

1. Read AH II Ch 19 (Higgs), Appx M (Gp Theory)
2. Consider the action of permuting three objects.
 - (a) Show that this forms a group.
 - (b) Give a matrix version of the defining representation, listing all elements.
 - (c) Show that this representation is reducible (Hint: find a vector which is an eigenvector of all the matrices.) Give the matrices in the reduced representation.
3. Apart from the trivial (scalar) representation, the simplest representations of the rotation group $SU(2)$ include vectors that are two-component objects called spinors. The generators are the 2×2 Pauli matrices (divided by two). Construct the matrix that rotates a spinor by a finite angle θ about the y axis using the Pauli matrix $(1/2)\sigma_x$. What is the effect of a rotation by 2π ?
4. Show that the combinations $\hat{x} \pm i\hat{y}$ rotate in the same way as states $|j, m\rangle$ with $j = 1$ and $m = \pm 1$.
5. The Lagrangian for a free, massive, vector boson is

$$\mathcal{L} = -\frac{1}{4}F^{\mu\nu}F_{\mu\nu} + \frac{1}{2}M^2 A^\mu A_\mu.$$

(Note the positive sign for the mass term, which is correct, unlike my lecture notes.)

- (a) Derive the Euler-Lagrange equations discussed in lecture.
- (b) Find the three independent solutions in momentum space for a free particle, $\epsilon^\mu(\mathbf{k}, \lambda) \exp(-ik \cdot x)$, in a frame in which \mathbf{k} is along the z axis. Choose the ϵ^μ vectors to be orthonormal,

$$\epsilon(\mathbf{k}, \lambda)^\mu \epsilon(\mathbf{k}, \lambda')^*_\mu = \delta_{\lambda, \lambda'}$$

and with definite helicity.

- (c) Give the form of these solutions in the particle's rest frame, and in the limit where the magnitude of \mathbf{k} is large.

For a massless field ($M = 0$), this becomes a gauge field. The equation

$$\partial_\mu A^\mu = 0$$

is no longer an equation of motion, but we may impose it as a gauge condition ("Lorentz gauge"). We may also impose $A^0 = 0$ (cf AH section 7.3). There are now only two independent solutions.

(d) Give these in a frame in which \mathbf{k} is along the z axis (again, with definite helicity).