

Euler-Lagrange for radial coordinate r

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{r}} - \frac{\partial L}{\partial r} = 0$$

$$m \ddot{r} - m r \dot{\theta}^2 + \frac{\partial V}{\partial r} = 0$$

↑
reduced mass

∩
- $f(r)$

substitute: $\dot{\theta} = \frac{l}{m r^2}$

$$m \ddot{r} = \frac{l^2}{m r^3} + f(r) \quad \text{one-dimensional problem}$$

$$\downarrow \quad \quad \downarrow \quad \quad \uparrow$$

$ma =$ centrifugal force real force

$$m \ddot{r} = - \frac{d}{dr} \left[\frac{1}{2} \frac{l^2}{m r^2} + V \right]$$

effective potential V_{eff}

Multiply both sides by integrating factor \dot{r}

$$m \ddot{r} \dot{r} = - \frac{d}{dr} \left[\frac{1}{2} \frac{l^2}{m r^2} + V \right] \dot{r} = - \frac{d}{dr} \left[\frac{l^2}{2 m r^2} + V \right] \frac{dr}{dt}$$
$$= \frac{d}{dt} \left(\frac{1}{2} m \dot{r}^2 \right)$$

$$\Rightarrow \frac{d}{dt} \left[\frac{1}{2} m \dot{r}^2 + \frac{l^2}{2 m r^2} + V(r) \right] = 0$$

$$\frac{1}{2} m \dot{r}^2 + \frac{l^2}{2mr^2} + V(r) = \text{constant} = E$$

energy

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + V(r) = T + V$$

$$\dot{r} = \frac{dr}{dt} = \sqrt{\frac{2}{m} \left[E - V(r) - \frac{l^2}{2mr^2} \right]}$$

$$dt = \frac{dr}{\sqrt{\frac{2}{m} \left[E - V(r) - \frac{l^2}{2mr^2} \right]}}$$

integrate

$$t = \int_{r'=r_0}^{r(t)} \frac{dr'}{\sqrt{\frac{2}{m} \left[E - V(r') - \frac{l^2}{2mr'^2} \right]}}$$

For a given $V(r)$, this gives $t(r)$. Invert to get $r(t)$.

How do we get $\theta(t)$

$$l = m r^2 \dot{\theta} \Rightarrow \dot{\theta} = \frac{d\theta}{dt} = \frac{l}{m r^2}$$

$$d\theta = \frac{l dt}{m r^2(t)}$$

integrate

$$\theta(t) = \int_{t'=0}^t \frac{l dt'}{m [r(t')]^2} + \theta_0$$

We have two second-order differential equations \Rightarrow need 4 initial conditions to fix $r(t)$ and $\theta(t)$.

Could have chosen: $r_0, \theta_0, \dot{r}_0, \dot{\theta}_0$.

Instead we have: r_0, θ_0, E, ℓ .

Particle speed

$$E = T + V = \frac{1}{2} m v^2 + V(r)$$

$$v = \sqrt{\frac{2}{m} [E - V(r)]}$$



$$\dot{r} = v_r = \sqrt{\frac{2}{m} \left[E - V(r) - \frac{\ell^2}{2mr^2} \right]}$$

$E - V_{\text{eff}}$

$$v_\theta = r\dot{\theta} = \sqrt{v^2 - v_r^2} = \sqrt{\frac{2\ell^2}{m \cdot 2mr^2}} = \frac{\ell}{mr}$$

Inverse square force law $\vec{f} = -\frac{k}{r^2} \hat{r}$

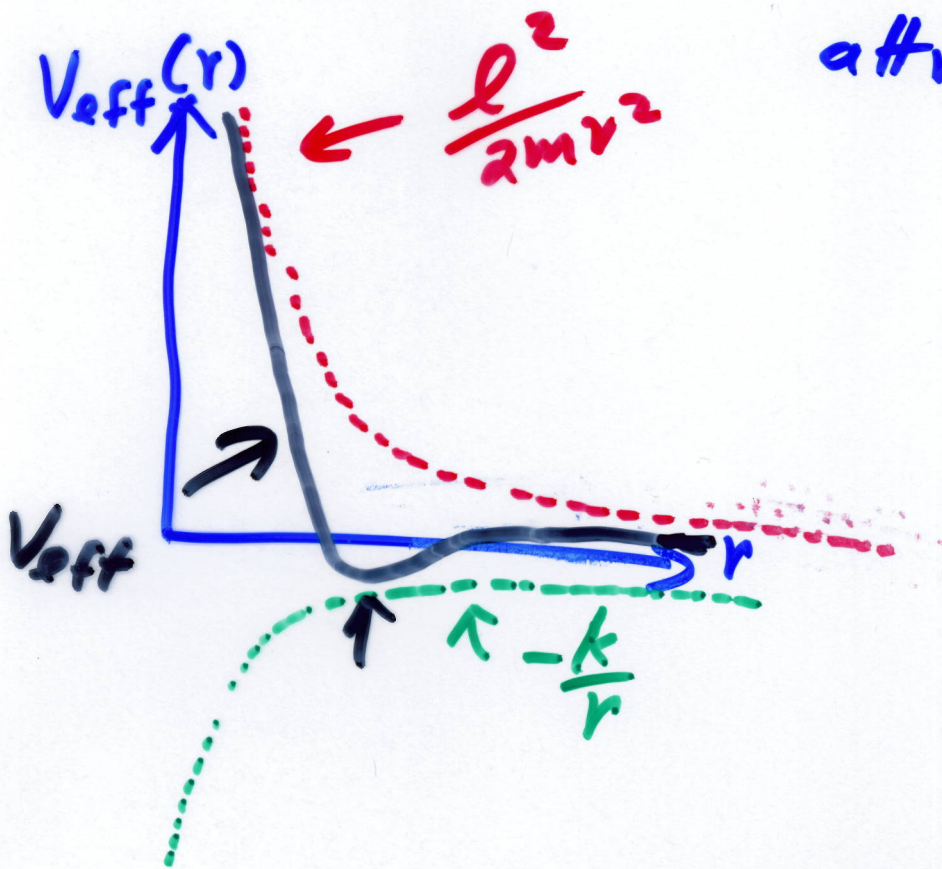
$k > 0$ is attractive, like gravity.

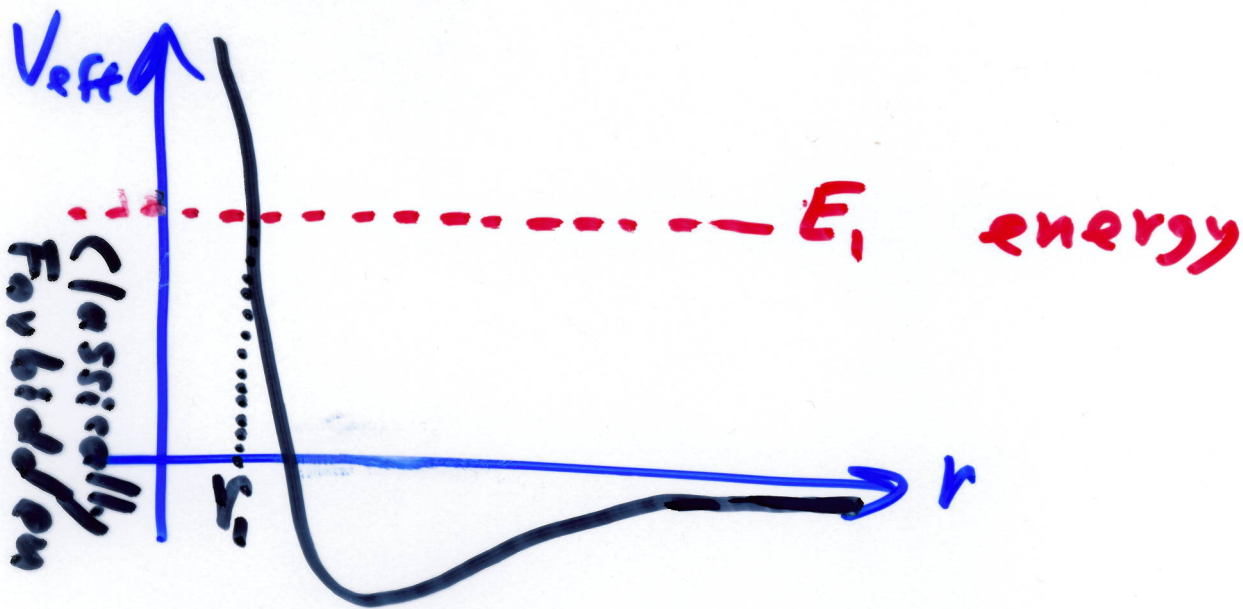
$$V(r) = -\frac{k}{r}$$

Effective potential $V_{\text{eff}} = -\frac{k}{r} + \frac{l^2}{2mr^2}$

attractive

repulsive





If $E < V_{\text{eff}}$ then $\dot{r} = U_r$ is imaginary.

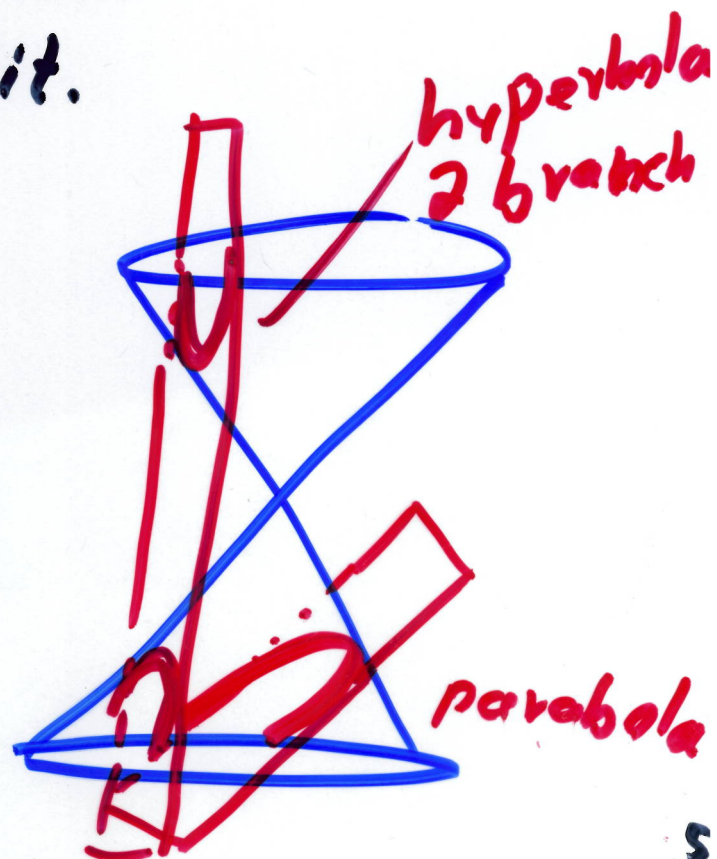
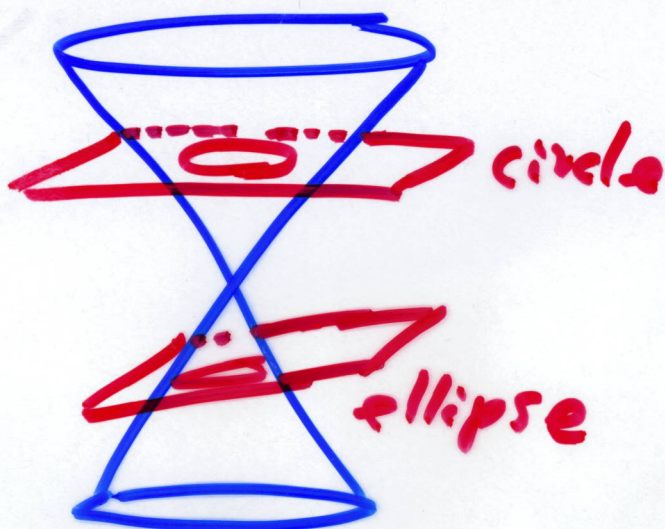
r_1 is a turning point - distance of closest approach. For this E_1 ,

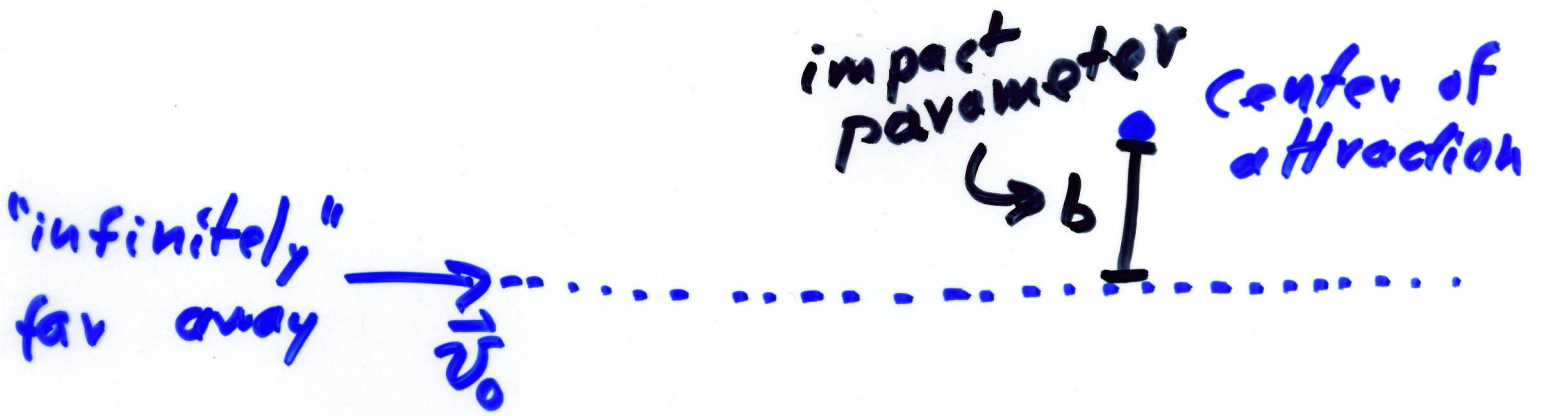
there is no upper limit to r

\Rightarrow motion is unbound.

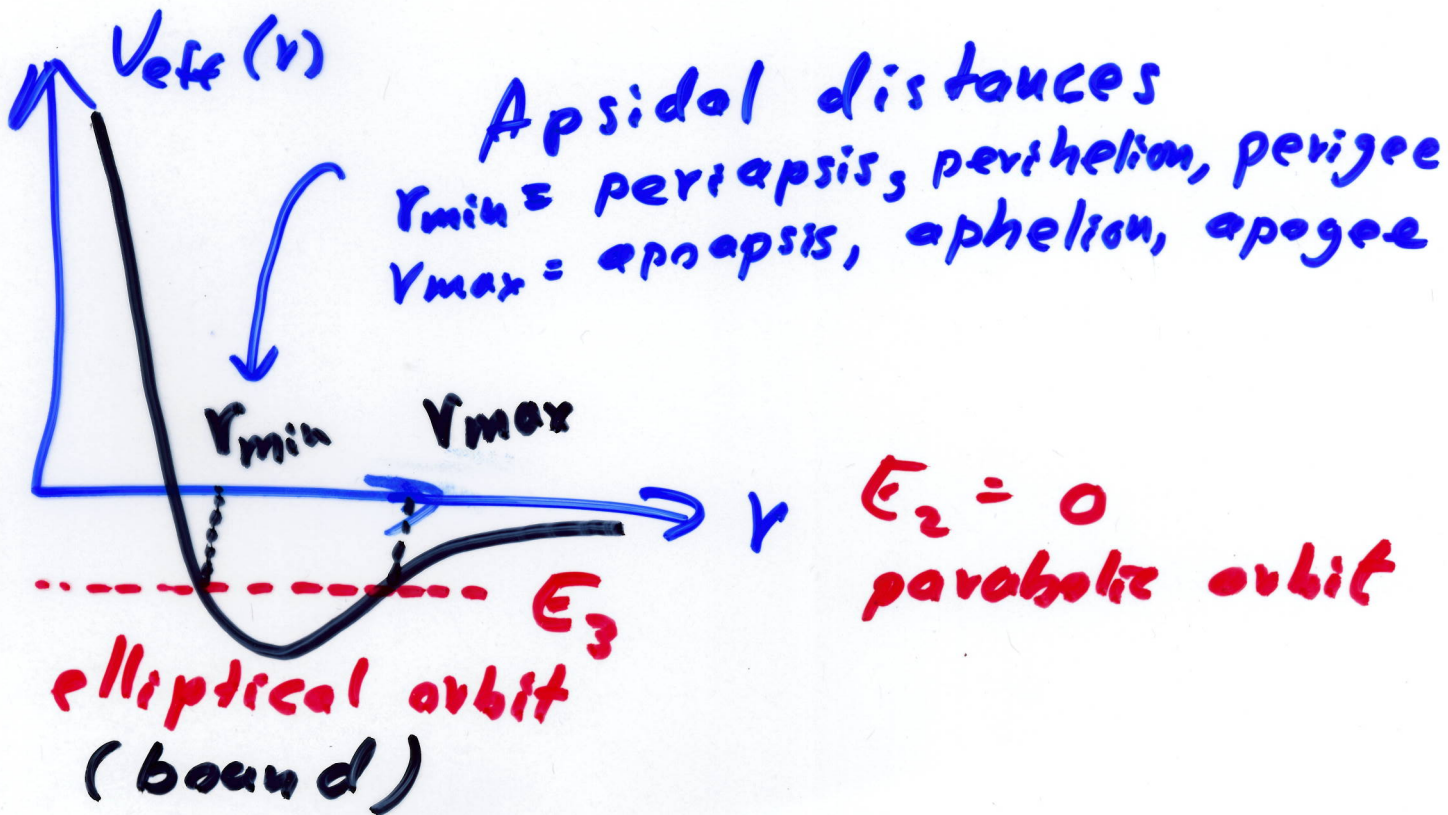
\Rightarrow hyperbolic orbit.

Conic Sections

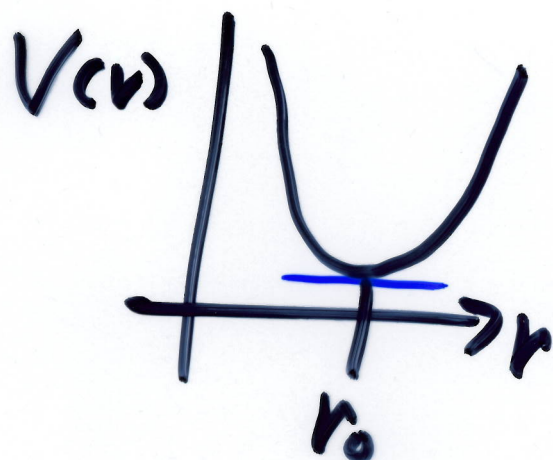




b is the lever arm for angular momentum. $\ell = m\vec{v}_0 b$



Any stable potential looks parabolic close to the minimum r value.



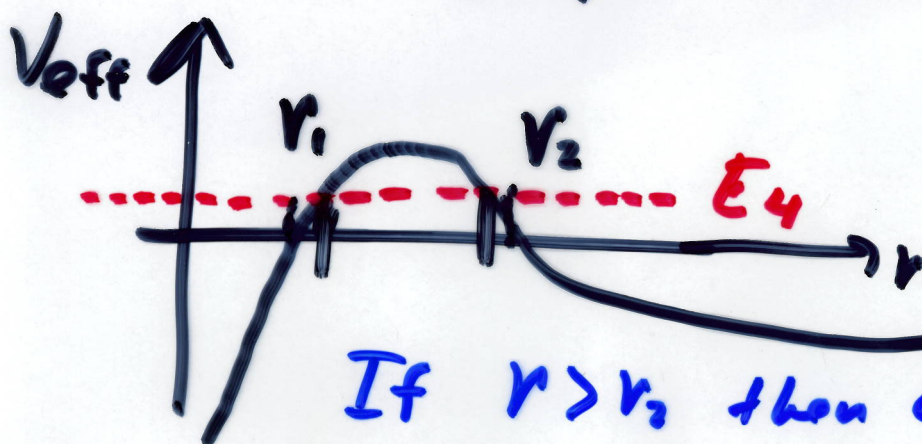
Taylor Expansion

$$V(r) = V(r_0) + \frac{dV}{dr} \Big|_{r_0} (r-r_0) + \frac{1}{2!} \frac{d^2V}{dr^2} \Big|_{r_0} (r-r_0)^2 + \dots$$

(choose zero $r=r_0$)

If $V(r) \cdot r^2 \rightarrow -\infty$ as $r \rightarrow 0$

V_{eff} is not dominated by the repulsive $\frac{d^2}{2mr^2}$ piece as $r \rightarrow 0$



If $r < r_1$, then bound motion - particle will pass through the force center.

If $r > r_2$ then unbound motion