

M 2-41

$$(a) T_{\text{GAIN}} (\text{wrt TRAIN}) = \frac{1}{2} m v^2$$

$$(b) T_{\text{GAIN}} (\text{wrt TRACK}) = T_f - T_i = \frac{1}{2} m (u+v)^2 - \frac{1}{2} m u^2 = \frac{1}{2} m v^2 + m u v$$

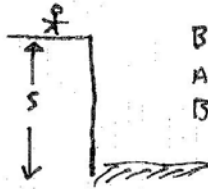
$$(c) W (\text{BY WOMAN}) = \frac{1}{2} m v^2$$

DOESN'T MATTER IF TRAIN IS MOVING OR STILL.

$$(d) W (\text{BY TRAIN}) = T_{\text{GAIN}} (\text{wrt TRACK}) - W (\text{WOMAN}) \\ = m u v$$

NOTE THAT TRAIN MUST DO WORK TO STAY MOVING AT SPEED  $u$ . IF IT DIDN'T DO WORK, CONS. OF MOMENTUM WOULD CAUSE IT TO SLOW DOWN WHEN THE WOMAN THREW THE BALL FORWARD.

M 2-30



BALLOON FALLS A DISTANCE  $S$  THEN A SOUND WAVE MUST TRAVEL BACK UP THE BLDG.

LET  $S \equiv$  BLDG HEIGHT

$t \equiv$  elapsed time = 4.021 sec

$t =$  DROP TIME + SOUND TRAVEL TIME

$$= \sqrt{\frac{2S}{g}} + \frac{S}{v_0} \quad ; \quad v_0 = \text{sound speed.}$$

$g = \text{accel. DUE TO GRAVITY}$

SOLVE FOR  $S$ . LET  $S = z^2$ , THEN WE HAVE QUADRATIC EQN.

$$t = \sqrt{\frac{2}{g}} z + z^2/v_0$$

$$z^2 + \sqrt{\frac{2v_0^2}{g}} z - v_0 t = 0$$

$$\Rightarrow z = \frac{-\sqrt{\frac{2v_0^2}{g}} \pm \left[ \frac{2v_0^2}{g} + 4v_0 t \right]^{1/2}}{2}$$

CHOOSE + SIGN SINCE  $z$  MUST BE  $> 0$ .

So,

$$S = z^2 = \frac{1}{4} \left[ \frac{2v_0^2}{g} + \frac{2v_0^2}{g} + 4v_0 t - 2\sqrt{\frac{2v_0^2}{g}} \left[ \frac{2v_0^2}{g} + 4v_0 t \right]^{1/2} \right]$$

$$= \frac{1}{4} \left[ 4v_0^2/g + 4v_0 t - \frac{4v_0^2}{g} \left[ 1 + \frac{2gt}{v_0} \right]^{1/2} \right]$$

$$\therefore S = \left[ v_0^2/g + v_0 t - \frac{v_0^2}{g} \left[ 1 + \frac{2gt}{v_0} \right]^{1/2} \right]$$

SUBSTITUTING  $t = 4.021$  s,  $g = 9.8 \text{ m/s}^2$ ,  $v_0 = 331 \text{ m/s}$

$$\boxed{S = 71 \text{ M}}$$

M 2-38

(a)  $v(x) = dx^{-n}$

$$F = m \frac{dv}{dt} = m \frac{dv}{dx} \frac{dx}{dt} = m v \frac{dv}{dx}$$

BUT  $v(x) = dx^{-n}$  &  $dv/dx = -2n x^{-(n+1)}$ , so

$$F = m v \frac{dv}{dx} = m dx^{-n} (-2n x^{-(n+1)})$$

$$F(x) = -m n d^2 x^{-(2n+1)}$$

(b)

$$\dot{x} = v = dx^{-n}$$

$$\int x^n dx = \int dt$$

$$\frac{x^{n+1}}{n+1} = dt + C_0^0, \text{ since } x=0 \text{ @ } t=0$$

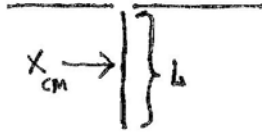
$$\Rightarrow x = [(n+1)dt]^{1/(n+1)}$$

(c)  $F(t) = F(x(t))$ . BY DIRECT SUBSTITUTION,

$$F(t) = -m n d^2 [(n+1)dt]^{-\frac{2n+1}{n+1}}$$

M9-15

$E_i = T_i + U_i = 0$ , ROPE AT REST & DEFINE  
TABLE TOP TO BE  $U=0$ .



$$\begin{aligned} E_F &= T_F + U_F \\ &= \frac{1}{2} M V_F^2 - \frac{Mgl}{2} \\ &= \frac{1}{2} M \left( \frac{2}{3} gl \right) - \frac{Mgl}{2} \\ &= -\frac{1}{6} Mgl \end{aligned}$$

$$\text{ENERGY LOST} = -(E_F - E_i) = \frac{1}{6} Mgl$$

M 9-7

BY INSPECTION, H ATOMS ARE SYMMETRICALLY  
PLACED ON EITHER SIDE OF +X AXIS &  
O ATOM IS AT ORIGIN. HENCE  $\bar{y} = 0$ .

FOR  $\bar{x}$ ,

$$\bar{x} = \frac{\sum M_i X_i}{\sum M_i}$$

$$= \frac{2a \cos 52^\circ}{1+1+16}$$

$$\frac{m_o}{m_H} = 16$$

$$\boxed{\begin{array}{l} \bar{x} = 0.068 a \\ \bar{y} = 0 \end{array}}$$

M 9-15 MULTIPLE SOLUTIONS POSSIBLE.



I SOLVED IT BY ASKING HOW DOES THE <sup>ROPE</sup> CM MOVE. LET  $x=0$  BE THE TABLE TOP. THEN

$$\bar{x}_{cm} = \frac{m(\text{ROPE ON TABLE}) \cdot 0 + m(\text{ROPE HANGING}) \cdot \frac{x}{2}}{M_{\text{ROPE}}}$$

$$= \frac{\frac{\rho x^2}{2}}{M} \quad ; \quad \rho = M/L$$

$$\bar{x}_{cm} = \frac{x^2}{2L}$$

RECALL THAT FOR MULTI-PARTICLE SYSTEMS,

$$M \ddot{R} = F_{\text{NET}} \quad ; \quad M = \text{ROPE TOTAL MASS} \\ R = \text{rope cm}$$

$$M \frac{dV_{cm}}{dt} = F_N$$

$$M \frac{dV_{cm}}{dx_{cm}} \cdot \frac{dx_{cm}}{dt} = F_N$$

$$M \frac{dV_{cm}}{dx_{cm}} \cdot V_{cm} = F_N$$

BUT  $F_N =$  FORCE DUE TO HANGING ROPE

$$= \rho x g \\ = \rho g [2L x_{cm}]^{1/2}$$

M 9-15, CONT.

$$\text{SO, } M V_{cm} \frac{dV_{cm}}{dX_{cm}} = \rho g [2L X_{cm}]^{1/2}$$

$$\int V_{cm} dV_{cm} = \int \left[ \frac{2g^2}{L} X_{cm} \right]^{1/2} dX_{cm}$$

$$\frac{V_{cm}^2}{2} = \sqrt{\frac{2g^2}{L}} \frac{2}{3} X_{cm}^{3/2} + C_0, \quad V_{cm} = 0 @ X_{cm} = 0$$

$$V_{cm} = \left[ \frac{32}{9} \frac{g^2}{L} \right]^{1/4} X_{cm}^{3/4}$$

NOW, WE REALLY WANT  $v(x)$  NOT  $V_{cm}(X_{cm})$ .

BUT  $X_{cm} = \frac{x^2}{2L}$  SO WE CAN PROCEED.

$$\text{FROM ABOVE, } X_{cm} = \frac{x^2}{2L}$$

$$\Rightarrow V_{cm} = \frac{\dot{x}x}{L} = \left[ \frac{32}{9} \frac{g^2}{L} \right]^{1/4} \left( \frac{x^2}{2L} \right)^{3/4}$$

$$\dot{x} = v = \left[ \frac{2}{3} g x \right]^{1/2}$$

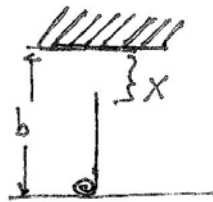
NOTE:  $v = \sqrt{2gx}$   
FOR FREE FALL.

FOR FREE FALL

$$v = \sqrt{2gx}$$

$$\Rightarrow a_{\text{rope}} = \frac{g}{3}$$

M 9-19



$$\vec{F}_{\text{CHAIN}} = \vec{F}_{\text{GRAVITY}} + \vec{F}_{\text{TABLE}}$$

$\vec{F}_{\text{CHAIN}} = \overset{\text{NET}}{\text{FORCE ON CHAIN}}$

$\vec{F}_{\text{GRAVITY}} = \text{GRAVITY FORCE ON CHAIN}$

$\vec{F}_{\text{TABLE}} = \text{FORCE OF TABLE ON CHAIN}$

$$F_c = \frac{dP_c}{dt} = \rho b g - F_T \quad ; \quad \rho = M/b$$

$P_c = \text{CHAIN MOMENTUM}$

$$P_c = m_c v_c \quad ; \quad m_c = \text{MASS OF MOVING CHAIN } \underline{\underline{\text{ONLY}}}$$

$$= \rho(b-x)\dot{x}$$

$$\Rightarrow F_c = \dot{P}_c = -\rho\dot{x}^2 + \rho(b-x)\ddot{x}$$

SINCE CHAIN IS IN FREE FALL,  $\dot{x}^2 = v^2 = 2gx$   
 $\ddot{x} = g$

So,

$$F_c = F_G - F_T$$

$$-\rho(2gx) + \rho(b-x)g = \rho b g - F_T$$

$$F_T = 3\rho g x$$

$$\therefore \boxed{F_T = 3mg \left(\frac{x}{b}\right)}$$