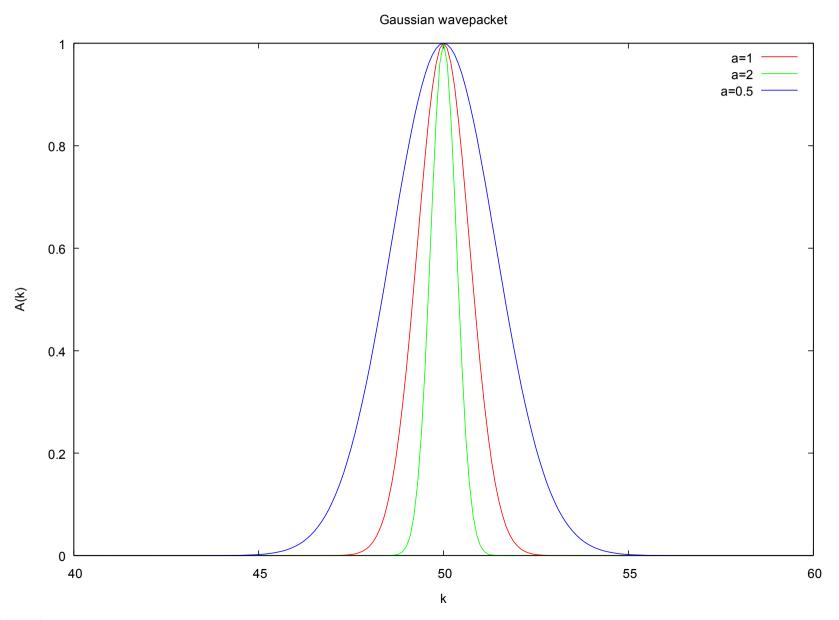
$$A_k = e^{-a^2(k-k_0)^2}$$

Or in the continuous limit

$$A(k)=e^{-a^{2}(k-k_{0})^{2}}$$

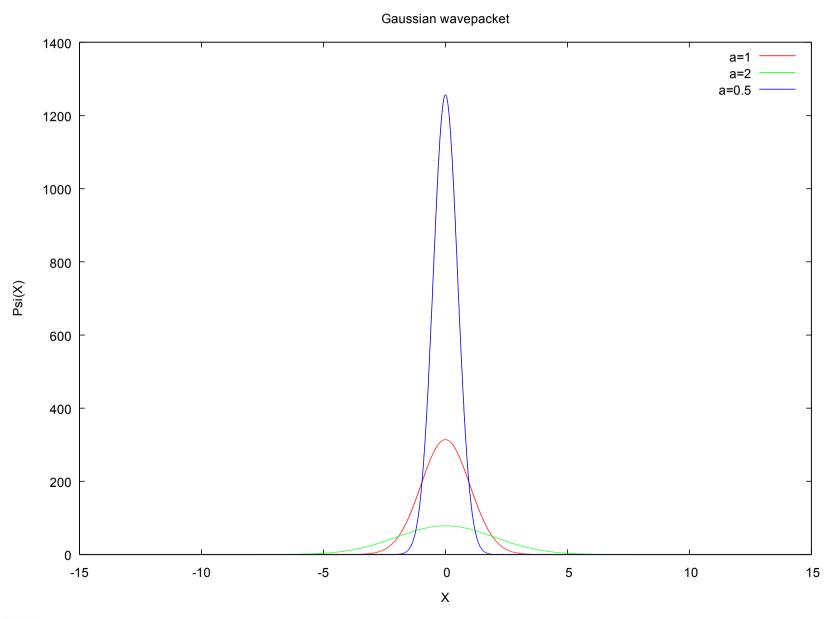


### Distribution of Wave Numbers





## Corresponding Spatial Wave Distribution





## Phase and Group Velocities

The phase velocity  $v_p$  of a single wave with particular values of k and  $\omega$  is the velocity of the point in space that maintains a constant sinusoidal phase

$$v_p = \frac{\omega}{k} = \frac{\hbar}{2m} k$$

The group velocity  $v_{q}$  of a wave packet is the velocity of the peak of spatial distribution

$$v_g = \frac{d\omega}{dk}|_{(k=k_0)} = \frac{2\hbar}{2m}k_0 = 2v_{p0}$$

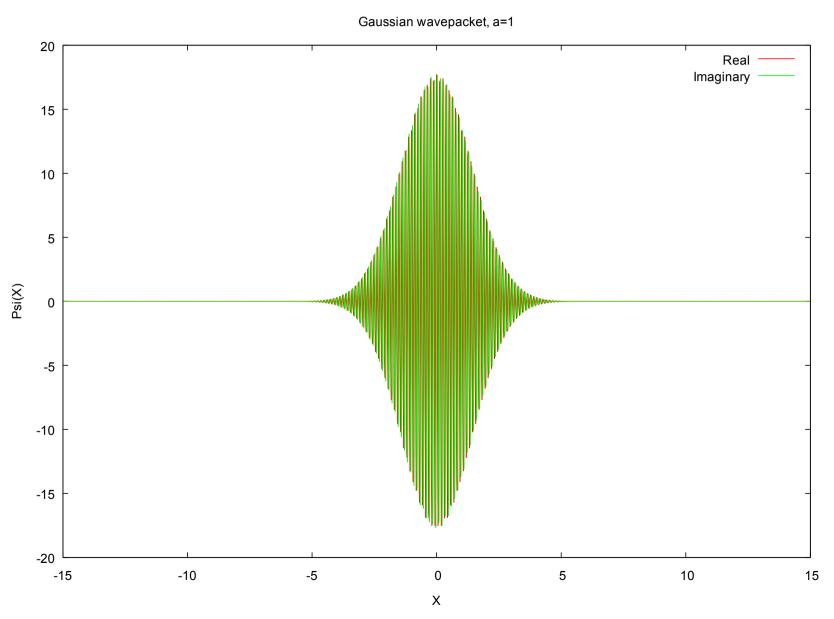
Where  $v_{p0}$  is the phase velocity of the single wave at the center of the k distribution

Note: 
$$v_g = \frac{2\hbar}{2m}k_0 = \frac{\hbar}{m}\frac{p_0}{\hbar} = \frac{p_0}{m}$$

So it is the wave packet group velocity that corresponds to the velocity p/m in the classical limit



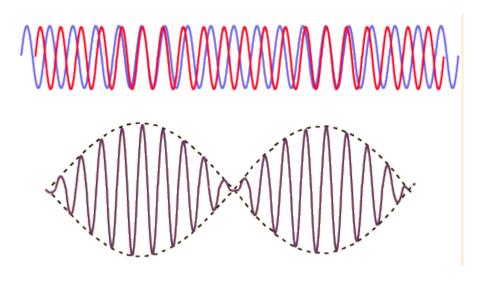
# Discrete Approximation to Gaussian Packet





## Why Do Wave Packets Form a Pulse?

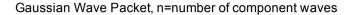
Consider the superposition of just two sine waves of different frequencies. They form a "beat" frequency where constructive and destructive interference alternate:

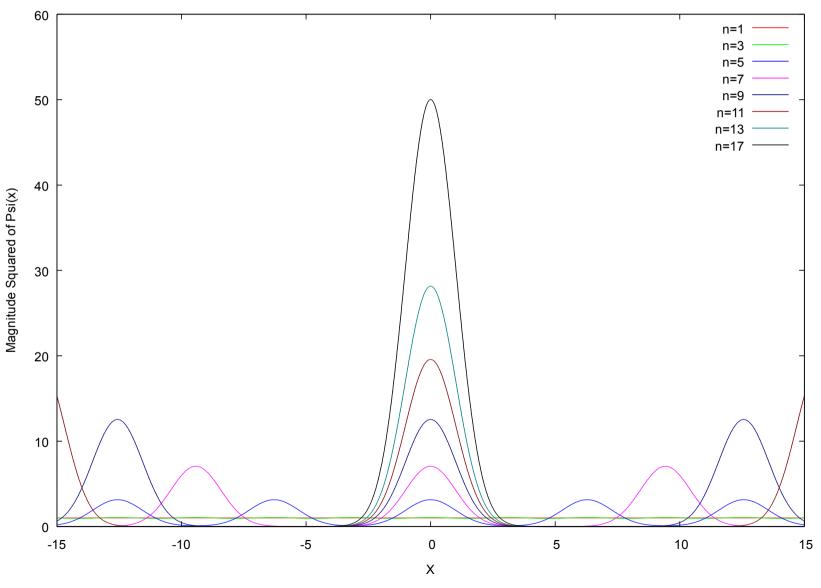


Wave packets are extensions of this property, with the sum over many frequencies. The region where all the waves line up with constructive interference becomes isolated to a pulse.



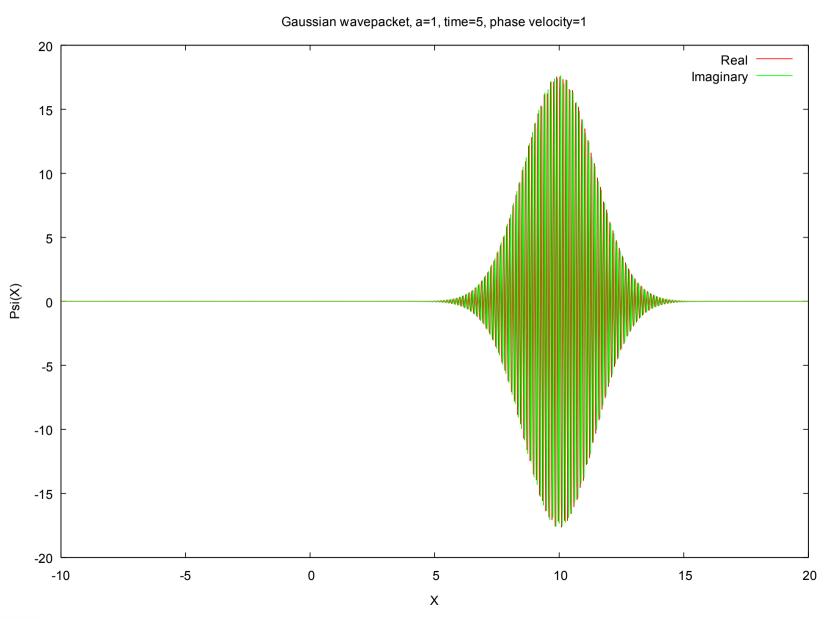
# Quality of Discrete Approximations







# Group Velocity versus Phase Velocity





## Uncertainty Principle of Wave Packets

$$\overline{\Delta x^2} = \overline{[x - \overline{x}]^2} = \frac{\int \psi(x)^2 [x - \overline{x}]^2 dx}{\int \psi(x)^2 dx}$$

$$\overline{\Delta k^2} = \overline{\left[k - \overline{k}\right]^2} = \frac{\int A(k)^2 \left[k - \overline{k}\right]^2 dk}{\int A(k)^2 dk}$$

then 
$$\overline{\Delta x^2} \cdot \overline{\Delta k^2} \ge \frac{1}{4}$$

