

Coordinate-Free Schrödinger Eq.

$$i\hbar \frac{\partial}{\partial t} \Psi(\vec{r}, t) = -\frac{\hbar^2}{2m} \nabla^2 \Psi(\vec{r}, t) + V(\vec{r}) \Psi(\vec{r}, t)$$

Separation of Variables

$$f(\vec{r}) = \Psi(\vec{r})$$

$$\Psi(x, y, z, t) = f_1(x) \cdot f_2(y) \cdot f_3(z) \cdot g(t)$$

$$\Psi(r, \theta, \varphi, t) = R(r) \cdot \overset{Y(\theta, \varphi)}{T(\theta) \cdot F(\varphi)} \cdot g(t)$$

$$g(t) = g_0 e^{-\frac{itE}{\hbar}} \quad E \text{ is separation constant.}$$

$$\text{solution to } \frac{\ddot{g}(t)}{g(t)} = -E$$

Laplacian Operator in Spherical Polar Coord's

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \theta} \left( \sin^2 \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2}$$

Time-independent S.E.

$$-\frac{\hbar^2}{2m} \nabla^2 f(\vec{r}) + V(\vec{r}) f(\vec{r}) = E f(\vec{r})$$

$$f(\vec{r}) = R(r) Y(\theta, \varphi)$$

S.E.

$$-\frac{\hbar^2}{2m} \left\{ \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial R(r) Y(\theta, \phi)}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial R(r) Y(\theta, \phi)}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 R(r) Y(\theta, \phi)}{\partial \phi^2} \right\} + V(r) R(r) Y(\theta, \phi) = E R(r) Y(\theta, \phi)$$

divide both sides by  $R(r) Y(\theta, \phi)$

$$-\frac{\hbar^2}{2m} \left\{ \frac{1}{R(r)} \frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{dR(r)}{dr} \right) + \frac{1}{Y(\theta, \phi)} \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y(\theta, \phi)}{\partial \theta} \right) + \frac{1}{Y(\theta, \phi)} \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 Y(\theta, \phi)}{\partial \phi^2} \right\} + \frac{V(r)}{r^2} - E = 0$$

function of  $r$ , not  $\theta$  &  $\phi$

multiply by  $r^2$ , divide by  $-\frac{\hbar^2}{2m}$

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$$\frac{1}{R(r)} \frac{d}{dr} \left( r^2 \frac{dR(r)}{dr} \right) - \frac{2m r^2}{\hbar^2} [V(r) - E]$$

$$+ \left[ \frac{1}{Y(\theta, \varphi)} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y(\theta, \varphi)}{\partial \theta} \right) \right.$$

$$\left. + \frac{1}{Y(\theta, \varphi)} \frac{1}{\sin^2 \theta} \frac{\partial^2 Y(\theta, \varphi)}{\partial \varphi^2} \right] = 0$$

$$\begin{array}{ccc} W(r) + B(\theta, \varphi) = 0 & \forall r, \theta, \varphi \\ \parallel & \parallel \\ C & -C \\ l(l+1) & -l(l+1) \end{array} \leftarrow \text{for later convenience}$$

Radial Equation

$$\text{ODE: } \frac{1}{R(r)} \frac{d}{dr} \left[ r^2 \frac{dR(r)}{dr} \right] - \frac{2m r^2}{\hbar^2} [V(r) - E] = l(l+1)$$

Angular Equation

$$\text{PDE: } \frac{1}{Y(\theta, \varphi)} \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial Y(\theta, \varphi)}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y(\theta, \varphi)}{\partial \varphi^2} \right] = -l(l+1)$$

$$\text{Ansatz: } Y(\theta, \varphi) = T(\theta) \cdot F(\varphi) \quad \begin{array}{l} \text{multiply by} \\ \sin^2 \theta \end{array}$$

