

TRANSLATIONS $\hat{U}(\vec{a}) = \exp\{-i \hat{\vec{p}} \cdot \vec{a}\}$

* WHERE $\hat{U}$ IS A GROUP ELEMENT

$$\hat{U}(\vec{a}) \hat{U}(\vec{b}) = \hat{U}(\vec{b}) \hat{U}(\vec{a}) = \hat{U}(\vec{a} + \vec{b}) \Rightarrow \text{GROUP ELEMENTS COMMUTE}$$

$$[\hat{p}_i, \hat{p}_j] = 0 \Rightarrow \text{ABELIAN LIE ALGEBRA } \mathfrak{3A}_1$$

DEFINITION: ABELIAN GROUPS, OR COMMUTATIVE GROUPS ARE GROUPS WHERE THE RESULT OF APPLYING A GROUP OPERATION TO TWO ELEMENTS DO NOT DEPEND ON THE ORDER IN WHICH THEY ARE WRITTEN. THIS WILL BE HELPFUL LATER FOR UNDERSTANDING GAUGE THEORIES.

ROTATIONS $\hat{U}(\vec{\theta}) = \exp\{-i \hat{\vec{J}} \cdot \vec{\theta}\}$

$$\hat{U}(\vec{\theta}_1) \hat{U}(\vec{\theta}_2) \neq \hat{U}(\vec{\theta}_2) \hat{U}(\vec{\theta}_1) \Rightarrow [\hat{J}_i, \hat{J}_j] = i \sum_{k=1}^3 \epsilon_{ijk} \hat{J}_k$$

LIE ALGEBRAS HAVE THE FOLLOWING GENERATOR:

$$[\hat{T}_a, \hat{T}_b] = \sum_c f_{abc} \hat{T}_c = \hat{T}_a \hat{T}_b - \hat{T}_b \hat{T}_a$$

* f_{abc} ARE STRUCTURE
CONSTANTS

STRUCTURE CONSTANTS f_{abc}

$SU(2)$ WILL PROVIDE A SIMPLE EXAMPLE OF WHAT STRUCTURE FUNCTIONS ARE, WE KNOW THE FOLLOWING RELATIONSHIP WITH THE PAULI MATRICES (σ_i):

$$[\sigma_a, \sigma_b] = 2i \epsilon^{abc} \sigma_c \Rightarrow f^{abc} = 2i \epsilon^{abc}$$

A LIE GROUP IS COMPACT IF THE PARAMETERS ARE BOUNDED. THEREFORE f_{abc} IS TOTALLY ANTI-SYMMETRIC. $SO(2)$ IS A COMPACT GROUP, WHEREAS THE LORENTZ GROUP $SO(3,1)$ IS NOT COMPACT.

DEFINITION: COMPACT GROUPS ARE A TOPOLOGICAL GROUP WHERE THE UNDERLYING TOPOLOGICAL SPACE IS ITSELF COMPACT SPACE. THE GROUP'S TOPOLOGY SATISFIES THE CONDITION THAT EVERY OPEN COVER OF THE GROUP HAS A FINITE SUBCOVER.

EXAMPLE) BOOSTS IN THE LORENTZ GROUP BY ϕ RAPIDITY ALONG THE X-AXIS

$$\Lambda = \begin{bmatrix} \cosh \phi & \sinh \phi & 0 & 0 \\ \sinh \phi & \cosh \phi & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\hat{U}(\vec{\phi}) = \exp\{\pm i \vec{k} \cdot \vec{\phi}\} \Rightarrow \hat{U}(\phi \hat{x}) = \exp\{\pm i \hat{k}_x \phi\}$$

$$\hat{k}_1 = \hat{k}_x = -i \left. \frac{\partial \hat{U}(\phi)}{\partial \phi} \right|_{\phi=0}$$

$$\hat{k}_1 = -i \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\hat{J}_1 = i \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & +1 & 0 \end{bmatrix}$$

$$\hat{k}_2 = -i \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\hat{J}_2 = i \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & +1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix}$$

$$\hat{k}_3 = -i \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\hat{J}_3 = i \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & +1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

FOR THE $\mathfrak{SO}(3,1)$ LIE ALGEBRAS HAVE THE FOLLOWING COMMUTATION RELATIONS

$$\left. \begin{aligned} [\hat{J}_i, \hat{J}_j] &= i \epsilon_{ijk} \hat{J}_k \\ [\hat{K}_i, \hat{K}_j] &= -i \epsilon_{ijk} \hat{L}_k \\ [\hat{J}_i, \hat{K}_j] &= i \epsilon_{ijk} \hat{K}_k \end{aligned} \right\} \quad \hat{U}(\Lambda^\mu{}_\nu) = \exp \left\{ -i (\hat{\vec{J}} \cdot \vec{\theta} - \hat{\vec{K}} \cdot \vec{\phi}) \right\}$$

AN ASIDE, A MATH TRICK TO THINK ABOUT LIE ALGEBRAS:

$$\text{DEFINE: } \tilde{A}_k = \frac{1}{2} (\hat{J}_k + i \hat{K}_k) \quad \hat{B}_k = \frac{1}{2} (\hat{J}_k - i \hat{K}_k)$$

$$\left. \begin{aligned} [\tilde{A}_i, \tilde{A}_j] &= i \epsilon_{ijk} \tilde{A}_k \\ [\hat{B}_i, \hat{B}_j] &= i \epsilon_{ijk} \hat{B}_k \\ [\tilde{A}_i, \hat{B}_j] &= 0 \end{aligned} \right\} \quad \mathfrak{SO}(3) \text{ OR } \mathfrak{SU}(2) \text{ ROTATION}$$

$$\mathfrak{SO}(3,1) \simeq \mathfrak{SU}(2) \oplus \mathfrak{SU}(2) \quad \text{HAVE THE SAME COMPLEXIFICATION } \mathfrak{SL}(2, \mathbb{C}) \oplus \mathfrak{SL}(2, \mathbb{C})$$

SCHRÖDINGER VERSUS HEISENBERG PICTURE

SCHRÖDINGER PICTURE IS TYPICALLY MORE USEFUL IN QUANTUM MECHANICS. WHEREAS THE HEISENBERG PICTURE IS FAR MORE USEFUL IN QFT.

$$|\psi(t)\rangle = \hat{U}(t, 0) |\psi(0)\rangle$$

$$\underline{|\psi_s(t)\rangle} = \hat{U}(t, 0) |\psi(0)\rangle = e^{-i\hat{H}t} |\psi(0)\rangle$$

* SCHRÖDINGER KET IS TIME DEPENDENT

EXPECTATION VALUE OF AN OPERATOR $\hat{O}$:

$$\langle \hat{O} \rangle_t = \langle \psi(t) | \hat{O} | \psi(t) \rangle = \langle \psi(0) | \hat{U}^\dagger(t, 0) \hat{O} \hat{U}(t, 0) | \psi(0) \rangle$$