

M7.3



$$T = \frac{1}{2} m (R-r)^2 \dot{\theta}^2 + \frac{1}{2} I \dot{\phi}^2, \quad I = \frac{2}{5} m r^2 \text{ (SPHERE)}$$

$$= \frac{1}{2} m (R-r)^2 \dot{\theta}^2 + \frac{1}{5} m r^2 \dot{\phi}^2$$

$$U = mg(R-r)(1 - \cos\theta)$$

$$\boxed{f = R\theta - r\phi = 0} \quad \text{SPHERE ROLLS w/o SLIPPING.}$$

$$\boxed{L = \frac{1}{2} m (R-r)^2 \dot{\theta}^2 + \frac{1}{5} m r^2 \dot{\phi}^2 - mg(R-r)(1 - \cos\theta)}$$

$$\frac{\partial L}{\partial \theta} = -mg(R-r) \sin\theta$$

$$\frac{\partial L}{\partial \dot{\theta}} = m(R-r)^2 \dot{\theta}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = m(R-r)^2 \ddot{\theta}$$

$$\frac{\partial f}{\partial \theta} = R$$

$$\frac{\partial L}{\partial \phi} = 0$$

$$\frac{\partial L}{\partial \dot{\phi}} = \frac{2}{5} m r^2 \dot{\phi}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}} = \frac{2}{5} m r^2 \ddot{\phi}$$

$$\frac{\partial f}{\partial \phi} = -r$$

$$\Rightarrow \boxed{-mg(R-r) \sin\theta - m(R-r)^2 \ddot{\theta} + \lambda R = 0} \quad (1)$$

$$\Rightarrow \boxed{-\frac{2}{5} m r^2 \ddot{\phi} - \lambda r = 0}$$

$$\lambda = -\frac{2}{5} m r \ddot{\phi}$$

$$= -\frac{2}{5} m R \ddot{\theta} \quad (2)$$

$$(R\ddot{\theta} = r\ddot{\phi}).$$

M7.3 CONT

FROM EQN (1) ABOVE & USING (2)

$$-mg(R-\rho)\sin\theta - m(R-\rho)^2\ddot{\theta} - \frac{2}{5}mR^2\ddot{\phi} = 0$$

$$-(R-\rho)g\sin\theta - \left[(R-\rho)^2 + \frac{2}{5}R^2\right]\ddot{\theta} = 0 \quad (3)$$

FOR SMALL OSCILLATIONS, $\sin\theta \approx \theta$, SO (3) BECOMES

$$+(R-\rho)g\theta + \left[(R-\rho)^2 + \frac{2}{5}R^2\right]\ddot{\theta} = 0$$

NOTE ANALOGY W/ SHM OF MASS ON SPRING:

$$m\ddot{x} + kx = 0$$

$$\nu = \frac{1}{2\pi} \sqrt{k/m}$$

HENCE

$$\nu = \frac{1}{2\pi} \left[\frac{(R-\rho)g}{(R-\rho)^2 + \frac{2}{5}R^2} \right]^{1/2}$$

7.4.

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2)$$

$$F = -A r^{\alpha-1} = -\nabla U \Rightarrow U = \frac{A}{\alpha} r^{\alpha}$$

$$L = T - U = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{A}{\alpha} r^{\alpha}$$

$$\frac{\partial L}{\partial r} = -A r^{\alpha-1} + m r \dot{\theta}^2$$

$$\frac{\partial L}{\partial \dot{r}} = m \dot{r}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{r}} = m \ddot{r}$$

$$\Rightarrow \boxed{m \ddot{r} - m r \dot{\theta}^2 + A r^{\alpha-1} = 0} \quad (1)$$

$$\frac{\partial L}{\partial \theta} = 0$$

$$\frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta}$$

$$\Rightarrow \frac{d}{dt} (m r^2 \dot{\theta}) = 0 \quad (2)$$

But $l = m r^2 \dot{\theta} = \text{angular momentum}$
so $l = \text{const}$

$$\text{And, (2)} \Rightarrow \boxed{2 m r \dot{r} \dot{\theta} + m r^2 \ddot{\theta} = 0}$$

7.4.

Q: IS $E = \text{const}$?

BY ANALOGY W/ GRAVITATIONAL FORCE
W/ $F \propto 1/r^2$

A: YES

EXPLICITLY, REWRITE (1)

$$m \ddot{r} - \frac{l^2}{mr^3} + A r^{\alpha-1} = 0$$

$$m r \ddot{r} - \frac{\dot{r}^2 l^2}{mr^3} + A \dot{r} r^{\alpha-1} = 0$$

$$\frac{d}{dt} \left(\frac{m}{2} \dot{r}^2 \right) + \frac{d}{dt} \left(\frac{l^2}{2mr^2} \right) + \frac{d}{dt} (A r^\alpha) = 0$$

FROM OUR DISCUSSION OF CENTRAL FORCE
MOTION,

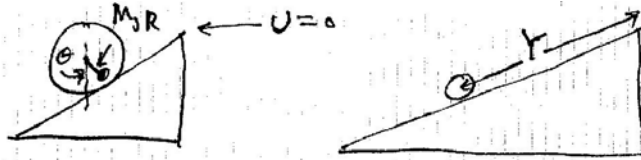
$$KE = \frac{m}{2} \dot{r}^2 + \frac{l^2}{2mr^2}$$

SO,

$$\frac{d}{dt} (KE) + \frac{d}{dt} (U) = 0$$

$$\Rightarrow \boxed{E_{\text{TOTAL}} = KE + U = \text{const.}}$$

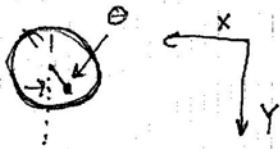
M 7.9



$T = \text{DISK} + \text{PENDULUM}$

$$= \frac{1}{2} M \dot{Y}^2 + \frac{1}{4} M \dot{Y}^2 + \text{PENDULUM}$$

PENDULUM:



$$x(\text{BOB}) = Y \cos \alpha - l \sin \theta$$

$$y(\text{BOB}) = Y \sin \alpha + l \cos \theta$$

$$\dot{x} = \dot{Y} \cos \alpha - l \dot{\theta} \cos \theta$$

$$\dot{y} = \dot{Y} \sin \alpha + l \dot{\theta} \sin \theta$$

$$\dot{x}^2 = \dot{Y}^2 \cos^2 \alpha + l^2 \dot{\theta}^2 \cos^2 \theta - 2 \dot{Y} l \dot{\theta} \cos \theta \cos \alpha$$

$$\dot{y}^2 = \dot{Y}^2 \sin^2 \alpha + l^2 \dot{\theta}^2 \sin^2 \theta + 2 \dot{Y} l \dot{\theta} \sin \theta \sin \alpha$$

$$\dot{x}^2 + \dot{y}^2 = \dot{Y}^2 + l^2 \dot{\theta}^2 - 2 \dot{Y} l \dot{\theta} (\sin \alpha \cos \theta + \cos \alpha \sin \theta)$$

$$T = \frac{1}{2} M \dot{Y}^2 + \frac{1}{4} M \dot{Y}^2 + \frac{1}{2} m \dot{Y}^2 + \frac{1}{2} m l^2 \dot{\theta}^2 - m Y l \dot{\theta} \sin(\alpha + \theta)$$

$$U = -M g Y \sin \alpha - m g l \cos \theta - m g Y \sin \alpha$$

$$\Delta = \frac{3}{4} M \dot{Y}^2 + \frac{1}{2} m \dot{Y}^2 + \frac{1}{2} m l^2 \dot{\theta}^2 - m Y l \dot{\theta} \sin(\alpha + \theta) + M g Y \sin \alpha + m g Y \sin \alpha + m g l \cos \theta$$

M 7.9

$$\frac{\partial L}{\partial \dot{Y}} = Mg \sin \alpha + mg \sin \alpha$$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{3}{2} M \dot{Y} + m \dot{Y} - m l \dot{\theta} \sin(\alpha + \theta)$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{Y}} = \frac{3}{2} M \ddot{Y} + m \ddot{Y} - m l \dot{\theta}^2 \cos(\alpha + \theta)$$

so $(M+m)g \sin \alpha = \left(\frac{3}{2}M+m\right)\ddot{Y} - m l \dot{\theta}^2 \cos(\alpha + \theta)$

$$g \sin \alpha = \left(\frac{\frac{3}{2}M+m}{M+m}\right)\ddot{Y} - \left(\frac{m}{M+m}\right)l \dot{\theta}^2 \cos(\alpha + \theta)$$

$$\frac{\partial L}{\partial \theta} = -m \dot{Y} l \dot{\theta} \cos(\alpha + \theta) - m g l \sin \theta$$

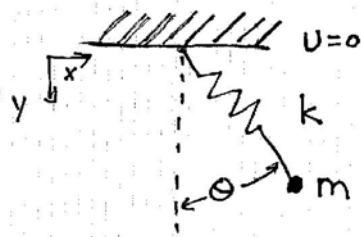
$$\frac{\partial L}{\partial \theta} = m l^2 \ddot{\theta} - m \dot{Y} l \sin(\alpha + \theta)$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = m l^2 \ddot{\theta} - m \dot{Y} l \sin(\alpha + \theta) - m \dot{Y} l \dot{\theta} \cos(\alpha + \theta)$$

so $-m \dot{Y} l \dot{\theta} \cos(\alpha + \theta) - m g l \sin \theta = m l^2 \ddot{\theta} - m \dot{Y} l \sin(\alpha + \theta) - m \dot{Y} l \dot{\theta} \cos(\alpha + \theta)$

$$-g \sin \theta = l \ddot{\theta} - \ddot{Y} \sin(\alpha + \theta)$$

7-15



$b = \text{UNSTRETCHED SPRING LENGTH}$

$l = \text{SPRING LENGTH}$

$$x = l \sin \theta \Rightarrow \dot{x} = \dot{l} \sin \theta + l \dot{\theta} \cos \theta$$

$$y = l \cos \theta \Rightarrow \dot{y} = \dot{l} \cos \theta - l \dot{\theta} \sin \theta$$

$$\dot{x}^2 = \dot{l}^2 \sin^2 \theta + l^2 \dot{\theta}^2 \cos^2 \theta + 2 \dot{l} l \dot{\theta} \sin \theta \cos \theta$$

$$\dot{y}^2 = \dot{l}^2 \cos^2 \theta + l^2 \dot{\theta}^2 \sin^2 \theta - 2 \dot{l} l \dot{\theta} \sin \theta \cos \theta$$

$$T = \frac{1}{2} m (\dot{l}^2 + l^2 \dot{\theta}^2)$$

$$U = \frac{1}{2} k (l-b)^2 - mg l \cos \theta$$

$$L = T - U = \frac{1}{2} m (\dot{l}^2 + l^2 \dot{\theta}^2) - \frac{1}{2} k (l-b)^2 + mg l \cos \theta$$

$$\frac{\partial L}{\partial l} = m \dot{\theta}^2 - k(l-b) + mg \cos \theta$$

$$\frac{\partial L}{\partial \dot{l}} = m \dot{l}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{l}} = m \ddot{l}$$

$$m \dot{\theta}^2 - k(l-b) + mg \cos \theta = m \ddot{l}$$

$$\ddot{l} - \dot{\theta}^2 + k(l-b) - g \cos \theta = 0$$

7.15 CONT

$$\frac{\partial L}{\partial \theta} = -mgl \sin \theta$$

$$\frac{\partial L}{\partial \dot{\theta}} = ml^2 \dot{\theta}$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = 2ml\dot{\theta} + ml^2 \ddot{\theta}$$

So, $-mgl \sin \theta = \cancel{2ml\dot{\theta}} + 2ml\dot{\theta} + ml^2 \ddot{\theta}$

$$\boxed{l\ddot{\theta} + 2\dot{\theta} + g \sin \theta = 0}$$