

## lecture 30

## Probability Functions

When dealing with discrete random variables, define a **Probability Function** as probability for  $i^{\text{th}}$  possibility

$$P(x_i) = p_i$$



Defined as limit of long term frequency

- probability of rolling a 3 :=  $\lim_{\# \text{ trials} \rightarrow \infty} (\# \text{ rolls with 3} / \# \text{ trials})$ 
  - you don't need an infinite sample for definition to be useful

Normalization

$$\sum_i P(x_i) = 1$$

## Probability Density Functions

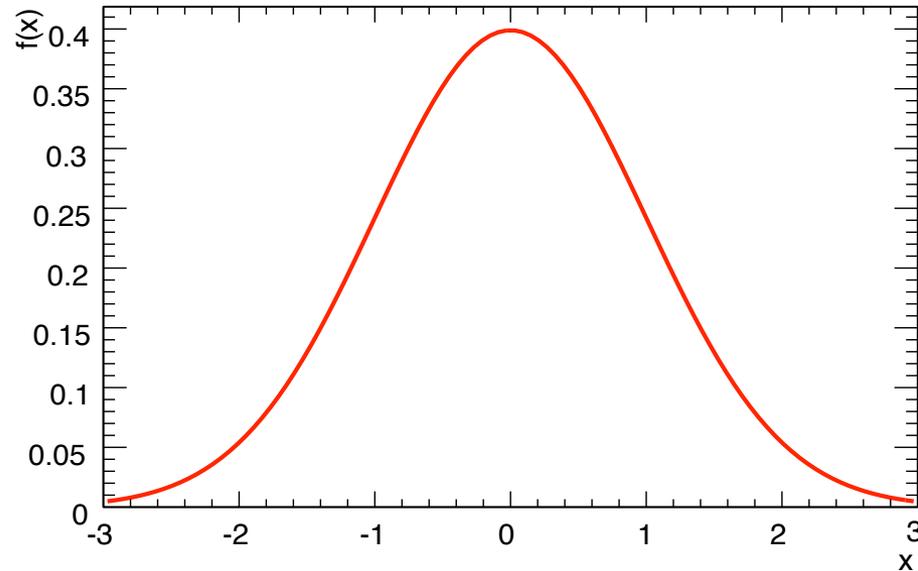
When dealing with continuous random variables, need to introduce the notion of a **Probability Density Function**

$$P(x \in [x, x + dx]) = f(x)dx$$

Note,  $f(x)$  is NOT a probability

PDFs are always normalized to unity:

$$\int_{-\infty}^{\infty} f(x)dx = 1$$



# What is Probability

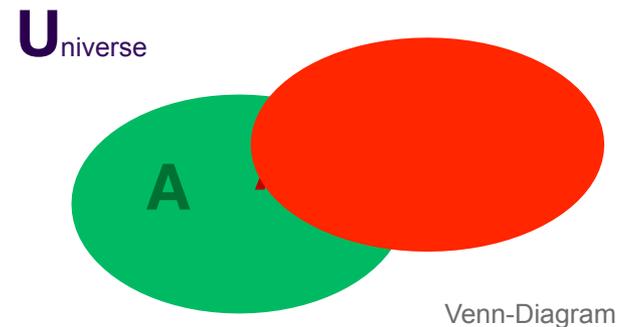
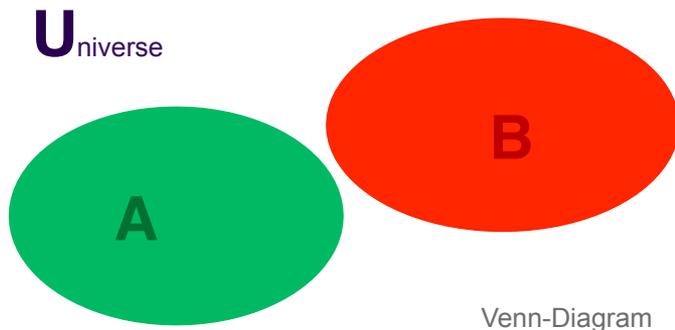
- **Axioms of probability: Kolmogorov (1933)**

- $P(A) \geq 0$
- $\int_U P(A)dU = 1$
- **if:  $(A \text{ and } B) \equiv (A \cap B) = 0$**   
**(i.e disjoint/independent/exclusive)**  
 $P(A \text{ or } B) \equiv (A \cup B) = P(A) + P(B)$



define e.g.: **conditional probability**

$$P(A|B) \equiv P(A \text{ given } B \text{ is true}) = \frac{P(A \cap B)}{P(B)}$$



# What is Probability

- Axioms of probability: - pure “set-theory”

**1) a measure of how likely an event will occur, expressed as the ratio of favourable—to—all possible cases in repeatable trials**

- Frequentist (classical) probability

$$P(\text{“Event”}) = \lim_{n \rightarrow \infty} \left( \frac{\text{\#outcome is “Event”}}{n_{\text{trials}}} \right)$$

**2) the “degree of belief” that an event is going to happen**

- Bayesian probability:
  - $P(\text{“Event”})$ : degree of belief that “Event” is going to happen -> no need for “repeatable trials”
  - degree of belief (in view of the data AND previous knowledge(belief) about the parameter) that a parameter has a certain “true” value



# Frequentist vs. Bayesian

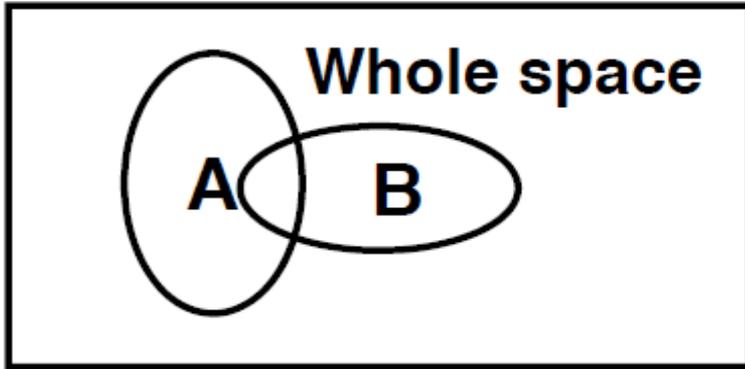
Bayes' Theorem

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)} = P(B|A) \frac{P(A)}{P(B)}$$

- This follows simply from the “conditional probabilities”:

# Derivation of Bayes' Theorem

... in picture ...taken from Bob Cousins



$$P(A) = \frac{\text{blue oval}}{\text{blue square}}$$

$$P(B) = \frac{\text{blue oval}}{\text{blue square}}$$

# Frequentist vs. Bayesian

Bayes' Theorem

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)} = P(B|A) \frac{P(A)}{P(B)}$$

- This follows simply from the “conditional probabilities”:

$$P(A|B)P(B) = P(A \cap B) = P(B \cap A) = P(B|A)P(A)$$

$$P(A|B)P(B) = P(B|A)P(A)$$

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

# Frequentist vs. Bayesian

Bayes' Theorem

$$P(\mu|n) = \frac{P(n|\mu)P(\mu)}{P(n)}$$

- $P(n|\mu)$ : Likelihood function
- $P(\mu|n)$ : posterior probability of  $\mu$
- $P(\mu)$ : the “prior”
- $P(n)$ : just some normalisation

∴ Nobody doubts Bayes' Theorem:  
discussion starts ONLY if it is used to turn

frequentist statements:

- probability of the observed data given a certain model:  $P(\text{Data}|\text{Model})$

into Bayesian probability statements:

- probability of a the model being correct (given data):  $P(\text{Model} | \text{Data})$

- ... there can be heated debates about ‘pro’ and ‘cons’ of either....

# $P(\text{Data}|\text{Theory}) \neq P(\text{Theory}|\text{Data})$

- Higgs search at LEP: the statement
  - the probability that the data is in agreement with the Standard Model background is less than 1% (i.e.  $P(\text{data}|\text{SMbkg}) < 1\%$ ) went out to the press and got turned round to:

~~$P(\text{data}|\text{SMbkg}) = P(\text{SMbkg}|\text{data}) < 1\%$     $P(\text{Higgs}|\text{data}) > 99\%$  !~~

**WRONG!**

An easy example:

Theory = fish (hypothesis) .. mammal (alternative)  
Data = swimming or not swimming

$P(\text{swimming} | \text{fish}) \sim 100\%$    but    $P(\text{fish} | \text{swimming}) = ??$

... OK... but what does it SAY?

# The correct frequentist interpretation

we know:  $P(\text{Data} \mid \text{Theory}) \neq P(\text{Theory} \mid \text{Data})$

Bayes Theorem:

$$P(\text{Data} \mid \text{Theory}) = P(\text{Theory} \mid \text{Data})$$

$$\frac{P(\text{Theory})}{P(\text{Data})}$$

Frequentists answer ONLY:  $P(\text{Data} \mid \text{Theory})$

**in reality** - we are all interested in  $P(\text{Theory} \dots)$

We only learn about the “probability” to observe certain data under a given theory. Without knowledge of how likely the theory (or a possible “alternative” theory) is .. we cannot say anything about how unlikely our current theory is !

We can define “confidence levels” ... e.g., if  $P(\text{data}) < 5\%$ , discard theory.

- can accept/discard theory and state how often/likely we will be wrong in doing so. But again: It does not say how “likely” the theory itself (or the alternative) is true
- note the subtle difference !!

# Frequentist vs. Bayesian

- **Certainly: both have their “right-to-exist”**
  - **Some “probably” reasonable and interesting questions cannot even be ASKED in a frequentist framework :**
    - “How much do I trust the simulation”
    - “How likely is it that it will raining tomorrow?”
    - “How likely is it that climate change is going to...
  - **after all.. the “Bayesian” answer sounds much more like what you really want to know: i.e.**
    - **“How likely is the “parameter value” to be correct/true ?”**
- **BUT:**
  - **NO Bayesian interpretation exist w/o “prior probability” of the parameter**
    - **where do we get that from?**
    - **all the actual measurement can provide is “frequentist”!**

# Bayesian Prior Probabilities

- “flat” prior  $\pi(\theta)$  to state “no previous” knowledge (assumptions) about the theory?

➤ often done, BUT WRONG:

- e.g. flat prior in  $M_{Higgs}$   $\rightarrow$  not flat in  $M_{Higgs}^2$

➤ Choose a prior that is invariant under parameter transformations

Jeffrey’s Prior  $\rightarrow$  “objective Bayesian”:

- “flat” prior in Fisher’s information space

- $\pi(\theta) \propto \sqrt{I(\theta)}$   $(\pi(\theta) \propto \sqrt{\det I(\theta)}$  if several parameters)

$$I(\theta) = -E_x \left[ \frac{\partial^2}{\partial \theta^2} \log(f(x; \theta)) \right]:$$

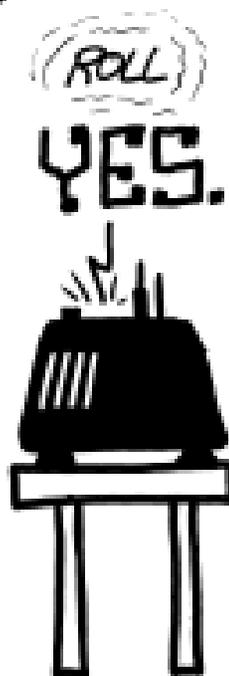
- $f(x; \theta)$ : Likelihood function of  $\theta$ , probability to observe  $x$  for a give parameter  $\theta$
- amount of “information” that data  $x$  is ‘expected’ to contain about the parameter  $\theta$
- **personal remark: nice idea, but “WHY” would you want to do that?**
  - still use a “arbitrary” prior, only make sure everyone does the same way
  - loose all “advantages” of using a “reasonable” prior if you choose already to

# DID THE SUN JUST EXPLODE? (IT'S NIGHT, SO WE'RE NOT SURE.)

THIS NEUTRINO DETECTOR MEASURES  
WHETHER THE SUN HAS GONE NOVA.

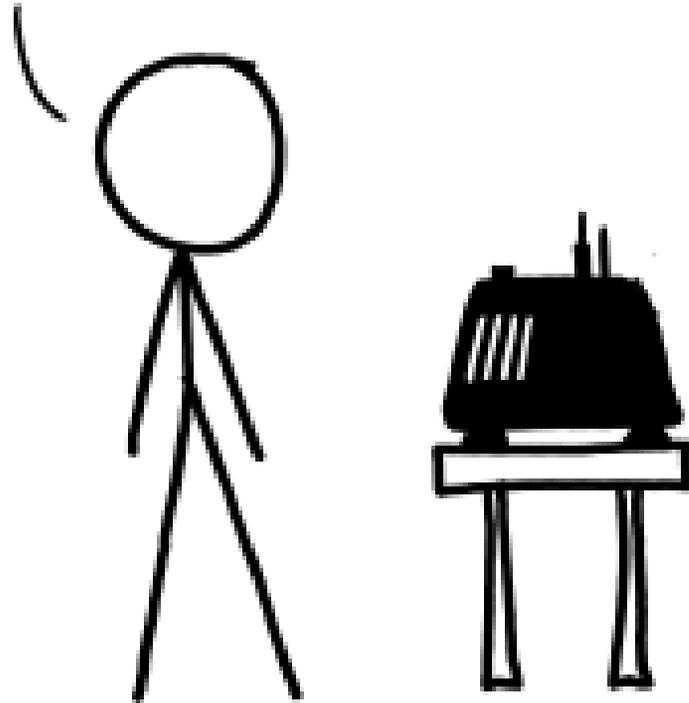
THEN, IT ROLLS TWO DICE. IF THEY  
BOTH COME UP SIX, IT LIES TO US.  
OTHERWISE, IT TELLS THE TRUTH.

LET'S TRY.  
DETECTOR! HAS THE  
SUN GONE NOVA?



## FREQUENTIST STATISTICIAN:

THE PROBABILITY OF THIS RESULT  
HAPPENING BY CHANCE IS  $\frac{1}{36} = 0.027$ .  
SINCE  $p < 0.05$ , I CONCLUDE  
THAT THE SUN HAS EXPLODED.



## BAYESIAN STATISTICIAN:

BET YOU \$50  
IT HASN'T.

