

## Least-Squares Method

Imagine have a set of  $n$  measurements,  $y_i$ , at points  $x_i$

→ each measurement has error  $\sigma_i$

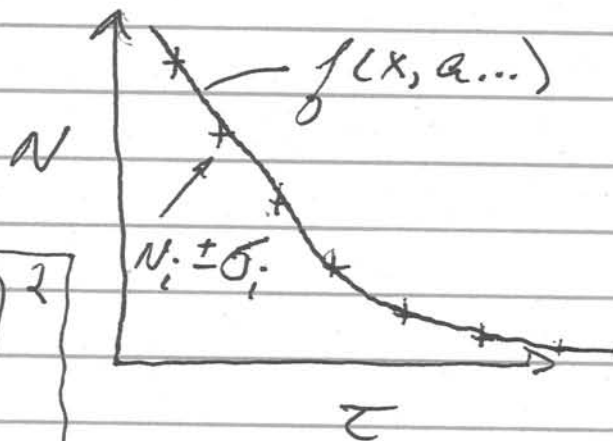
We want to fit to some function

$$f(x; a_1, a_2, \dots, a_n)$$

↳ fit parameters - unknown

Calculate figure  
of merit

$$S = \sum_{i=1}^n \left[ \frac{y_i - f(x_i; a_j)}{\sigma_i} \right]^2$$



↳ would be a  $\chi^2$  if errors Gaussian  
(not always the case)

Seek  $a_j$  for which  $S$  is a minimum

Analytically, determining  $a_j$  would require solving system of equations

$$\frac{\partial S}{\partial a_j} = 0$$

→ not always an analytic solution

∴ need to probe ~~analytically~~ for minimum computationally

### Errors

Obtained from covariance matrix

$$(V_{\hat{\beta}}^{-1})_{ij} = \frac{1}{2} \frac{\partial^2 S}{\partial a_i \partial a_j} \rightarrow \text{evaluate at minimum}$$

~ change of  $a_j$  near minimum ~~var~~  
⇒ variances of  $a_j$

$$V = \begin{bmatrix} \sigma_1^2 & \text{cov}(1,2) & \text{cov}(1,3) & \dots \\ \vdots & \sigma_2^2 & - & - \\ \vdots & \vdots & \sigma_3^2 & - \\ & & & \dots \end{bmatrix}$$

## Straight Line Fit

Consider points fitted to a simple linear function  $y = ax + b$

To get 'a' and 'b':

$$\frac{\partial S}{\partial a} = 0 \quad ; \quad \frac{\partial S}{\partial b} = 0$$

→ assigning

$$A = \sum \frac{x_i^2}{\sigma_i^2} \quad B = \sum \frac{1}{\sigma_i^2}$$

$$C = \sum \frac{x_i y_i}{\sigma_i^2} \quad D = \sum \frac{y_i^2}{\sigma_i^2}$$

$$E = \sum \frac{x_i y_i}{\sigma_i^2}$$

Given

$$a = \frac{EB - CA}{DB - A^2}$$

$$b = \frac{DC - EA}{DB - A^2}$$

Covariance matrix in yields

$$\sigma_a^2 = B / (DB - A^2) \quad ; \quad \sigma_b^2 = D / (DB - A^2)$$

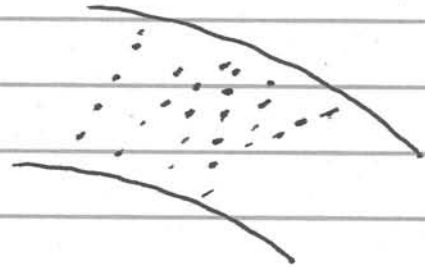
$$\text{cov}(a, b) = -A / (DB - A^2)$$

# Charged Particle Trajectories

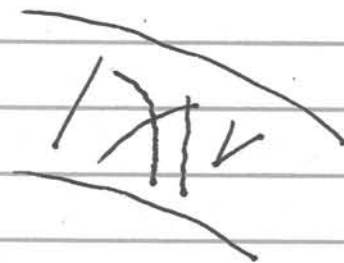
## Pattern recognition

- individual hits in tracking detectors

How go from  
this?



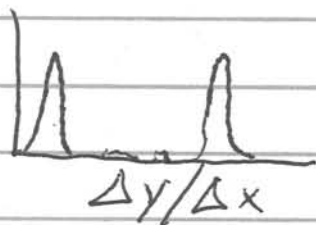
To this? =>



It is impractical to  
try all combinations of hits to find the  
best associations for tracks  
- but have advantage of considering  
full range of configurations

Can also analyze hits by several calculable  
parameters

eg.  $\frac{y_i - y_j}{x_i - x_j}$  for straight tracks



## Road Method: Tracking

If have a track with measured positions relative to that calculated.

$$\eta_i \equiv y_i - \epsilon_i = \vec{y} - \vec{\epsilon}$$

$$= X_i \cdot a_1 + 1 \cdot a_2$$

linear relation

$$\vec{\eta} = X \cdot \vec{a}$$

To obtain  $\vec{a}$ , we need the covariance matrix of  $\vec{y}$

$$C_y = \begin{pmatrix} \sigma_1^2 & & & 0 \\ & \sigma_2^2 & & \\ & & \sigma_3^2 & \\ 0 & & & \sigma_4^2 \end{pmatrix} = G_y^{-1}$$

diagonal because each measurement is independent

using least-squares, one minimizes

$$\chi^2 = \vec{\epsilon}^T G_y \vec{\epsilon}$$

get

$$\vec{a} = (X^T G_y X)^{-1} X^T G_y \vec{y} \quad (\text{values})$$

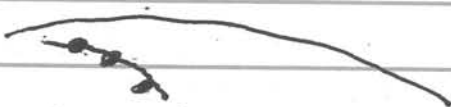
$$C_a = (X^T G_y X)^{-1} \quad (\text{error})$$

For large trackers with many hits

- may start at outer edge of detector

- consider 3 hit triplets

- fit to a parabola



- do extrapolate inward



- forming track segments this way

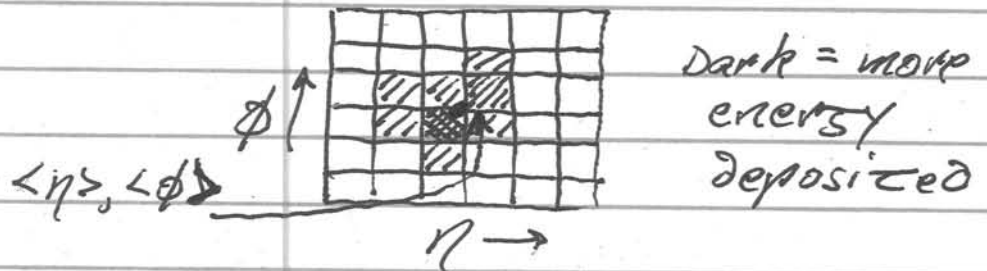
- a series of segments is combined to form a final track

- drop points with large 'residuals'  
(distance from track of good  $\chi^2$ )

- refit

## Clustering

- a series of "hits" or "calls" in a 2D plane
- often a 3rd coordinate involved



- a position measurement is determined for centroid of distribution


$$e.g. \quad \langle \eta \rangle = \frac{\sum_{i=1}^{\# \text{ cells}} \eta_i \cdot E_i}{\sum_{i=1}^{\# \text{ cells}} E_i}$$

- accuracy of location due to
  - granularity of detector
  - characteristic size + fluctuations of "pulse height" measurements
    - "Energy" in calorimeters

## A Simple Cone Algorithm

Need to find the cluster of high energy hits/cells in a calorimeter

- one method is to draw a cone in detector with vertex at interaction point

$$\Delta R = \sqrt{\Delta\eta^2 + \Delta\phi^2}$$


- Look for cells with large energy deposition
- draw cone  $\Delta R$  in radius around this cell
- calculate a new  $\eta'$ ,  $\phi'$  centroid

An iterative process is often needed



## Quark Jets:

Aftermath of parton fragmentation: jets

- a spray of particles arrayed roughly around direction of an initiating colored object: a quark or gluon
- there is not a perfect mapping between the kinematics of this 'jet' and the partons

- at detector level

- final state particles from prompt decays of hadronic fragmentation products
- collision + shower in calorimeter
  - many overlapping showers

Several reconstruction schemes: two most common

ITERATIVE FIXED-CONE

JADE (energy or momentum space algorithm)

## JADE Algorithm

We will iteratively consider the closeness of cells in momentum space  
- as opposed to using  $\eta$ , of more directly

Use

$$\gamma_{ij} = \frac{2E_i E_j (1 - \cos \theta_{ij})}{E_{vis}^2} m_{ij}^k$$

Cells within a threshold on  $\gamma_{ij}$  are combined:

yields a new "pseudojet" with its own  $E_i$  and direction

The specifics of many algorithms can vary by experiment

**Example 4.7** Find the best straight line through the following measured points

$x$	0	1	2	3	4	5
$y$	0.92	4.15	9.78	14.46	17.26	21.90
$\sigma$	0.5	1.0	0.75	1.25	1.0	1.5

Applying (4.75) to (4.82), we find

$$a = 4.227 \quad b = 0.878$$

$$\sigma(a) = 0.044 \quad \sigma(b) = 0.203 \quad \text{and}$$

$$\text{cov}(a, b) = -0.0629.$$