

Conservation Laws

For a single particle, Newton's 2nd Law

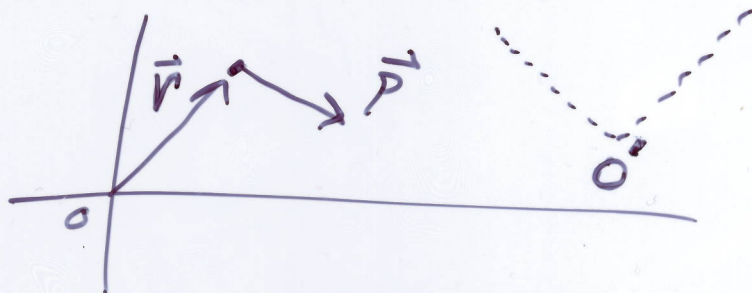
$$\vec{F}_{\text{tot}} = \frac{d\vec{p}}{dt}$$

If the total force is zero, then the linear momentum of the particle is conserved (is constant in time)

$$\vec{F}_{\text{tot}} = 0 \Rightarrow \frac{d\vec{p}}{dt} = 0 \Rightarrow \vec{p} = \text{constant} \Rightarrow \vec{p}(t_1) = \vec{p}(t_2).$$

Angular Momentum about origin O

$$\vec{L}_O \equiv \vec{r} \times \vec{p}$$



Torque $\vec{N}_O^{(1)} = \vec{r} \times \vec{F}^{(1)}$, $\vec{N}_O^{(2)} = \vec{r} \times \vec{F}^{(2)}$, ...

$$\vec{N}_{\text{tot}} = \vec{r} \times \vec{F}_{\text{tot}} = \vec{r} \times \frac{d\vec{p}}{dt} = \vec{r} \times m \frac{d\vec{v}}{dt}$$

If $m = \text{constant}$.

$$\text{Notice: } \frac{d}{dt}(\vec{r} \times \vec{v}) = \underbrace{\frac{d\vec{r}}{dt} \times \vec{v}}_{\vec{v} \times \vec{v} = 0} + \vec{r} \times \frac{d\vec{v}}{dt}$$

$$\vec{N}_{\text{tot}} = \frac{d}{dt} (\vec{r} \times m\vec{v}) = \frac{d\vec{L}_0}{dt} = \dot{\vec{L}}_0$$

If the total torque acting on a particle is zero, then the angular momentum of that particle is conserved.

If all the forces acting on a particle are conservative, then

$$\vec{\nabla} \times \vec{F}_{\text{tot}} = 0 \implies \oint \vec{F}_{\text{tot}} \cdot d\vec{r} = 0 \implies \vec{F}_{\text{tot}} = -\vec{\nabla} V(\vec{r})$$

\nwarrow Stokes' theorem \nearrow

\leftarrow total derivative

$$\vec{F}_{\text{tot}} \cdot d\vec{r} = -(\vec{\nabla} V) \cdot d\vec{r} = -dV$$

$$\text{Work: } W = \int_i^f \vec{F}_{\text{tot}} \cdot d\vec{r} = \int_i^f m \frac{d\vec{v}}{dt} \cdot \vec{v} dt = \frac{m}{2} \int_i^f \frac{d}{dt} (v^2) dt$$

$$= \frac{m}{2} (v_f^2 - v_i^2) = T_f - T_i \leftarrow \text{kinetic energy}$$

$$W = - \int_i^f dV = -V_f + V_i$$

$$-V_f + V_i = T_f - T_i \implies V_i + T_i = V_f + T_f$$

total mechanical energy = kinetic + potential.

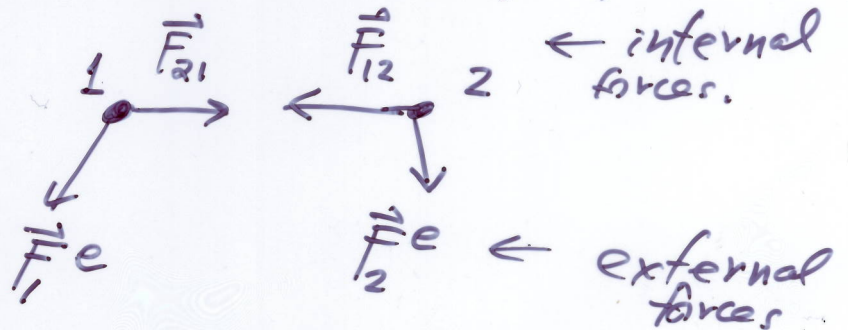
If the forces acting on a particle are conservative, then the total mechanical energy of the particle is conserved.

Note: $V = V(\vec{r})$ only coordinates

if $V(\vec{r}, t)$, then $T+V$ not conserved.

Consider a system of N interacting particles.

First, just two



Internal forces are caused by some particle in the system and act on a different particle in the system.

External forces are caused by some agent not in the system.

Newton's 3rd law

$$\vec{F}_{12} = -\vec{F}_{21}$$

Weak form of Law of action and reaction

This is not always true! E.g. velocity-dependent forces

$$\vec{F}_{\text{mag}} = q \vec{v} \times \vec{B}$$

Total force on the i^{th} particle.

$$\vec{F}_{\text{tot } i} = \vec{F}_i^e + \sum_{j=1}^N \vec{F}_{ji} = \dot{\vec{p}}_i$$

prime on sum means omit $j=i$ term

Total forces on the system

$$\sum_{i=1}^N \vec{F}_{\text{tot } i} = \sum_i \vec{F}_i^e + \sum_{i,j} \vec{F}_{ji} = \frac{d^2}{dt^2} \sum_i m_i \vec{r}_i$$

total external
force on system

$$\vec{F}_{\text{tot}}^e$$

zero, forces will
cancel in pairs
if Weak form 3rd Law holds.

Define the center of mass position

$$\vec{R}_{\text{cm}} \equiv \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i} = \frac{\sum_i m_i \vec{r}_i}{M_{\text{tot}}}$$

$$\Rightarrow \vec{F}_{\text{Tot}}^e = M_{\text{Tot}} \frac{d^2 \vec{R}_{\text{cm}}}{dt^2}$$

The center of mass (c-o-m) of a system moves as if all the mass were concentrated there and subject to the net external forces.

E.g. Exploding Bomb



The total Linear momentum of the system

$$\vec{P}_{\text{tot}} = \sum_i \vec{P}_i = \sum_i m_i \frac{d\vec{v}_i}{dt} = M_{\text{tot}} \frac{d\vec{R}_{\text{cm}}}{dt} \equiv M_{\text{tot}} \vec{V}_{\text{cm}}$$

$$\vec{F}_{\text{tot}}^e = \dot{\vec{P}}_{\text{tot}}$$

If the total external force on a system is zero, then the total linear momentum of the system is conserved.

$$\vec{F}_{\text{tot}}^e = 0 \Rightarrow \vec{P}_{\text{tot}} = \text{constant} \Rightarrow \vec{P}_{\text{tot}}(t_1) = \vec{P}_{\text{tot}}(t_2)$$

Total Angular Momentum of a system

$$\vec{L}_{\text{tot}} = \sum_i \vec{L}_i = \sum_i \vec{r}_i \times m_i \vec{v}_i = \sum_i \vec{r}_i \times \vec{p}_i$$

$$\begin{aligned} \dot{\vec{L}}_{\text{tot}} &= \sum_i \frac{d}{dt} (\vec{r}_i \times m_i \vec{v}_i) \\ &= \underbrace{\sum_i \vec{v}_i \times m_i \vec{v}_i}_{\text{zero}} + \sum_i \vec{r}_i \times \dot{\vec{p}}_i = \sum_i \vec{r}_i \times \vec{F}_{i,\text{tot}} \end{aligned}$$

$$= \underbrace{\sum_i \vec{r}_i \times \vec{F}_i^e}_{\text{wavy}} + \underbrace{\sum_{i \neq j} \vec{r}_i \times \vec{F}_{ji}}_{\text{red underline}} \quad ?$$

$$\sum_i \vec{N}_{oi}^e = \vec{N}_o^e$$

= total external torque about origin O.

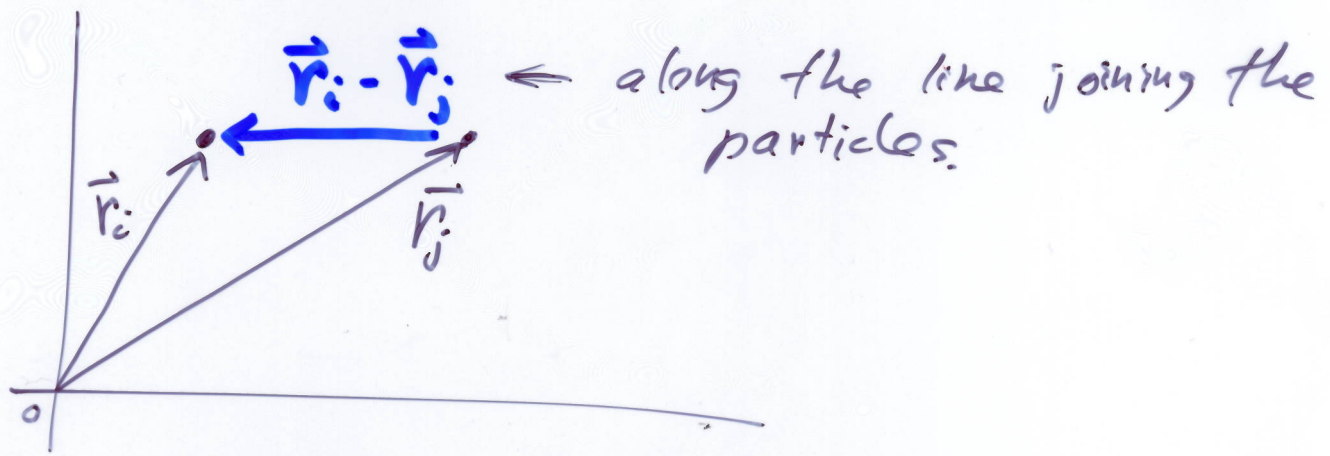
$$\sum_{i \neq j} \vec{r}_i \times \vec{F}_{ji} = \sum_{\substack{i=1 \\ (i \neq j)}}^N \sum_{j=1}^N \vec{r}_i \times \vec{F}_{ji} = \sum_{\substack{j=1 \\ (j \neq i)}}^N \sum_{i=1}^N \vec{r}_j \times \vec{F}_{ij}$$

$$= \frac{1}{2} \sum_{i \neq j} (\vec{r}_i \times \vec{F}_{ji} + \vec{r}_j \times \vec{F}_{ij})$$

$$= \frac{1}{2} \sum_{i \neq j} (\vec{r}_i - \vec{r}_j) \times \vec{F}_{ji}$$

using weak form of 3rd Law

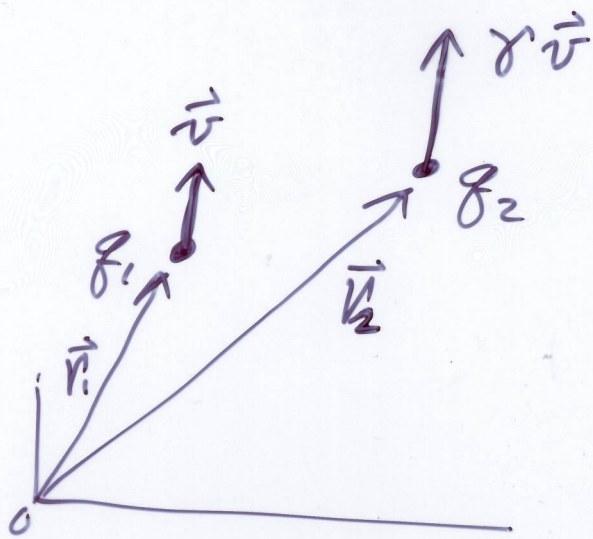
that is, $\vec{F}_{ij} = -\vec{F}_{ji}$ ←



So $\frac{1}{2} \sum_{ij} (\vec{r}_i - \vec{r}_j) \times \vec{F}_{ji}$ will be zero if the forces also act on a line joining the particles (Eg. Coulomb electric force, gravity). This is called the strong form of the 3rd Law.

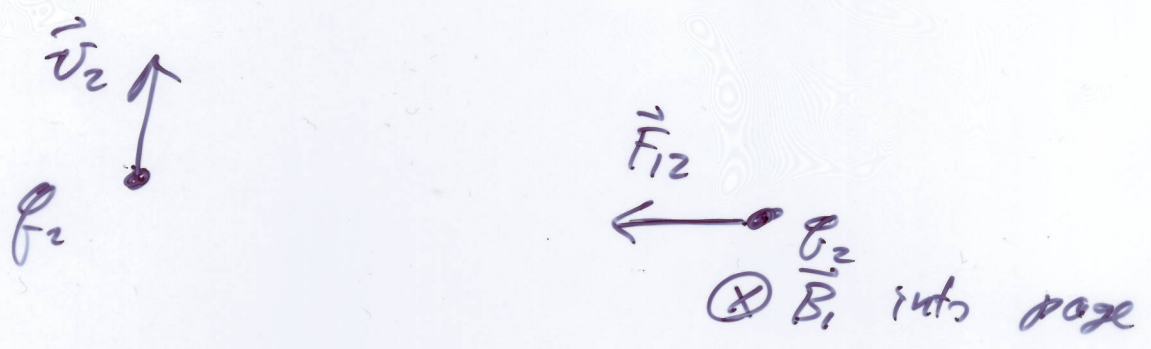
$$\vec{N}_{tot}^e = \dot{\vec{L}}_{tot}$$

If the total external torque is zero, then the total angular momentum of the system is constant. **(IF the strong form of the 3rd Law holds.)**



\vec{F}_{12}
 $\leftarrow q_2$
 $q_1 \rightarrow \vec{F}_{21}$
 satisfies the weak form
 but violates the strong
 form of the third Law

$$\vec{F}_{12} = -\vec{F}_{21}$$



Here even the weak form of the 3rd Law is violated

$$\vec{F}_{12} \neq -\vec{F}_{21}$$