

Newton's Law

$$F = ma = \dot{p}$$

D'Alembert's Principle

$$(\dot{p} - F_A) \delta q = 0$$

Constraint forces do no work

Lagrange Equations

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) - \frac{\partial L}{\partial q} = 0 \quad L = T - V$$

Hamilton's Equations

Symmetric in q and p

$$\frac{\partial H}{\partial p} = +\dot{q}$$

$$\frac{\partial H}{\partial q} = -\dot{p}$$

$$H(q, p) = \dot{q} p - L(q, \dot{q})$$

Least Action Principle

Compact Statement

$$\delta S = 0 = \delta \int dt L(q, \dot{q})$$

Lagrangian

$$L(q, \dot{q})$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) - \frac{\partial L}{\partial q} = 0$$

$$\frac{\partial L}{\partial \dot{q}} = \overset{\circ}{p}$$

$$\frac{\partial L}{\partial q} = -\overset{\circ}{p}$$

Hamiltonian

$$H(q, p)$$

$$H(q, p) = \overset{\circ}{q} p - L(q, \dot{q})$$

$$\frac{\partial H}{\partial p} = \overset{\circ}{q}$$

$$\frac{\partial H}{\partial q} = -\overset{\circ}{p}$$

SHO Lagrangian

$$L = T - V = \frac{m \dot{q}^2}{2} - \frac{k q^2}{2}$$

$$E_{eqs} \Rightarrow m \ddot{q} + k q = 0$$

$$q = e^{i\omega t} \Rightarrow \omega = \sqrt{\frac{k}{m}}$$

One 2nd-order DEQ.

SHO Hamiltonian

$$H = T + V = \frac{p^2}{2m} + \frac{k q^2}{2}$$

$$\frac{\partial H}{\partial p} = \frac{p}{m} = \overset{\circ}{q}$$

$$\frac{\partial H}{\partial q} = k q = -\overset{\circ}{p}$$

$$p = m \dot{q}$$

$$-k q = \overset{\circ}{p}$$

$$p = m v$$

$$-k x = F$$

Hooke's Law

SHO || Hamiltonian $\mu = \frac{K}{m}$

$$F = -Kx \quad V = \frac{1}{2} Kx^2 \quad T = \frac{1}{2} m v^2$$

$$L(q, \dot{q}) = T - V = \frac{m}{2} \dot{q}^2 - \frac{K}{2} q^2$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} - \frac{\partial L}{\partial q} = \boxed{m \ddot{q} + Kq = 0} \quad \text{Lagrange Eq.}$$

$$H = P \dot{q} - L = \frac{P^2}{m} - \frac{P^2}{2m} + \frac{K}{2} q^2 = \frac{P^2}{2m} + \frac{K}{2} q^2$$

$$H = T + V \quad \left[\text{is } t \text{ invariant !!!} \right]$$

$$\boxed{\frac{\partial H}{\partial P} = \dot{q} \quad \frac{\partial H}{\partial q} = -\dot{P}}$$

$$\frac{\partial H}{\partial P} = \frac{P}{m} = \dot{q} \Rightarrow P = m \dot{q} = m v$$

$$\frac{\partial H}{\partial q} = Kq = -\dot{P} \Rightarrow \dot{P} = F = -Kx \quad \text{Hook's Law}$$

$$\dot{P} = -Kq \Rightarrow (m \ddot{q}) = m \ddot{q} = -Kq$$

$$\boxed{m \ddot{q} + Kq = 0} \quad \text{Equiv to Lagrangian}$$

Atwood



$$T = \frac{1}{2} (m_1 + m_2) \dot{x}^2 =$$

$$V = - (m_1 - m_2) g x$$

$$P = \frac{\partial \mathcal{L}}{\partial \dot{x}} = (m_1 + m_2) \dot{x}$$

$$H = T + V = \frac{P^2}{2(m_1 + m_2)} - (m_1 - m_2) g x$$

$$\frac{\partial H}{\partial P} = \frac{P}{m_1 + m_2} = \dot{q} \Rightarrow P = (m_1 + m_2) \dot{q}$$

$$\frac{\partial H}{\partial x} = - (m_1 - m_2) g = - \dot{P}$$

$$\overset{\circ}{\circ} F = \dot{P} = (m_1 - m_2) g$$

$$\dot{P} = (m_1 + m_2) \ddot{q} = (m_1 - m_2) g$$

$$\ddot{q} = \left(\frac{m_1 - m_2}{m_1 + m_2} \right) g$$