

$$\Delta P \Delta X \geq \frac{\hbar}{2} ; \quad \Delta \hat{A} \Delta \hat{B} \geq \frac{1}{2} | \langle [\hat{A}, \hat{B}] \rangle |$$

From this relation one can obtain an "uncertainty-like" relation for energy and time.

From Relativistic Mechanics: $\vec{p} = \gamma m \vec{v}$ $\gamma = \frac{1}{\sqrt{1-v^2/c^2}}$
 $E = \gamma m c^2$

$$E^2 = p^2 c^2 + m^2 c^4 ; \quad c p / E = v / c \Rightarrow \frac{E}{c p} = \frac{c}{v}$$

$$2 E dE = 2 p d p c^2$$

$$\Rightarrow d p = E / p c^2 dE \Rightarrow \Delta p = E / p c^2 \Delta E$$

$$= \frac{1}{v} \Delta E = \frac{\Delta t}{\Delta x} \Delta E$$

$$\Delta p \Delta x = \Delta t \Delta E$$

$$\Delta E \Delta t \geq \hbar / 2$$

$$\Delta t \neq \langle t^2 \rangle - \langle t \rangle^2$$

Recall,

$$\frac{d \langle \hat{Q} \rangle}{dt} = \frac{i}{\hbar} \langle [\hat{H}, \hat{Q}] \rangle$$

assuming $\frac{\partial \hat{Q}}{\partial t} = 0$
 $[\hat{H}, \hat{Q}] \neq 0$

$$\text{but } \frac{1}{2} | \langle [\hat{H}, \hat{Q}] \rangle | \leq \Delta \hat{H} \Delta \hat{Q}$$

$$\Delta \hat{H} \Delta \hat{Q} \geq \frac{\hbar}{2} \left| \frac{d \langle \hat{Q} \rangle}{dt} \right|$$

Defn $\Delta t \equiv \frac{\Delta \hat{Q}}{\left| \frac{d \langle \hat{Q} \rangle}{dt} \right|}$

$$\Delta \hat{H} \Delta t \geq \frac{\hbar}{2}$$

$$\Delta E \Delta t \geq \hbar / 2$$

$\Delta t =$ time that it takes for expectation value of \hat{Q}

to change by one std deviation.

If any observable of the system changes rapidly $\Rightarrow \Delta E$ must be large.

Unstable Particle: In the particles rest frame $\Delta E \sim MC^2$

$$\Delta E \Delta t \gtrsim \hbar/2$$

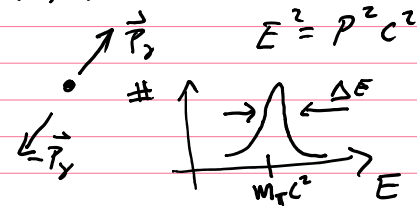
$$\Delta E \Delta t \sim \frac{\hbar}{2}$$

$$MC^2 \Delta t \sim \hbar/2$$

$$\tau \sim \frac{\hbar}{2MC^2}$$

$\Delta t \sim \tau$ "lifetime"

$$\pi^0 \rightarrow \gamma\gamma$$



Stationary States: Eigenstates of \hat{H}

$$\hat{H} \psi(x) = E \psi(x)$$

$$\Psi(\vec{x}, t) = e^{-i/\hbar \hat{H} t} \Psi(\vec{x}, 0)$$

If $\Psi(\vec{x}, 0)$ is an eigenfunction of \hat{H} , then,

$$\Psi(\vec{x}, t) = e^{-i/\hbar E t} \Psi(\vec{x}, 0) = e^{-i/\hbar E_n t} \psi_n(\vec{x})$$

In contrast a wave function which is not an eigenfunction of \hat{H} can always be expanded as a linear superposition of eigenfunctions of \hat{H} , i.e.

$$\Psi(\vec{x}, 0) = \sum_n c_n \psi_n(\vec{x}) \quad \text{where} \quad \hat{H} \psi_n(\vec{x}) = E_n \psi_n(\vec{x})$$

\hookrightarrow "Superposed State"

The time evolution of a superposed state is a bit more complicated,

$$\Psi(\vec{x}, t) = e^{-i/\hbar \hat{H} t} \Psi(\vec{x}, 0)$$

$$= \sum_n c_n e^{-i/\hbar E_n t} \psi_n(\vec{x})$$

$$\langle \psi_n(\vec{x}) | \hat{A} | \psi_m(\vec{x}) \rangle$$

$$\langle A \rangle_{\text{super}} = \sum_{n'} c_{n'} \langle A \rangle_{n'}$$

$$\begin{aligned} \langle \hat{A} \rangle_{\text{stationary}} &= e^{i\frac{E_n}{\hbar}t} e^{-i\frac{E_n}{\hbar}t} \langle \psi_n(\vec{x}) | \hat{A} | \psi_n(\vec{x}) \rangle \\ &= \langle \psi_n(\vec{x}) | \hat{A} | \psi_n(\vec{x}) \rangle \quad \text{"No time dependence"} \end{aligned}$$

$$\frac{d\langle \hat{A} \rangle}{dt} = \frac{i}{\hbar} \langle [\hat{H}, \hat{A}] \rangle$$

For an stationary state:

$$\begin{aligned} &= \frac{i}{\hbar} \int d^3x \psi_n^*(\vec{x}) [\hat{H}\hat{A} - \hat{A}\hat{H}] \psi_n(\vec{x}) \\ &= \frac{i}{\hbar} \left[\int d^3x (\hat{A}\psi_n(\vec{x}))^* \hat{A} \psi_n(\vec{x}) - \int d^3x \psi_n^*(\vec{x}) \hat{A} \hat{H} \psi_n(\vec{x}) \right] \\ &= \frac{i}{\hbar} \left[E_n \int d^3x \psi_n^*(\vec{x}) \hat{A} \psi_n(\vec{x}) - E_n \int d^3x \psi_n^*(\vec{x}) \hat{A} \psi_n(\vec{x}) \right] \\ &= 0 \end{aligned}$$

for stationary states $\frac{d\langle \hat{Q} \rangle}{dt} = 0 \Rightarrow \Delta t \rightarrow 0$

\Rightarrow we can have $\Delta E = 0$

$$(\Delta E)^2 = \langle H^2 \rangle - \langle H \rangle^2 = \begin{cases} E^2 - E^2 = 0 & \text{for stationary states} \end{cases}$$

But $\frac{d\langle \hat{Q} \rangle}{dt} = 0$ also when $[\hat{H}, \hat{Q}] = 0$

so again $\Delta E = 0$ is allowed.

$$\langle \hat{Q} \rangle = \int \Psi^*(\vec{x}, t) \hat{Q} \Psi(\vec{x}, t) d^3x$$

$$\Psi(\vec{x}, t) = \sum_{n, g} c_{ng} e^{-i\frac{E_n}{\hbar}t} \psi_{ng}(\vec{x})$$

$$\begin{aligned} \hat{Q} \psi_{ng} &= q \psi_{ng} \\ \hat{H} \psi_{ng} &= E_n \psi_{ng} \end{aligned}$$

$$\langle \hat{K} \rangle = \langle \hat{p}^2 \rangle = \langle \hat{p} \rangle^2$$

$$(\Delta E)^2 = \langle \hat{H}^2 \rangle - \langle \hat{H} \rangle^2$$

$$\stackrel{?}{=} 0$$

$$\langle \hat{H}^2 \rangle = \int \Psi^*(\vec{x}, t) \hat{H}^2 \Psi(\vec{x}, t) d^3x$$

$$\langle \hat{H} \rangle = \int \Psi^*(\vec{x}, t) \hat{H} \Psi(\vec{x}, t) d^3x$$

Example : $\frac{d\langle \hat{Q} \rangle}{dt} = 0$ for stationary state
 $\neq \Delta E = 0$

Consider a two state system

$$\Psi(\vec{x}, t) = \frac{e^{-i/\hbar E_1 t} \psi_1(\vec{x}) + e^{-i/\hbar E_2 t} \psi_2(\vec{x})}{\sqrt{2}}$$

$$\hat{H} \psi_i(\vec{x}) = E_i \psi_i(\vec{x})$$

$$i=1, 2$$

$$\frac{d\langle \hat{Q} \rangle}{dt} = \int \Psi^*(\vec{x}, t) \hat{Q} \Psi(\vec{x}, t) d^3x$$

$$\frac{d\langle \hat{Q} \rangle}{dt} = (E_1 + E_2) \hat{Q}_{12} \cos \omega_{21} t$$

$$\hat{Q}_{12} \equiv \int \psi_1^*(\vec{x}) \hat{Q} \psi_2(\vec{x}) d^3x$$

$$\omega_{21} = \frac{E_2 - E_1}{\hbar} ; \text{Assumed } \hat{Q}_{12}^* = \hat{Q}_{12}$$

\therefore Here $\Delta t \sim$ Period of oscillation

$$\Delta t \sim T = \frac{2\pi}{|\omega_{21}|} = \frac{2\pi}{|E_2 - E_1|} \hbar = \frac{\pi \hbar}{\Delta E}$$

$$\Delta E = \frac{|E_2 - E_1|}{2}$$

$$\Delta E \Delta t \sim \pi \hbar > \hbar/2$$

$$\Delta E = \frac{|E_1 - E_2|}{2} *$$