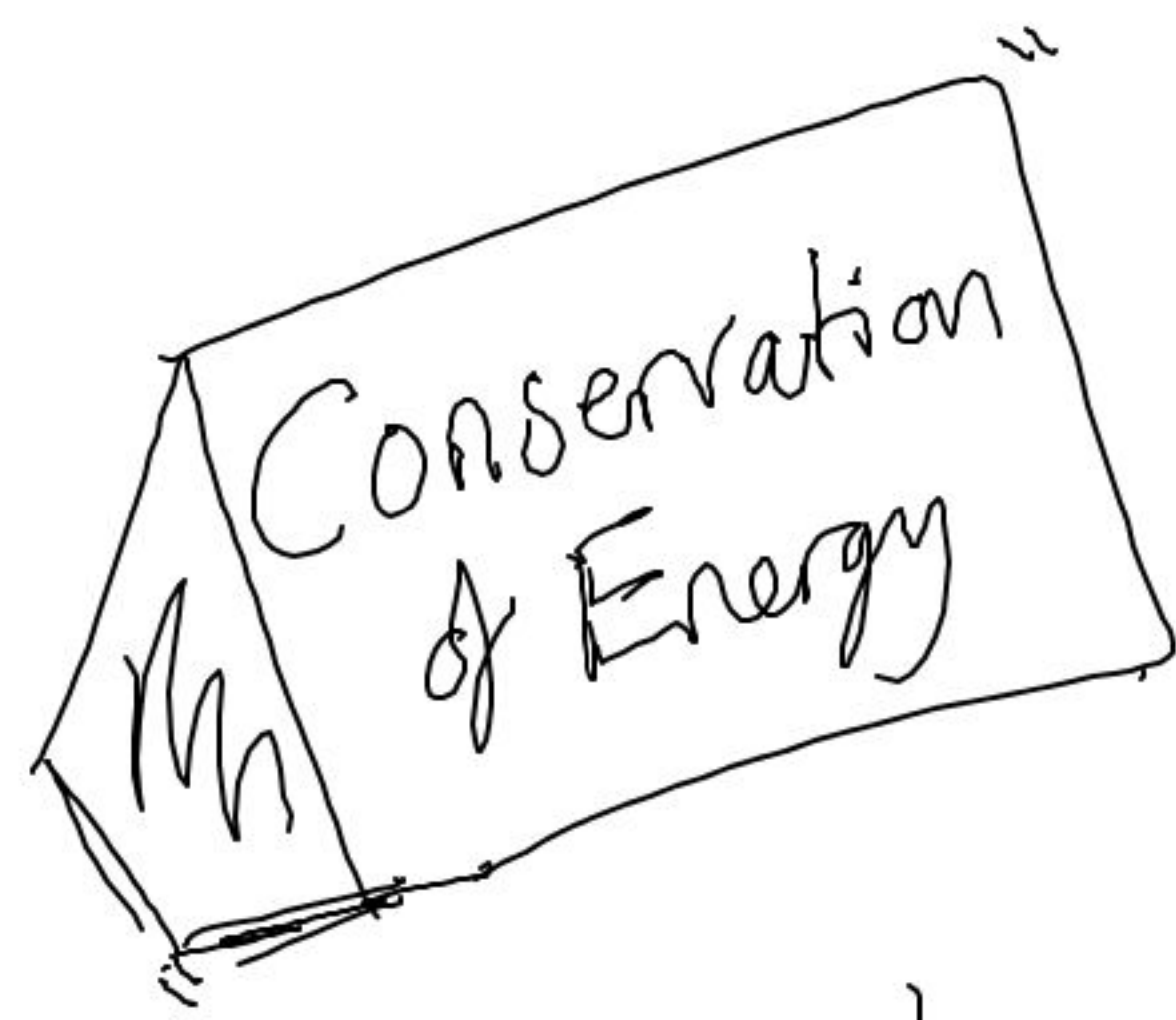




$$W_{\text{net}} \approx \underbrace{F}_{\text{net}} \Delta r = \Delta K = K_f - K_i$$
$$= F \Delta r \cos \phi$$

$$W_{\text{net}} = W_{\text{gravity}} + W_{\text{person}}$$

$$W_{\text{net}} = \cancel{W_{\text{non}}} + W_{\text{cons}} \Rightarrow \Delta K$$

$$- \sum_i \Delta U_i$$

all
consrv
forces

$$\sim \Delta U$$



$$0 = \Delta U + \Delta K$$

$$E = U + K$$

mechanical
energy

$\Rightarrow \Delta E = 0$
Conservation
law

$$\Delta E = 0$$

$$E_f = E_i$$

$$\frac{1}{2}mv_f^2 + mgy_f = \frac{1}{2}mv_i^2 + mgy_i$$

$$y_f - y_i$$

$$(y_f - y_i) = \frac{1}{2} \frac{(v_i^2 - v_f^2)}{g}$$

$$= \frac{v_i^2}{2g}$$

Potential Energy

$U(x)$

Conservative
forces
(path-independent W)

Note
 $U=0$ location
arbitrary

$\rightarrow W = -\Delta U$

definition

Ex/ Gravity
 $\uparrow +y$

W_{gravity}

$$= -mg \Delta y$$

$\Rightarrow$

$$U_g = mgy$$

Elastic

W_{elastic}

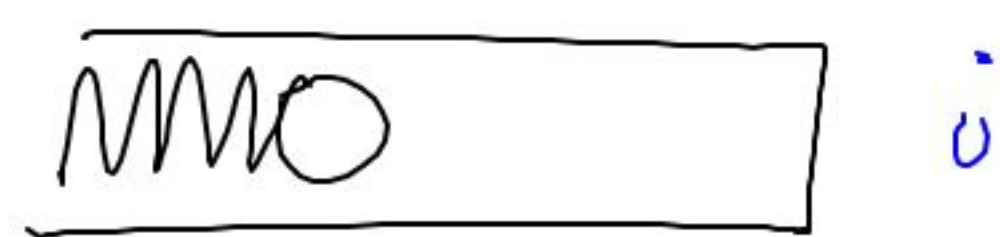
$$= \int_{x_1}^{x_2} -kx \, dx$$

$\Rightarrow$

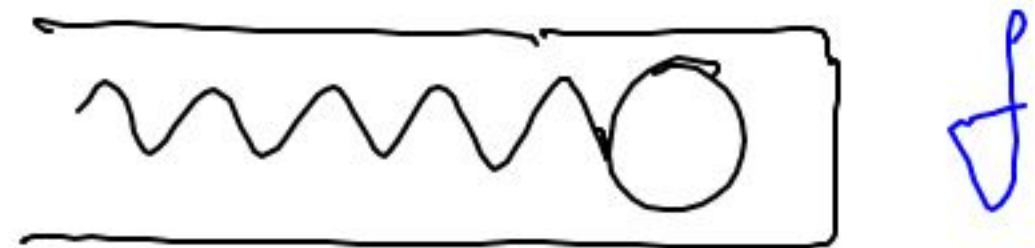
$$U_e = \frac{1}{2} kx^2$$

$x=0$ equilibrium

$$K = \frac{1}{2} mv^2$$



i



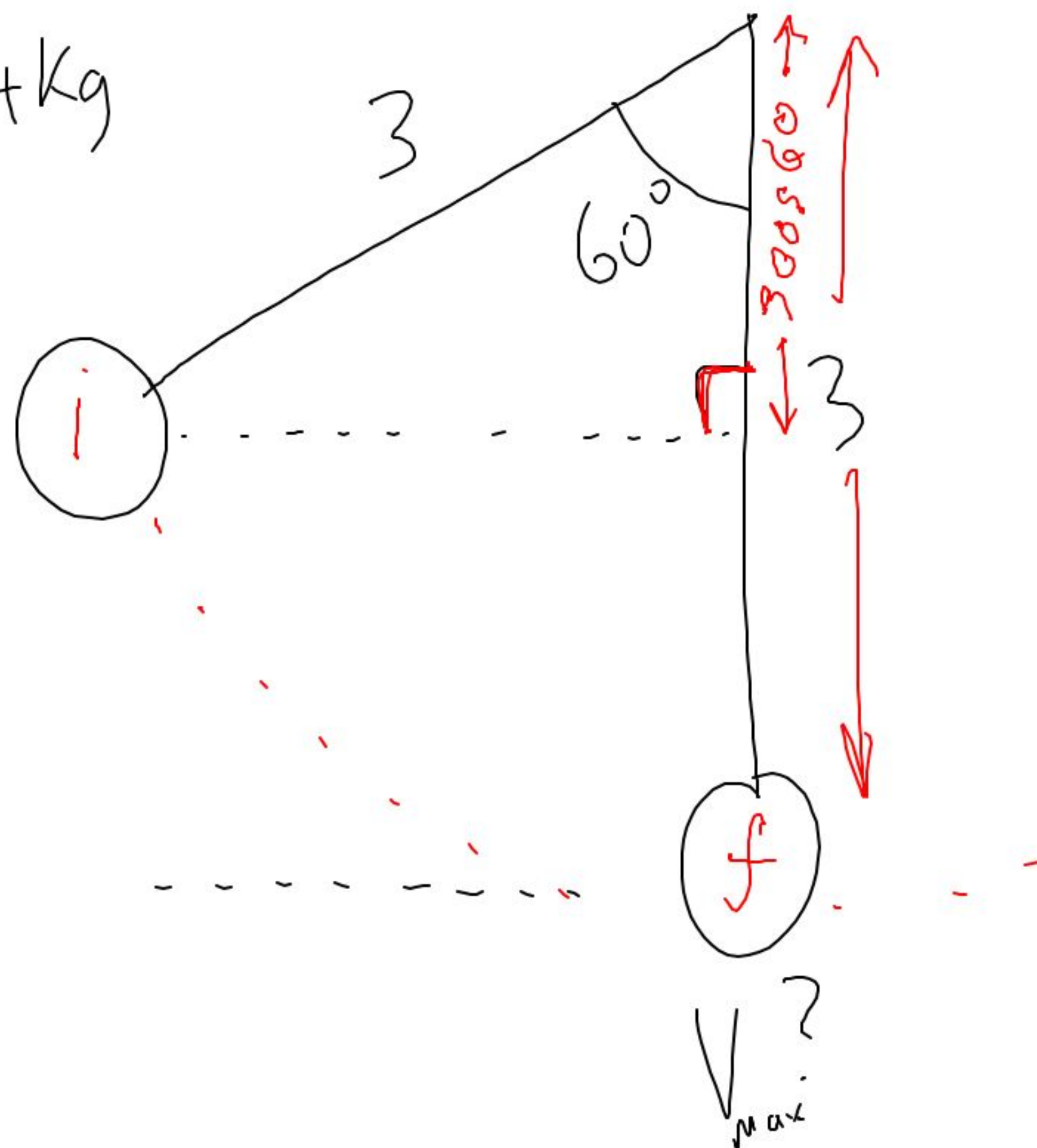
f

$$\frac{1}{2} m v_i^2 + \frac{1}{2} k x_i^2 + m g y_i = \frac{1}{2} m v_f^2 + \frac{1}{2} k x_f^2 + m g y_f$$

$$\frac{1}{2} k x_i^2 = \frac{1}{2} m v_f^2$$

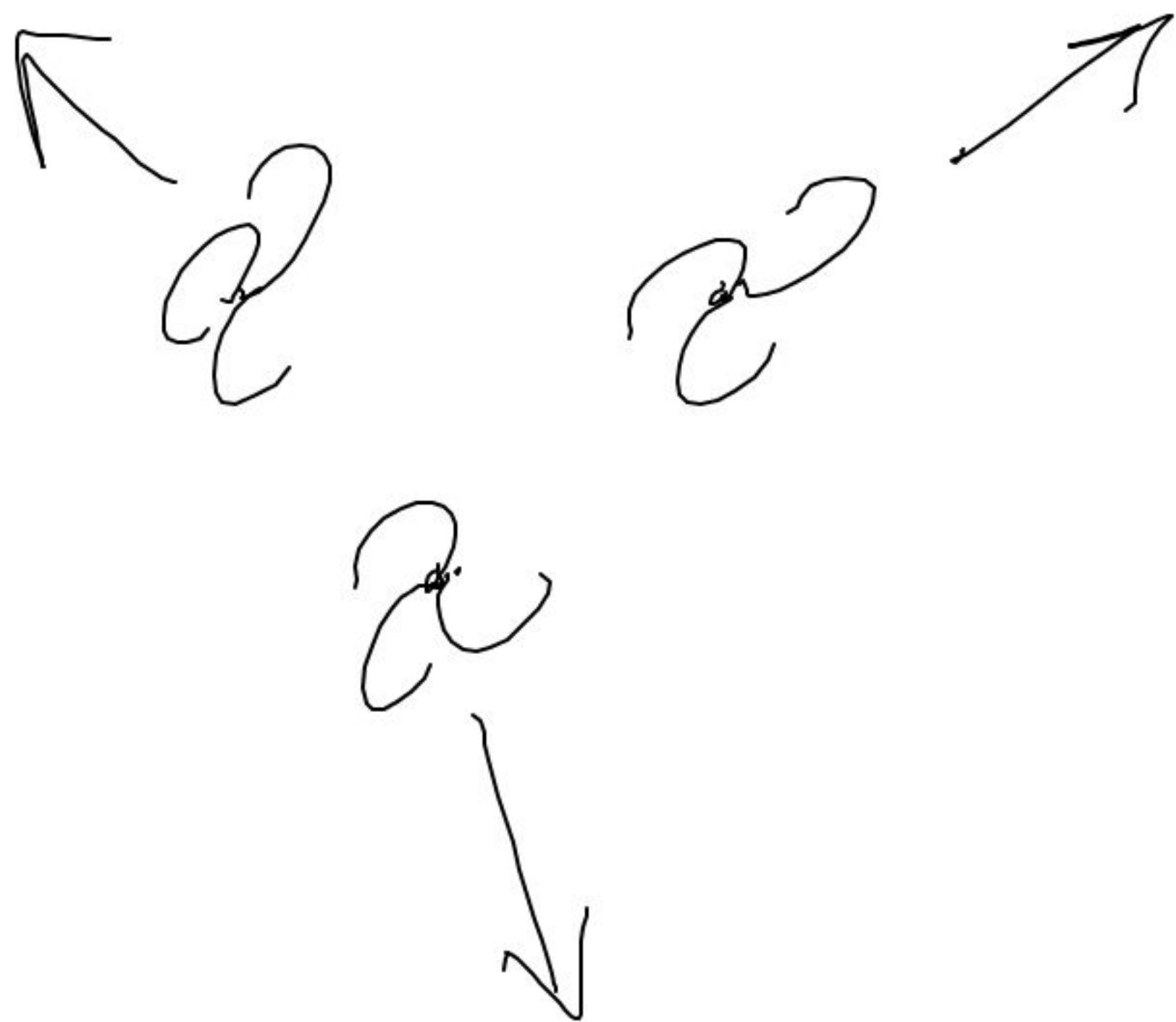


$$m = 0.4 \text{ kg}$$



$$E_i = E_f$$

$$\cos 60 = \frac{1}{2}$$



E

$=$



K

$+$



U_g

$+$?

Dark
Energy