

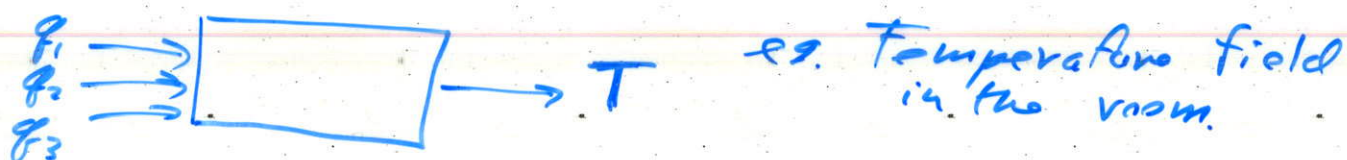
Displacement Vector \vec{r}

Cartesian: $x\hat{e}_x + y\hat{e}_y + z\hat{e}_z = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = (x, y, z)$

Spherical: $r\hat{e}_r + \text{~~stuff~~}$

Cylindrical: $s\hat{e}_s + z\hat{e}_z$

Scalar Fields (Scalar Function of Coordinates)



$T(\vec{r}) = T(r_1, r_2, r_3)$ e.g. $T(x, y, z)$ or $T(r, \theta, \phi)$

Coordinate-free notation

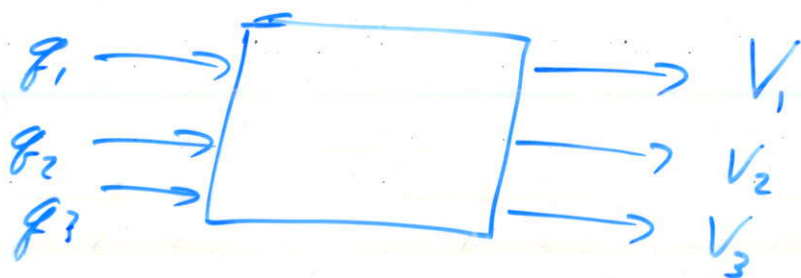
$T(x, y, z) = T(1\text{m east}, 2\text{m north}, 3\text{m up})$

$T(r, \theta, \phi) = T(4000\text{mi}, 57.3^\circ, 263.2^\circ)$

functions $T(x, y, z) = x^2\sqrt{y} + \cos(z)$

$T(r, \theta, \phi) = \frac{1}{r} \sec \phi$

Vector Fields (Vector Functions of Coordinates)



3 coordinates $\{r_i\}$
3 components $\{V_i\}$
because \mathbb{R}^3

$V_\theta(r, \theta, \phi) = \vec{V} \cdot \hat{e}_\theta$

$$\vec{V}(\vec{r}) = V_1(r_1, r_2, r_3) \hat{e}_1(r_1, r_2, r_3) + V_2(r_1, r_2, r_3) \hat{e}_2(r_1, r_2, r_3) + V_3(r_1, r_2, r_3) \hat{e}_3(r_1, r_2, r_3)$$

Cartesian: $\vec{V}(\vec{r}) = V_x(x, y, z) \hat{e}_x + V_y(x, y, z) \hat{e}_y + V_z(x, y, z) \hat{e}_z$

↑
constant vector

e.g. $\vec{V}(\vec{r}) = x^3 y^4 \hat{e}_x + \frac{1}{x} \sin y \hat{e}_y + 3 \hat{e}_z$

Spherical: $\vec{V}(\vec{r}) = V_r(r, \theta, \phi) \hat{e}_r(r, \theta, \phi)$

↑
radial component

+ $V_\theta(r, \theta, \phi) \hat{e}_\theta(r, \theta, \phi) + V_\phi(r, \theta, \phi) \hat{e}_\phi(r, \theta, \phi)$

↑
polar component

↑
azimuthal component

e.g. $\vec{V}(\vec{r}) = \frac{1}{r} \tan \theta \hat{e}_r + \theta^2 \hat{e}_\theta + r \tan \phi \cos^2 \theta \hat{e}_\phi$

3 scalars in a matrix \neq vector

e.g. $\begin{pmatrix} 2 \text{ apples} \\ 1 \text{ banana} \\ 3 \text{ peaches} \end{pmatrix}$

Vectors (in any coordinate system) transform under rotations like \vec{v} . vectors: $\vec{v}, \vec{a}, \vec{p}, \vec{L}, \vec{F}, \vec{c}$

Differential Operators

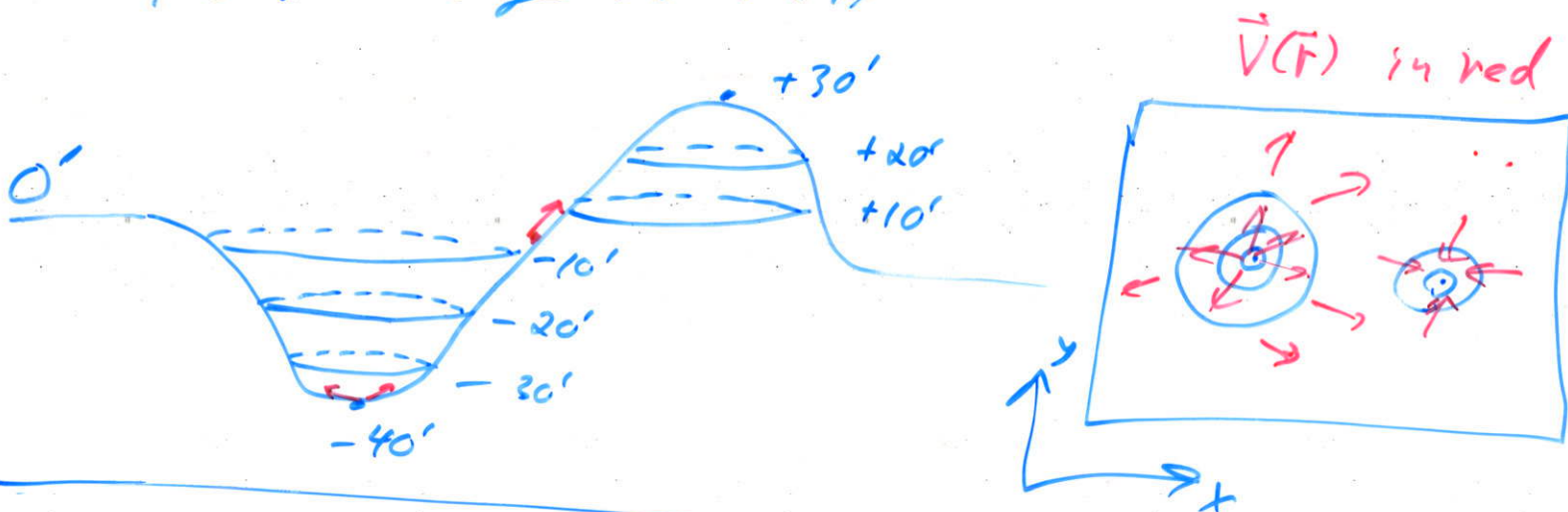
① Gradient acts on scalar field and produces a vector field



$\vec{\nabla}$ nabra, del

$$\vec{V}(\vec{r}) = \vec{\nabla}[T(\vec{r})] = \text{grad}[T(\vec{r})]$$

physically, $\vec{V}(\vec{r})$ points in the direction of the fastest change in $T(\vec{r})$



Cartesian: $\vec{\nabla} T = \hat{e}_x \frac{\partial T(x,y,z)}{\partial x} + \hat{e}_y \frac{\partial T(x,y,z)}{\partial y} + \hat{e}_z \frac{\partial T(x,y,z)}{\partial z}$

$\underbrace{\hspace{10em}}_{V_x}$
 $\underbrace{\hspace{10em}}_{V_y}$
 $\underbrace{\hspace{10em}}_{V_z}$

scalar field

$$f(\vec{r}) = x^2 \sin(y) + \cos(z)$$

$$\begin{aligned} \vec{\nabla} f(\vec{r}) &= \hat{e}_x 2x \sin(y) + \hat{e}_y x^2 \cos(y) + -\hat{e}_z \sin(z) \\ &= \begin{pmatrix} 2x \sin(y) \\ x^2 \cos(y) \\ -\sin(z) \end{pmatrix} \end{aligned}$$

In general $\{q_1, q_2, q_3\}$ $T(\vec{q})$ scalar field

$$\vec{\nabla} T(\vec{q}) = \frac{\hat{e}_1}{h_1} \frac{\partial T}{\partial q_1} + \frac{\hat{e}_2}{h_2} \frac{\partial T}{\partial q_2} + \frac{\hat{e}_3}{h_3} \frac{\partial T}{\partial q_3}$$

Spherical Polar

$$\vec{\nabla} T(\vec{r}) = \hat{e}_r \frac{\partial T}{\partial r} + \frac{\hat{e}_\theta}{r} \frac{\partial T}{\partial \theta} + \frac{\hat{e}_\phi}{r \sin \theta} \frac{\partial T}{\partial \phi}$$

Cylindrical Polar

$$\vec{\nabla} T(\vec{r}) = \hat{e}_s \frac{\partial T}{\partial s} + \frac{\hat{e}_\phi}{s} \frac{\partial T}{\partial \phi} + \hat{e}_z \frac{\partial T}{\partial z}$$

e.g. Electrostatic scalar potential (Voltage)

Cartesian

$$\Phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{x^2 + y^2 + z^2}}$$

point charge q
at the origin.
in MKS units.

Spherical polar

$$\Phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$$

Next Electrostatic Field $\vec{E}(\vec{r}) \equiv -\vec{\nabla}\Phi(\vec{r})$

$$\text{Cartesian } \vec{E}(x, y, z) = -\left[\hat{e}_x \frac{\partial}{\partial x} + \hat{e}_y \frac{\partial}{\partial y} + \hat{e}_z \frac{\partial}{\partial z}\right] \Phi(x, y, z)$$

$$\begin{aligned} \text{one piece } \frac{\partial}{\partial x} \Phi(x, y, z) &= \frac{\partial}{\partial x} \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{x^2 + y^2 + z^2}} \\ &= \frac{q}{4\pi\epsilon_0} \frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{-1/2} = \frac{q}{4\pi\epsilon_0} \left(-\frac{1}{2}\right) (x^2 + y^2 + z^2)^{-3/2} \cdot 2x \\ &= -\frac{q}{4\pi\epsilon_0} \frac{x}{(\sqrt{x^2 + y^2 + z^2})^3} \end{aligned}$$

$$\begin{aligned} \vec{E}(x, y, z) &= \hat{e}_x \frac{q}{4\pi\epsilon_0} \frac{x}{(\sqrt{x^2 + y^2 + z^2})^3} + \hat{e}_y \frac{q}{4\pi\epsilon_0} \frac{y}{(\sqrt{x^2 + y^2 + z^2})^3} \\ &\quad + \hat{e}_z \frac{q}{4\pi\epsilon_0} \frac{z}{(\sqrt{x^2 + y^2 + z^2})^3} \end{aligned}$$

$$\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{(\sqrt{x^2 + y^2 + z^2})^3} = \frac{q}{4\pi\epsilon_0} \frac{\vec{r}}{|\vec{r}|^3} \leftarrow$$

Spherical
Polar $\Phi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$

$$\begin{aligned} \vec{E}(r, \theta, \phi) &= -\vec{\nabla}\Phi(r, \theta, \phi) = -\hat{e}_r \frac{\partial \Phi}{\partial r} = -\hat{e}_r \frac{d}{dr} \left[\frac{q}{4\pi\epsilon_0} \frac{1}{r} \right] \\ &= +\hat{e}_r \frac{q}{4\pi\epsilon_0} \frac{1}{r^2} \leftarrow \quad \hat{e}_r = \frac{\vec{r}}{|\vec{r}|} \end{aligned}$$