

# Non linear Simple Pendulum

$$\ddot{\theta}(t) = -\frac{g}{l} \sin[\theta(t)]$$

$$\text{IF } [\dot{\theta}(t)]^2 = \frac{2g}{l} \left\{ \cos[\theta(t)] - \cos[\theta_0] \right\} \quad \text{then} \quad \leftarrow \text{constant}$$

$$\frac{d}{dt} [\dot{\theta}(t)]^2 = 2\dot{\theta}(t)\ddot{\theta}(t) = -\frac{2g}{l} \sin[\theta(t)] \dot{\theta}(t)$$

$$\Rightarrow \ddot{\theta}(t) = -\frac{g}{l} \sin[\theta(t)] \quad \text{when } \dot{\theta}(t) \neq 0 \quad \forall t$$

$$\dot{\theta}(t) = \sqrt{\frac{2g}{l} [\cos \theta - \cos \theta_0]} = \frac{d\theta}{dt}$$

$$T = 4 \int_{t=0}^{t(\theta_0)} dt = 4 \int_{\theta=0}^{\theta_0} \frac{d\theta}{\sqrt{\frac{2g}{l} [\cos \theta - \cos \theta_0]}}$$

substitute  $\cos \theta = 1 - 2 \sin^2\left(\frac{\theta}{2}\right)$

$$T = 4 \sqrt{\frac{l}{2g}} \int_{\theta=0}^{\theta_0} \frac{d\theta}{\sqrt{2 \sin^2\left(\frac{\theta_0}{2}\right) - 2 \sin^2\left(\frac{\theta}{2}\right)}} = 2 \sqrt{\frac{l}{g}} \int_{\theta=0}^{\theta_0} \frac{d\theta}{\sqrt{\sin^2\left(\frac{\theta_0}{2}\right) - \sin^2\left(\frac{\theta}{2}\right)}}$$

Change of variable:  $\sin\left(\frac{\theta}{2}\right) \equiv \sin\left(\frac{\theta_0}{2}\right) \sin \varphi$

$$d\left[\sin\left(\frac{\theta}{2}\right)\right] = \frac{1}{2} \cos\left(\frac{\theta}{2}\right) d\theta = \sin\left(\frac{\theta_0}{2}\right) \cos \varphi d\varphi$$

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$$T = 2\sqrt{\frac{l}{g}} \int_{\varphi=0}^{\pi/2} \frac{d\varphi \cdot 2 \cos \varphi \sin\left(\frac{\theta_0}{2}\right)}{\cos\left(\frac{\theta}{2}\right) \sqrt{\sin^2\left(\frac{\theta_0}{2}\right) - \sin^2\left(\frac{\theta_0}{2}\right) \sin^2 \varphi}}$$

$$T = 2\sqrt{\frac{l}{g}} \int_{\varphi=0}^{\pi/2} \frac{d\varphi \cdot 2 \cos \varphi}{\cos\left(\frac{\theta}{2}\right) \sqrt{1 - \sin^2 \varphi}} = 4\sqrt{\frac{l}{g}} \int_{\varphi=0}^{\pi/2} \frac{d\varphi}{\cos\left(\frac{\theta}{2}\right)}$$

$$T = 4\sqrt{\frac{l}{g}} \int_{\varphi=0}^{\pi/2} \frac{d\varphi}{\sqrt{1 - \sin^2\left(\frac{\theta_0}{2}\right) \sin^2 \varphi}}$$

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Binomial Expansion (convergent for  $x < 1$ )

$$\frac{1}{\sqrt{1-x}} = 1 + \frac{1}{2}x + \frac{1}{2} \cdot \frac{3}{4}x^2 + \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6}x^3 + \dots$$

$$x = \sin^2\left(\frac{\theta_0}{2}\right) \sin^2 \varphi < 1$$

$$T = 4\sqrt{\frac{l}{g}} \int_{\varphi=0}^{\pi/2} d\varphi \left[ 1 + \frac{1}{2} \sin^2\left(\frac{\theta_0}{2}\right) \sin^2\varphi + \frac{1}{2} \cdot \frac{3}{4} \sin^4\left(\frac{\theta_0}{2}\right) \sin^4\varphi + \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6} \sin^6\left(\frac{\theta_0}{2}\right) \sin^6\varphi + \dots \right]$$

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$$\text{Now } \int_{\varphi=0}^{\pi/2} \sin^2\varphi = \frac{\pi}{4} \quad \text{and} \quad \int_{\varphi=0}^{\pi/2} \sin^4\varphi = \frac{3\pi}{16}$$


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$$T = 4\sqrt{\frac{l}{g}} \left[ \frac{\pi}{2} + \frac{1}{2} \sin^2\left(\frac{\theta_0}{2}\right) \frac{\pi}{4} + \frac{1}{2} \cdot \frac{3}{4} \sin^4\left(\frac{\theta_0}{2}\right) \frac{3\pi}{16} + \dots \right]$$

$$T = 2\pi\sqrt{\frac{l}{g}} \left[ 1 + \underbrace{\left(\frac{1}{2}\right)^2 \sin^2\left(\frac{\theta_0}{2}\right) + \left(\frac{1}{2} \cdot \frac{3}{4}\right)^2 \sin^4\left(\frac{\theta_0}{2}\right) + \dots}_{\text{non-linear corrections}} \right]$$



linear  
result

non-linear corrections

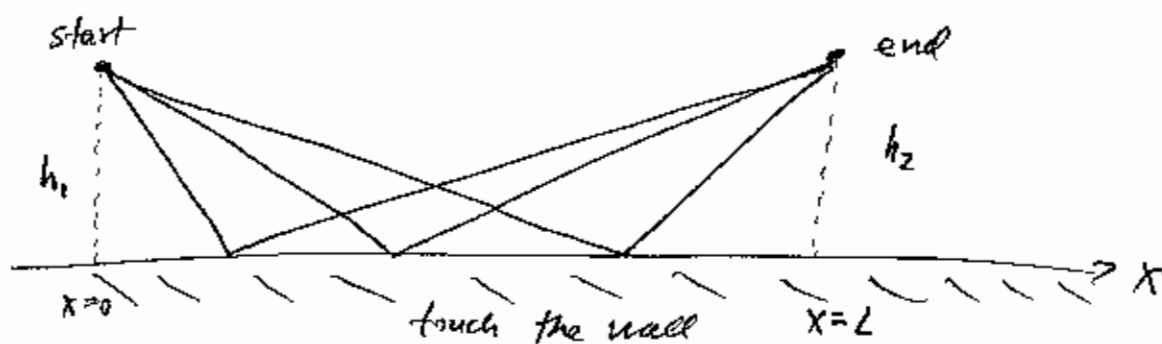
This period is written as an expansion in  $\sin^2\left(\frac{\theta_0}{2}\right)$ .

To compare with Marion, where the expansion is in  $\frac{\theta_0}{2}$ ,

$$\text{use } \sin x = x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 - \dots$$

# Extremization Principles

## Specular Reflection

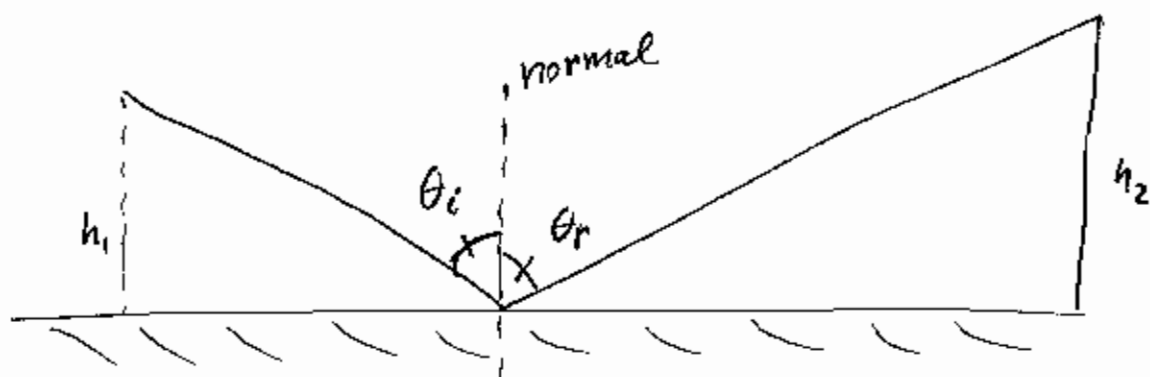


path length:  $D = \sqrt{h_1^2 + x^2} + \sqrt{h_2^2 + (L-x)^2}$

extremize (minimize)

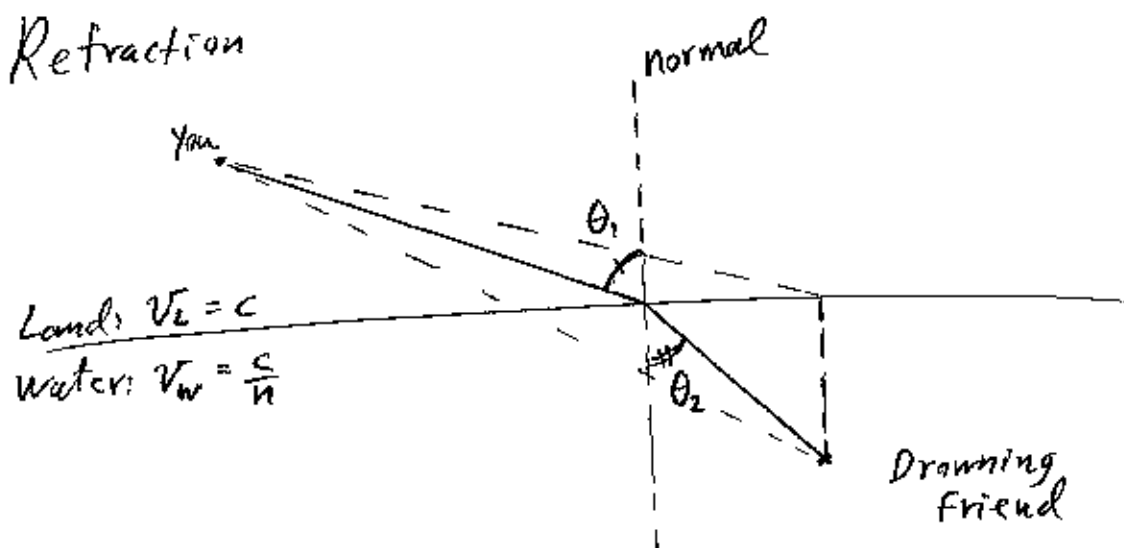
$$\left. \frac{dD}{dx} \right|_{x=x_0} = 0 \quad x_0 = \frac{L}{2} \text{ if } h_1 = h_2$$

Light takes the path that minimizes the distance travelled.



The incident angle = the reflected angle.

## Refraction



Minimizing the travel time gives Snell's Law

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

$$t = \frac{\sqrt{h_1^2 + x^2}}{v_L} + \frac{\sqrt{h_2^2 + (L-x)^2}}{v_W}$$

$$\left. \frac{dt}{dx} \right|_{x=x_D} = 0$$

In hindsight, the Law of Specular Reflection also follows from minimizing the time rather than the distance.