

#1.

$$(\hat{\sigma} \cdot \underline{A})(\hat{\sigma} \cdot \underline{B}) = \sigma_i A_i \sigma_j B_j$$

$$= A_i B_j \sigma_i \sigma_j$$

$$= A_i B_j [\delta_{ij} + i \epsilon_{ijk} \sigma_k]$$

$$\hat{\sigma} \cdot \underline{A} \hat{\sigma} \cdot \underline{B} = \underline{A} \cdot \underline{B} + i (\underline{A} \times \underline{B}) \cdot \hat{\sigma}$$

#2. TWO COMPONENT SPINOR, SPIN =  $\frac{1}{2} \hbar$

& NOTE THAT OPERATOR IS OF FORM

$\hat{S} \cdot \hat{n}$ , AS IN RECENT TEST.

ROTATE YOUR COORDINATE SYSTEM UNTIL

YOUR Z-AXIS IS ALIGNED W/  $\hat{n}$  DIRECTION.

THEN SINCE IN GENERAL

$|\langle \uparrow | \text{SPIN} \rangle|^2 = \text{PROBABILITY OF SPIN UP}$

$$|\langle 1 | \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \end{pmatrix} |^2 = 4/5$$

$|\langle \downarrow | \text{SPIN} \rangle|^2 = \text{PROB OF SPIN DOWN}$

$$|\langle 0 | \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \end{pmatrix} |^2 = 1/5$$

PROB OF MEASURING  $-\frac{\hbar}{2} = 20\%$

$$\#3. \left| \frac{1}{2} - \frac{1}{2} \right\rangle = \sqrt{\frac{1}{6}} \left| \frac{3}{2} \frac{1}{2} \right\rangle |1-1\rangle - \sqrt{\frac{1}{3}} \left| \frac{3}{2} - \frac{1}{2} \right\rangle |10\rangle + \sqrt{\frac{1}{2}} \left| \frac{3}{2} - \frac{3}{2} \right\rangle |11\rangle$$

#4(a). SUBSTITUTE THE  $\hat{S}_+$  OPERATOR FOR  $\hat{S}_z$  IN THE EXAMPLE IN THE PROBLEM.

NOTE  $S_+ |11\rangle = 0$   
 $S_+ |10\rangle = \sqrt{2} \hbar |11\rangle$   
 $S_+ |1-1\rangle = \sqrt{2} \hbar |10\rangle$

$$\Rightarrow \hat{S}_+ = \hbar \begin{pmatrix} 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{2} \\ 0 & 0 & 0 \end{pmatrix}$$

SIMILARLY,

$$S_- |11\rangle = \sqrt{2} \hbar |10\rangle$$

$$S_- |10\rangle = \sqrt{2} \hbar |1-1\rangle$$

$$S_- |1-1\rangle = 0$$

OR  $S_- = S_+^\dagger$

BOTH  $\Rightarrow S_- = \begin{pmatrix} 0 & 0 & 0 \\ \sqrt{2} & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{pmatrix}$

#4(b)  $S_+ = S_x + i S_y$

$$S_- = S_x - i S_y$$

$$\Rightarrow S_x = \frac{1}{2} (S_+ + S_-)$$

$$S_y = \frac{1}{2i} (S_+ - S_-)$$

From ABOVE,

$$S_x = \hbar \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix}$$

$$S_y = \hbar \begin{pmatrix} 0 & -i/\sqrt{2} & 0 \\ i/\sqrt{2} & 0 & -i/\sqrt{2} \\ 0 & i/\sqrt{2} & 0 \end{pmatrix}$$

#5

$$(a) A(t) = a(t) e^{i\omega_0 t}$$

$$\dot{A}(t) = \dot{a}(t) e^{i\omega_0 t} + a(t) (i\omega_0) e^{i\omega_0 t}$$

$$i \dot{A}(t) = i \dot{a}(t) e^{i\omega_0 t} - \omega_0 a(t) e^{i\omega_0 t}$$

$$= i \dot{a}(t) e^{i\omega_0 t} - \omega_0 A(t)$$

$$= -\omega_0 A(t) + (\omega_0 a(t) + \omega_1 b(t) \cos \omega t) e^{i\omega_0 t}$$

$$= -\omega_0 A(t) + \omega_0 A(t) + \omega_1 b(t) \cos \omega t e^{i\omega_0 t}$$

$$i \dot{A}(t) = \omega_1 B(t) \cos \omega t e^{2i\omega_0 t} \quad (1)$$

Similarly,

$$\dot{B}(t) = \dot{b}(t) e^{-i\omega_0 t} + b(t) (-i\omega_0) e^{-i\omega_0 t}$$

$$i \dot{B}(t) = i \dot{b}(t) e^{-i\omega_0 t} + \omega_0 b(t) e^{-i\omega_0 t}$$

$$i \dot{B}(t) = +\omega_0 b(t) e^{-i\omega_0 t} + (\omega_1 a(t) \cos \omega t - \omega_0 b(t)) e^{-i\omega_0 t}$$

~~$i \dot{B}(t) =$~~

$$i \dot{B}(t) = \omega_1 A(t) \cos \omega t e^{-2i\omega_0 t} \quad (2)$$

#5(b) USE THE ROTATING WAVE APPROXIMATION,

$$\cos \omega t e^{2i\omega_0 t} \simeq \frac{1}{2} e^{i(2\omega_0 - \omega)t}$$

REWRITE EQ (1) FROM (a) AS

$$\boxed{i\dot{A}(t) \simeq \frac{1}{2}\omega_1 B(t) e^{i(2\omega_0 - \omega)t}} \quad (3)$$

REWRITE EQ (2) FROM (a) AS

$$\boxed{i\dot{B}(t) \simeq \frac{1}{2}\omega_1 A(t) e^{-i(2\omega_0 - \omega)t}} \quad (4)$$

(c) DIFFERENTIATE EQ. (3) AND USE (4) TO OBTAIN

$$d^2 A/dt^2 = (2\omega_0 - \omega) i dA/dt - \left(\frac{\omega_1}{2}\right)^2 A(t) \quad (5)$$

$$\text{TRY } A(t) = A_0 e^{i\Omega t}$$

$$\dot{A}(t) = i\Omega A_0 e^{i\Omega t}$$

$$\ddot{A}(t) = -\Omega^2 A_0 e^{i\Omega t}$$

SUB THESE RESULTS INTO (5):

$$-\Omega^2 = \frac{-\omega_1^2}{4} - (2\omega_0 - \omega)\Omega$$

$$\Omega^2 - (2\omega_0 - \omega)\Omega - (\omega_1/2)^2 = 0$$

$$\Rightarrow \Omega = \frac{+(2\omega_0 - \omega) \pm [(2\omega_0 - \omega)^2 + \omega_1^2]^{1/2}}{2}$$

$$\therefore \Omega = \left(\omega_0 - \frac{\omega}{2}\right) \pm \left[\left(\omega_0 - \frac{\omega}{2}\right)^2 + \frac{\omega_1^2}{4}\right]^{1/2}$$

$$(d) A(t) = A_+ e^{i\Omega_+ t} + A_- e^{-i\Omega_- t}$$

$$\text{Since } i\dot{A}(t) = \frac{\omega_1}{2} B(t) e^{i(2\omega_0 - \omega)t}$$

$$B(t) = \frac{2i}{\omega_1} \dot{A}(t) e^{-i(2\omega_0 - \omega)t}$$

$$= \frac{2i}{\omega_1} e^{-i(2\omega_0 - \omega)t} \left[ A_+ i\Omega_+ e^{i\Omega_+ t} + iA_- \Omega_- e^{i\Omega_- t} \right]$$

$$= -\frac{2}{\omega_1} e^{-i(2\omega_0 - \omega)t} \left[ A_+ \Omega_+ e^{i\Omega_+ t} + A_- \Omega_- e^{i\Omega_- t} \right]$$

(1) (2) (8)

Now,

$$\text{Term (1)} = e^{-i(2\omega_0 - \omega)t} e^{i\Omega_+ t} = e^{i\left[\left(\omega_0 - \frac{\omega}{2}\right) + \sqrt{-2\omega_0 + \omega}\right]t}$$

$$= e^{i\left(-\omega_0 + \frac{\omega}{2} + \sqrt{\quad}\right)t}$$

$$(1) = e^{-i\left[\left(\omega_0 - \frac{\omega}{2}\right) - \sqrt{\quad}\right]t} = e^{-i\Omega_- t}$$

$$\omega/\sqrt{\quad} = \left[\left(\omega_0 - \frac{\omega}{2}\right)^2 + \omega_1^2/4\right]^{1/2}$$

LIKEWISE, TERM ② CAN BE WRITTEN AS

$$\textcircled{2} = e^{-i(2\omega_0 - \omega)t} e^{i\Omega_- t}$$

$$= e^{i\left[\omega_0 - \frac{\omega}{2} - \sqrt{-2\omega_0 + \omega}\right]t}$$

$$= e^{i\left[-\omega_0 + \frac{\omega}{2} - \sqrt{-\phantom{-2\omega_0 + \omega}}\right]t}$$

$$= e^{-i\left[\omega_0 - \frac{\omega}{2} + \sqrt{-\phantom{-2\omega_0 + \omega}}\right]t} = e^{-i\Omega_+ t}$$

COLLECTING RESULTS AND SUB'ING INTO EQ (8) YIELDS

$$B(t) = \frac{-Z}{\omega_1} \left( \Omega_+ A_+ e^{-i\Omega_- t} + \Omega_- A_- e^{-i\Omega_+ t} \right)$$

(e)  $|\langle \downarrow | \text{SPIN}(t) \rangle|^2 = \text{PROBABILITY OF MEASURING SPIN DOWN}$

$$= \left| (0 \ 1) \begin{pmatrix} a(t) \\ b(t) \end{pmatrix} \right|^2 = |b(t)|^2$$

$$\text{w/ } b(t) = B(t) e^{-i\omega_0 t}$$

$$|b(t)|^2 = |B(t)|^2$$

$$\begin{aligned}
 |B(t)|^2 &= \left(\frac{2}{\omega_1}\right)^2 \left| \frac{\Omega_+ \Omega_- e^{+i\Omega_- t}}{\Omega_- - \Omega_+} - \frac{\Omega_- \Omega_+ e^{+i\Omega_+ t}}{\Omega_- - \Omega_+} \right|^2 \\
 &= \frac{4}{\omega_1^2} \left[ \frac{\Omega_+ \Omega_-}{\Omega_- - \Omega_+} \right]^2 \left| e^{+i\Omega_- t} - e^{+i\Omega_+ t} \right|^2 \quad (12)
 \end{aligned}$$

BUT

$$| |^2 = \left| e^{+i\Omega_- t} (1 - e^{+i(-\Omega_- + \Omega_+)t}) \right|^2$$

$$= \left| 1 - e^{+i(-\Omega_- + \Omega_+)t} \right|^2$$

$$= \left| 1 - e^{+i\Delta t} \right|^2 \quad \omega/2 \equiv \Omega_+ - \Omega_-$$

$$= \left| e^{i\Delta t/2} (e^{-i\Delta t/2} - e^{+i\Delta t/2}) \right|^2$$

$$= \left| e^{i\Delta t/2} 2i \sin \Delta t/2 \right|^2$$

$$= 4 \sin^2 \Delta t/2 = 4 (1 - \cos \Delta t)$$

$$| |^2 = 4 \left[ 1 - \cos(\Omega_+ - \Omega_-)t \right]$$

SUB THIS INTO EQ (12):

$$P(t) = |B(t)|^2 = \frac{4}{\omega_1^2} \left( \frac{\Omega_+ \Omega_-}{\Omega_- - \Omega_+} \right)^2 (1 - \cos(\Omega_+ - \Omega_-)t)$$

#5 (f).

$$AT \quad \omega = 2\omega_0 :$$

$$\Omega_+ = \omega_1/2$$

$$\Omega_- = -\omega_1/2$$

$$\text{So, } P(t) = \frac{\omega_0}{\omega_1^2} \left( \frac{\omega_1^2/4}{-\omega_1} \right)^2 (1 - \cos(-\omega_1)t)$$

$$P(t) = \frac{1}{2} (1 - \cos \omega_1 t)$$

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