Lecture 12 Review

Simultaneous 2nd-order ODEs & solution via RK4 à la GSL Elliptical orbits as an example of simultaneous 2nd-order ODEs C++ file IO.

Return of the van der Pol oscillator

Our favorite nonlinear oscillator.

$$\ddot{x} + \mu(x^2 - a^2)\dot{x} + \omega_0^2 x = 0$$
 (μ is small and positive)

 μ = 0: familiar simple harmonic motion (SHM)

 $x^2 - a^2 > 0$: damped SHM

 $x^2 - a^2 < 0$: "anti-damped" SHM

Note $x^2 - a^2$ reverses sign as x evolves with time.

Equilibrium motion of x results. (You saw this for yourself last time.)

vdpol.cc

Need a way to use more than 1 parameter in an ODE.

Copy vdpol.cc

```
int
   func (double t, const double y[], double f[],
      void *params)
    struct duo{ // this object holds 2 parameters
     double mu;
     double a;
    duo PARAM;
    PARAM = *(duo *)params;
         double mu = *(double *)params;
    f[0] = y[1];
    f[1] = -y[0] - PARAM.mu*y[1]*(y[0]*y[0] - pow(PARAM.a, 2.0)); // CHANGE ME
    return GSL_SUCCESS;
```

C++ struct data structure

```
// struct construction
#include <iostream>
using namespace std;
int main()
 struct triplet{
    double a;

    Defines variable type "triplet"

    double b;
    double c;
                  Don't forget semicolon (;) !!
triplet Test; - Declares variable Test
    Test.a = 10.0;
    Test.b = 15.0;
    Test.c = 30.0;
```

Peculiarities of Non-linear Systems

$$\frac{\Delta N_i}{\Delta t} = \lambda' N_i$$
 Similar to radioactive decay

limiting population

$$\lambda' = \lambda(N_* - N_i)$$

 $\lambda' = \lambda(N_* - N_i)$ Growth rate slows as N_* approached.

$$\Rightarrow \frac{\Delta N_i}{\Delta t} = \lambda (N_* - N_i) N_i$$
 Typo(s) in book: no λ'

$$N_{i+1} = N_i + \lambda \Delta t (N_* - N_i) N_i$$
 "new" = "old" + "change"

$$=N_i(1+\lambda \Delta t N_*)\left[1-rac{\lambda \Delta t}{1+\lambda \Delta t N_*}N_i
ight]$$

$$\mu \equiv 1 + \lambda \Delta t N_*$$

μ is a kind of growth parameter $\lambda \Delta t$ is the number of insects born/generation

$$x_i \equiv rac{\lambda \Delta t}{\mu} N_i \simeq rac{N_i}{N_*}$$
 $0 \leq \mathsf{x_i} \leq 1$

$$0 \le x_i \le 1$$

$$x_{i+1} = \mu x_i (1 - x_i)$$
 "Logistic map"

Imap.cc

Peculiarities of Non-linear Systems (2)

In class exercise:

Plot x_i versus "generation number i

$$x_{i+1} = \mu x_i (1 - x_i)$$

Try μ = 0.75, 2.8. 3.3, 3.5. What do you notice?

Fixed points and 1D maps

$$x_{i+1} = \mu x_i (1 - x_i)$$

$$|x_{i+1} = f(x_i)|$$

 $x_{i+1} = f(x_i)$ General notation for a map.

In certain cases, $f(x^*) = x^*$ x^* is a "fixed point."

$$x^* = \mu x^* (1 - x^*)$$

$$x^* = \frac{\mu - 1}{\mu}$$

or
$$x^* = 0$$

 $x^* = \frac{\mu - 1}{\mu}$ or $x^* = 0$ x^* can be stable or unstable

Suppose you are close to but not exactly at x* Do you head toward x* or away?

$$x_n = x^* + \eta_n$$
 or \downarrow

$$x^* + \eta_{n+1} = x_{n+1} = f(x^* + \eta_n) = f(x^*) + f'(x^*)\eta_n + \mathcal{O}(\eta_n^2)$$

$$\eta_{n+1} = f'(x^*)\eta_n + \mathcal{O}(\eta_n^2)$$
Mr. Taylor ...

Fixed points and 1D maps (2)

$$\eta_{n+1} = f'(x^*)\eta_n + \mathcal{O}(\eta_n^2)$$

$$\eta_{n+1} \simeq f'(x^*)\eta_n$$

Note that if $|f'(x^*)| < 1$, $\eta_{n+1} \rightarrow 0$.

Note that if $|f'(x^*)| > 1$, $\eta_{n+1} \to \infty$.

$$\frac{df}{dx}|_{x^*} = \mu - 2\mu x^* = \left\{ \begin{array}{c} \mu \\ 2 - \mu \end{array} \right.$$

x* is a stable fixed point.

x* is an unstable fixed point.

Stable at $x^* = 0$ if $\mu < 1$ Stable at $x^* = (\mu - 1)/\mu$ if $\mu < 3$

Summary

How to use multiple parameters in an ODE. (vdpol.cc)

C++ struct structure

Intro to the logistic map

Don't suffer in silence. Scream for help!!!

Appendix

Orbit slides for easy reference

Reminder: Simultaneous 2nd-order ODEs

Suppose we have a pair of simultaneous 2nd-order ODEs.

$$\ddot{x} = f(t, x, y, \dot{x}, \dot{y})$$

$$\ddot{y} = g(t, x, y, \dot{x}, \dot{y})$$

What do we do?

$$d\vec{y}/dt = \vec{f}(t, \vec{y})$$
 ("standard "form")

$$\vec{y} = \begin{pmatrix} y^{(0)}(t) \\ y^{(1)}(t) \\ \vdots \\ y^{(N-1)}(t) \end{pmatrix}$$

$$\vec{y} = \begin{pmatrix} y^{(0)}(t) \\ y^{(1)}(t) \\ \vdots \\ y^{(N-1)}(t) \end{pmatrix} \vec{f} = \begin{pmatrix} f^{(0)}(t, \vec{y}) \\ f^{(1)}(t, \vec{y}) \\ \vdots \\ f^{(N-1)}(t, \vec{y}) \end{pmatrix}$$

$$y^{(0)}(t) = x(t)$$
 $y^{(2)}(t) = y(t)$

$$y^{(2)}(t) = y(t)$$

$$y^{(1)}(t) = \dot{x}(t)$$
 $y^{(3)}(t) = \dot{y}(t)$

$$y^{(3)}(t) = \dot{y}(t)$$

Repeat: Example of Simultaneous 2nd-order ODEs

What to use for $f^{(0)}$, $f^{(1)}$, ...?

$$f^{(0)}(t, \vec{y}) = y^{(1)}(t) \ \ (=\dot{x})$$

$$f^{(2)}(t, \vec{y}) = y^{(3)}(t) \ (= \dot{y})$$

$$f^{(1)}(t, \vec{y}) = \dot{y}^{(1)}(t) \ \ (= \ddot{x})$$

$$f^{(3)}(t, \vec{y}) = \dot{y}^{(3)}(t) \ (= \ddot{y})$$

If we had more coupled equations, we just add <u>pairs</u> of y and f as here.

Example: Planetary motion. (See *CP*, sec 15.11)

$$f = -\frac{GMm}{r^2}$$

 $f = -\frac{GMm}{r^2}$ Attractive force exerted on m by M along center-line.

$$\vec{f} = m\vec{a} = m\frac{d^2\vec{r}}{dt^2}$$

$$f_x = f\cos\theta = frac{x}{r}$$
 $f_y = f\sin\theta = frac{y}{r}$

$$f_y = f \sin \theta = f \frac{y}{r}$$

$$r = \sqrt{x^2 + y^2}$$

$$\frac{d^2x}{dt^2} = -GM\frac{x}{r^3}$$

$$\frac{d^2y}{dt^2} = -GM\frac{y}{r^3}$$

$$\frac{d^2y}{dt^2} = -GM\frac{y}{r^3}$$

Reminder: Elements of Orbital Mechanics

Consider the case where a small object (e.g., a comet) orbits the Sun.

$$ec{F} = -rac{GMm}{|r|^2}\hat{r}$$

$$E = \frac{1}{2}mv^2 - \frac{GMm}{r}$$

$$\vec{L} = \vec{r} \times (m\vec{v})$$

conserved

$$\frac{mv^2}{r} = \frac{GMm}{r^2}$$

$$v = \sqrt{GM/r}$$

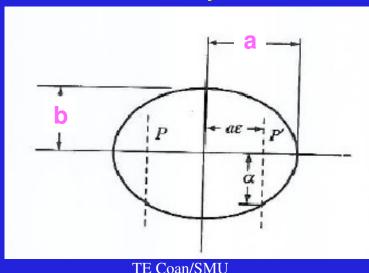
$$E = -\frac{GMm}{2r}$$

Circular orbits only

$$e = \sqrt{1 - b^2/a^2}$$

a = "semi-major axis"

b = "semi-minor axis"



Earth_e = 0.017

Elliptical Orbits and Kepler's 3rd Law

For <u>elliptical</u> orbits around Sun, we have:

$$E = -\frac{GMm}{2a}$$

$$v = \sqrt{GM\left(\frac{2}{r} - \frac{1}{a}\right)}$$

$$T^2 = \frac{4\pi^2}{GM}a^3$$

Exact only for m << M

$$G=6.67 imes10^{-11}\,\mathrm{m}^3/\mathrm{kg}\mathrm{-sec}^2$$

$$1\,{\sf AU} = 150 imes 10^6\,{\sf km} = 1.50 imes 10^{11}\,{\sf m}$$

$$1\,\mathrm{yr} = \pi \times 10^7\,\mathrm{sec}$$

$$M_{\odot}=2.0 imes10^{30}\,\mathrm{kg}$$

$$[r] = AUs$$

$$[t] = years$$

$$GM_{\odot} = 4\pi^2 AU^3/yr^2$$

Useful for calc's w/ orbit.cc

orbit.cc

In class exercise:

Copy orbit.cc

For simplicity, set GM = 1.

Initial conditions:

$$x(0) = 0.5$$

$$|y(0) = 0.0$$

$$v_x(0) = 0.0$$

$$y(0) = 0.0$$
 $v_x(0) = 0.0$ $v_y(0) = 1.63$

Adjust number and size of time steps to see orbit close. Visualize w/ gnuplot.

Q: Suppose
$$f = kr^{-n}, n \neq 2$$

How is orbit effected?

Mercury's orbit shows such an effect. $f = kr^{-2} + (k'r^{-4})$

$$f = kr^{-2} + k'r^{-4}$$

Gen'l Relativity

