1. The matrix $\mathrm{A}=$

| $1 / \sqrt{ } 2$ | $1 / \sqrt{ } 2$ | 0 |
| :---: | :---: | :---: |
| 0 | 0 | 1 |
| $1 / \sqrt{ } 2$ | $-1 / \sqrt{ } 2$ | 0 |

represents a finite rotation about a certain axis. Find the direction cosines of the axis and the angle of rotation.
2. Consider the Foucault Pendulum. Compute the rotation frequency of the pendulum as a function of the co-latitude $\theta$.
3. The matrix $L$ represents a rotation by an angle $\phi$ around some axis. The eigenvalues of L are $\lambda 1=+1, \lambda 2=(\sqrt{3}+\mathrm{i}) / 2 . \lambda 3=(\sqrt{3}-\mathrm{i}) / 2$. Find the angle $\phi$.
4. Consider a tensor of third rank whose components $\mathrm{t}_{\mathrm{ijk}}$ are antisymmetric under exchange of any two indices. Show that a single number is sufficient to characterize this tensor and that this number transforms like a pseudoscalar.
5. We want to demonstrate that the $3 \times 3$ and $2 \times 2$ representation of rotations are identical for infinitesimal rotations on a vector $\mathrm{v}=\{\mathrm{x}, \mathrm{y}, \mathrm{z}\}$.
The $3 \times 3$ rotations can be represented as $\operatorname{Exp}[\theta n \cdot M]$ where $n$ is the axis vector, and $M$ are the matrix generators of the rotation, and the rotated vector is $\operatorname{Exp}[\theta n \cdot M] \cdot v$.
The 2 X 2 rotations can be represented as $\operatorname{Exp}[-\mathrm{I} \theta / 2 n \bullet \sigma]$ where $n$ is the axis vector, and $\sigma$ are the matrix generators of the rotation, and the rotated vector is $\operatorname{Exp}[-\mathrm{I} \theta / 2 n \cdot \sigma] \cdot v$.
a) Perform an infinitesimal rotation about the $x$-axis with both representations, and show the components transform identically.
b) Repeat for the $y$-axis.
c) Repeat for the $z$-axis.

