

## Experimental Data

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Many measurements deal in raw signals

- often from many detector elements
  - ADC counts giving ionization charge
  - signal giving transition radiation and ionization for particle identification

Even in simplest cases

- steps needed to arrive at most useful physical quantity

Energy lost in calorimeter cells

- sampling fractions, High Voltage correction, pulser calibration...

3D space point in tracker

- drift time corrections, wire sag, magnetic field...

# Reconstruction

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Often, further calculations needed to "reconstruct" observables for physical particles

- Hits : track reconstruction :  $\vec{p}$  track
- $E$  in cells : cluster reconstruction  
:  $E, \phi, \eta$  of jet

Requires proper use of knowledge of experimental uncertainties

- statistics of probability distributions
- optimization

## Dealing with Experimental Data

- nature has inherently random processes
- measurements have uncertainties due essentially to a random element in making measurements

Statistics study of this randomness given that an underlying probability distribution

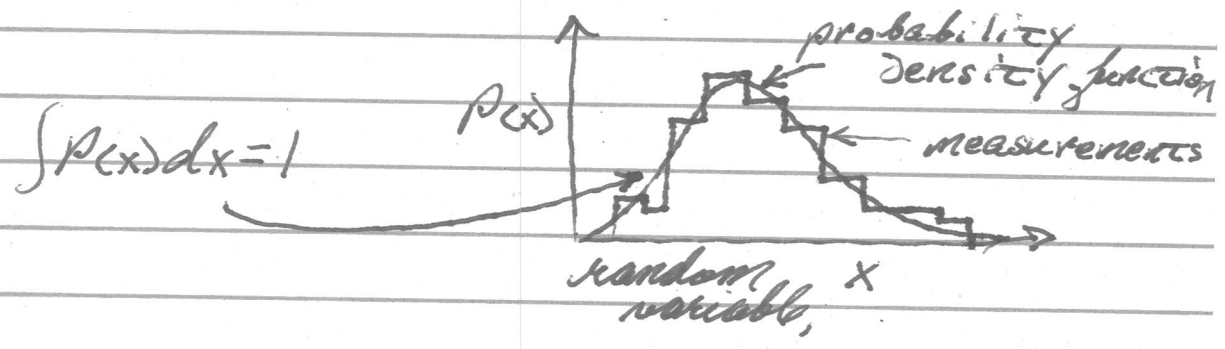
- also important in studying + optimizing detector design

∴ statistics critical to study of particle physics

# Probability Distributions

We consider random processes as described by a "probability distribution",  $P(x)$

- this is the 'universe' of all cases of this process
- we 'sample' this distribution when we make measurements



- if  $x$  discrete:  $P(x)$  gives frequency for each case
- if  $x$  continuous: speak of probability in window  $x$  to  $x+dx$

## Integral distributions:

$$P(x_1 \leq x \leq x_2) = \int_{x_1}^{x_2} P(x) dx \quad \left( \text{or } = \sum_{i=1}^2 P(x_i) \right)$$

if discrete  $x$

- normalization

## Expectation Values and Moments

Expected value of  $x$

$$E(x) = \int x P(x) dx \quad (= \sum_i x_i P(x_i))$$

↳ all allowed values of  $x$

The ' $r$ 'th moment of variable  $x$  around a point  $x_0 = E((x - x_0)^r)$

Mean:

$$\mu = E(x) = \int x P(x) dx$$

- Technically the "theoretical mean" as  $P(x)$  is function from universe
- experimental measurement is an estimate of this

Variance:

$$\sigma^2 = E((x - \mu)^2) = \int (x - \mu)^2 P(x) dx$$

$\sigma$  is "standard deviation"

- gives "width" of distribution around mean

## Covariance:

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Consider process described by multiple variables

$$P(x, y, z, \dots)$$

eg. height + weights of individuals

- variables may be correlated partially or fully

Define covariance

$$\text{cov}(x, y) = E[(x - \mu_x)(y - \mu_y)]$$

↓ ↓  
means in x and y

→ for each pairing of variables

eg.  $\text{cov}(x, y)$ ,  $\text{cov}(y, z)$ ,  $\text{cov}(z, x)$   
for  $x, y, z$  space

- a measure of the linear correlation between two variables
- correlation coefficient

$$\rho = \frac{\text{cov}(x, y)}{\sigma_x \sigma_y}$$

standard deviations of x and y

$$= -1 \text{ or } +1$$

$\rho = 0$  (independent)     $\rho = -1$  (anticorrelated)

## Binomial Distribution

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Let us have a process which can only have one of two values (eg. coin toss)

Probability of  $r$  successes in  $N$  trials

$$P(r) = \frac{N!}{r!(N-r)!} p^r (1-p)^{N-r}$$

number failures

where  $p$  is probability of success for each trial.

Gives mean,  $\mu = Np$  and variance

$$\sigma^2 = Np(1-p)$$

When  $N$  is large <sup>( $> 30$ )</sup>, and  $p \geq 0.05$ , can approximate by a Gaussian distribution

When  $N$  large and  $x \leq 0.05$ , can approximate as a Poisson distribution



## Efficiency Calculation

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If you have a measurement where either detect or identify a particle: binomial statistics

- trigger efficiency
- ↳ tracking efficiency ...

detect/identify  $\Rightarrow$  # successes =  $r$   
" " "  $\Rightarrow$  # failures =  $N - r$

One's estimate of the mean efficiency,  $\underline{e} = r/N$   
estimated  
↳ Error on this vs. theoretical value,  $p$

$$\underline{\delta e} = \frac{\sigma}{N} = \sqrt{\frac{e(1-e)}{N}}$$

Example: muon trigger efficiency

100 events with  $\mu^{\pm}$ : 99 detected  
 $e = 99\%$ ;  $\delta e = 1\%$   $(99 \pm 1)\%$

1000 events with 990 triggered  
 $e = 99\%$ ;  $\delta e = 0.3\%$   $(99.0 \pm 0.3)\%$



## Poisson Distribution

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Special case of binomial distribution when  
 $p \rightarrow 0$  and  $N \rightarrow \infty$   
 $\rightarrow$  mean  $Np$  stays finite

Probability of observing  $r$  events

$$P(r) = \frac{\mu^r e^{-\mu}}{r!}$$

- only mean  $\mu$  appears
- no explicit mention of  $N$  or  $p$

This gives variance  $\sigma^2 = \mu$

$$\therefore \sigma = \sqrt{\mu}$$

$\rightarrow$  reason that measurements depending on counting have  $\sqrt{N}$  behavior

Sensible to use for radioactive decay, or particle interactions (i.e. very small probabilities)

## Radioactive Decay

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Consider  $10^{-6}$  g of  $^{137}\text{Cs} \rightarrow 10^{15}$  nuclei.

- probability for each nucleus to decay

$$p = \underline{8 \times 10^{-10}}/\text{s}$$

$$\rightarrow \mu = Np \sim 8 \times 10^5 \text{ decays/s}$$

In many cases, we know the mean counting rate  $\rightarrow$  eq. # reactions/sec.

$\rightarrow$  Want to know probability of observing  $r$  events in  $\tau$  units

$$P(r) = \frac{(\lambda\tau)^r}{r!} e^{-\lambda\tau}$$

where  $\lambda$  is rate in  $\tau$  units

In above example, probability of seeing 1 event in 3s is

$$P(1) = 2.4 \times 10^6 e^{-2.4 \times 10^6}$$

$\sim \underline{\underline{0}}$  (will see many more)

~~In~~ In typical experiment, if observe for 1 sec, error on rate

$$\frac{\sigma}{\mu} = \frac{1}{\sqrt{\mu}} \sim \underline{\underline{10^{-3}}}$$

# Gaussian Distribution

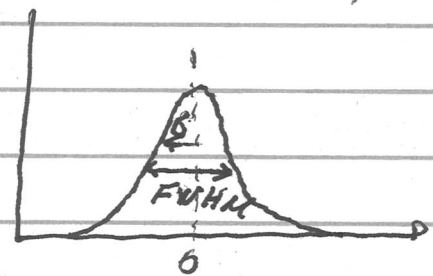
A distribution for a continuous variable

$$P(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(x-\mu)^2}{2\sigma^2}\right]$$

→  $\mu + \sigma^2$  are mean and variance of distribution

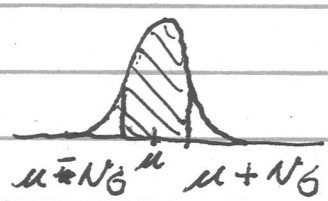
- a symmetric distribution in  $x$

FWHM (full-width at half maximum)  
= 2.356



Gaussian is a limiting case for Poisson if also switch to  $x$  being a continuous variable  
→ as  $\mu$  becomes large, Poisson gets more symmetric + adheres to Gaussian form

Integral intervals:



- $N=1: 68.3\%$
- $N=2: 95.5\%$
- $N=3: 99.7\%$

# Chi Squared Distribution

To test goodness-of-fit, define for  $n$  independent random variables,  $x_i$   
→ have Gaussian probability densities

$$u \equiv \chi^2 = \sum_{i=1}^n \left( \frac{x_i - \mu_i}{\sigma_i} \right)^2$$

The probability distribution of  $u$  is

$$P(u)du = \frac{\left(\frac{u}{2}\right)^{\frac{\nu}{2}-1} \exp\left(-\frac{u}{2}\right)}{2\Gamma(\nu/2)}$$

where  $\nu$  is # of independent variables in sum  
 $\Gamma$  is gamma function.

$\mu = \nu$	(ie. $\mu/\text{dof} = 1$ )
$\sigma^2 = 2\nu$	(ie. $\sigma/\text{dof} = \sqrt{2/\nu}$ )