1. The matrix A=		
1/√2	1/√2	0
0	0	1
1/√2	-1/√2	0

represents a finite rotation about a certain axis. Find the direction cosines of the axis and the angle of rotation.

- 2. Consider the Foucault Pendulum. Compute the rotation frequency of the pendulum as a function of the co-latitude θ .
- 3. The matrix L represents a rotation by an angle ϕ around some axis. The eigenvalues of L are $\lambda 1 = +1$, $\lambda 2 = (\sqrt{3}+i)/2$. $\lambda 3 = (\sqrt{3}-i)/2$. Find the angle ϕ .
- 4. Consider a tensor of third rank whose components t_{ijk} are antisymmetric under exchange of any two indices. Show that a single number is sufficient to characterize this tensor and that this number transforms like a pseudoscalar.
- 5. We want to demonstrate that the 3x3 and 2x2 representation of rotations are identical for infinitesimal rotations on a vector v={x,y,z}. The 3x3 rotations can be represented as Exp[θ n•M] where n is the axis vector, and M are the matrix generators of the rotation, and the rotated vector is Exp[θ n•M]•v. The 2X2 rotations can be represented as Exp[-I θ/2 n•σ] where n is the axis vector, and σ are the matrix generators of the rotation, and the rotated vector is Exp[-I θ/2 n•σ]•v.
 a) Perform an infinitesimal rotation about the x-axis with both representations, and show the components transform identically.
 b) Repeat for the y-axis.
 c) Repeat for the z-axis.