

Due: 7 September 2006

1. Show that  $\hat{e}_\theta = -\hat{e}_r\dot{\theta}$ .
2. Find the radial and tangential components of the jerk (time derivative of the acceleration) in two dimensions.
3. If  $\vec{X}$  is an unknown vector satisfying the following relations involving the known vectors  $\vec{A}$  and  $\vec{B}$  and the known scalar  $\phi$

$$\vec{A} \times \vec{X} = \vec{B} \qquad \vec{A} \cdot \vec{X} = \phi$$

express  $\vec{X}$  in terms of  $\vec{A}$ ,  $\vec{B}$ , and  $\phi$ .

4. Derive the scale factors  $h_r$ ,  $h_\theta$ , and  $h_\phi$  for spherical polar coordinates from the equations relating  $\{r, \theta, \phi\}$  to  $\{x, y, z\}$ .
5. Evaluate the following. (You may find it convenient to work in spherical polar coordinates, although Cartesian will give the same answers.) Simplify as much as possible.
  - (a)  $\vec{\nabla} r$  where  $r = |\vec{r}|$  (gradient of the magnitude of the displacement vector)
  - (b)  $\vec{\nabla} \cdot \vec{r}$  (divergence of the displacement vector)
  - (c)  $\vec{\nabla} \times \vec{r}$  (curl of the displacement vector)
  - (d)  $\vec{\nabla}[\ln(r)]$  (gradient of the natural logarithm of the magnitude of the displacement vector)
  - (e)  $\nabla^2[\ln(r)]$  (laplacian of the natural logarithm of the magnitude of the displacement vector)