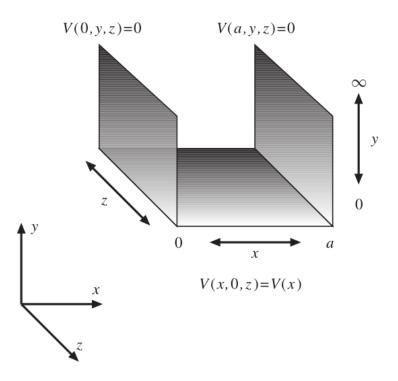
PROBLEM 2 Potential in a Rectangular Groove. Consider a rectangular groove that runs from $z = -\infty$ to $+\infty$ and is open in the positive *y*-direction. The groove is bounded by two parallel walls at x = 0, x = a, and at the y = 0 end. The walls at x = 0 and x = aare at zero potential and the end is at a specified potential V[x] that is independent of the *z*coordinate. The boundary conditions suggest that the potential is independent of *z*. Express the potential as a superposition of products X[x]Y[y], where $X[x] = {Sin[\alpha x], Cos[\alpha x]}$ and $Y[y] = {e^{+\gamma y}, e^{-\gamma y}}$. The relation between the separation constants is $\alpha^2 = \gamma^2$.

a. Express the expansion coefficients as integrals over the potential X[x] given on the y = 0 end.



- **b.** Let X[x] = Sin[x] and write the first few terms of the potential. Plot the potential using the command **Plot3D**. Use the user-defined command **VEPlot** to plot the equipotential and electric field lines.
- c. Let X[x] = V0 and sum the series to get an exact solution. Plot the potential using **Plot3D**.
- **db**. Consider the case where the potential on the end of the groove is **V**[**x**]=**Sin**[**x**].

- 7. Solve Problem 2 if the sides x = 0 and x = 1 are insulated.
- 19. A long conducting cylinder is placed parallel to the z axis in an originally uniform electric field in the negative x direction. The cylinder is held at zero potential. Find the potential in the region outside the cylinder. *Hints:* See Problem 7.13. You want solutions of Laplace's equation in polar coordinates (Problem 5.12).

##) For the Laplacian equation in Cartesian coordinates in3-D: {x,y,z}

- separate the variables to obtain the differential equations for the 3 coordinates.
- Find the function that satisfies each of the differential equations.

##) For the Laplacian equation in Polar coordinates in 3-D: $\{r, z, \phi\}$

- separate the variables to obtain the differential equations for the 3 coordinates.
- Find the function that satisfies each of the differential equations.

##) For the Laplacian equation in Spherical coordinates in 3-D: {r, θ , ϕ }

- separate the variables to obtain the differential equations for the 3 coordinates.
- Find the function that satisfies each of the differential equations.

2.9 Separation of Variables; Laplace Equation in Rectangular Coordinates

The partial differential equations of mathematical physics are often solved conveniently by a method called *separation of variables*. In the process, one often generates orthogonal sets of functions that are useful in their own right. Equations involving the three-dimensional Laplacian operator are known to be separable in eleven different coordinate systems (see *Morse and Feshbach*, pp. 509, 655). We discuss only three of these in any detail—rectangular, spherical, and cylindrical—beginning with the simplest, rectangular coordinates.

The Laplace equation in rectangular coordinates is

$$\frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} + \frac{\partial^2 \Phi}{\partial z^2} = 0$$
(2.48)

A solution of this *partial* differential equation can be found in terms of three ordinary differential equations, all of the same form, by the assumption that the potential can be represented by a product of three functions, one for each coordinate:

$$\Phi(x, y, z) = X(x)Y(y)Z(z)$$
(2.49)

Substitution into (2.48) and division of the result by (2.49) yields

$$\frac{1}{X(x)}\frac{d^2X}{dx^2} + \frac{1}{Y(y)}\frac{d^2Y}{dy^2} + \frac{1}{Z(z)}\frac{d^2Z}{dz^2} = 0$$
(2.50)

where total derivatives have replaced partial derivatives, since each term involves a function of one variable only. If (2.50) is to hold for arbitrary values of the independent coordinates, each of the three terms must be separately constant:

$$\frac{1}{X}\frac{d^{2}X}{dx^{2}} = -\alpha^{2}$$

$$\frac{1}{Y}\frac{d^{2}Y}{dy^{2}} = -\beta^{2}$$

$$\frac{1}{Z}\frac{d^{2}Z}{dz^{2}} = \gamma^{2}$$
(2.51)

where

$$\alpha^2 + \beta^2 = \gamma^2$$

If we arbitrarily choose α^2 and β^2 to be positive, then the solutions of the three ordinary differential equations (2.51) are $e^{\pm i\alpha x}$, $e^{\pm i\beta y}$, $e^{\pm \sqrt{\alpha^2 + \beta^2 z}}$. The potential (2.49) can thus be built up from the product solutions:

$$\Phi = e^{\pm i\alpha x} e^{\pm i\beta y} e^{\pm \sqrt{\alpha^2 + \beta^2 z}}$$
(2.52)

3.7 Laplace Equation in Cylindrical Coordinates; Bessel Functions

In cylindrical coordinates (ρ , ϕ , z), as shown in Fig. 3.8, the Laplace equation takes the form:

$$\frac{\partial^2 \Phi}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial \Phi}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 \Phi}{\partial \phi^2} + \frac{\partial^2 \Phi}{\partial z^2} = 0$$
(3.71)

The separation of variables is accomplished by the substitution:

$$\Phi(\rho, \phi, z) = R(\rho)Q(\phi)Z(z)$$
(3.72)

In the usual way this leads to the three ordinary differential equations:

$$\frac{d^2 Z}{dz^2} - k^2 Z = 0 (3.73)$$

$$\frac{d^2Q}{d\phi^2} + \nu^2 Q = 0 \tag{3.74}$$

$$\frac{d^2R}{d\rho^2} + \frac{1}{\rho}\frac{dR}{d\rho} + \left(k^2 - \frac{\nu^2}{\rho^2}\right)R = 0$$
(3.75)

The solutions of the first two equations are elementary:

$$Z(z) = e^{\pm kz}$$

$$Q(\phi) = e^{\pm i\nu\phi}$$
(3.76)

where $\nu = m$ is an integer and k is a constant to be determined. The radial factor is

$$R(\rho) = CJ_m(k\rho) + DN_m(k\rho)$$

If the potential is finite at $\rho = 0$, D = 0. The requirement that the potential vanish at $\rho = a$ means that k can take on only those special values:

$$k_{mn} = \frac{x_{mn}}{a}$$
 (*n* = 1, 2, 3, ...)

where x_{mn} are the roots of $J_m(x_{mn}) = 0$.

Combining all these conditions, we find that the general form of the solution is

$$\Phi(\rho, \phi, z) = \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(k_{mn}\rho) \sinh(k_{mn}z) (A_{mn} \sin m\phi + B_{mn} \cos m\phi)$$
(3.105a)

At $\tau = I$, we are given the notential as V(a, b). Therefore we have

Laplace's spherical harmonics [edit]

Main article: Spherical harmonics § Laplace's spherical harmonics

Laplace's equation in spherical coordinates is:[4]

$$abla^2 f = rac{1}{r^2}rac{\partial}{\partial r}\left(r^2rac{\partial f}{\partial r}
ight) + rac{1}{r^2\sin heta}rac{\partial}{\partial heta}\left(\sin hetarac{\partial f}{\partial heta}
ight) + rac{1}{r^2\sin^2 heta}rac{\partial^2 f}{\partialarphi^2} = 0.$$

Consider the problem of finding solutions of the form $f(r, \theta, \varphi) = R(r) Y(\theta, \varphi)$. By separation of variables, two differential equations result by imposing Laplace's equation:

$$\frac{1}{R}\frac{d}{dr}\left(r^2\frac{dR}{dr}\right) = \lambda, \qquad \frac{1}{Y}\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\left(\sin\theta\frac{\partial Y}{\partial\theta}\right) + \frac{1}{Y}\frac{1}{\sin^2\theta}\frac{\partial^2 Y}{\partial\varphi^2} = -\lambda.$$

The second equation can be simplified under the assumption that *Y* has the form $Y(\theta, \varphi) = \Theta(\theta) \Phi(\varphi)$. Applying separation of variables again to the second equation gives way to the pair of differential equations

$$egin{aligned} &rac{1}{\Phi}rac{d^2\Phi}{darphi^2} = -m^2 \ &\lambda\sin^2 heta + rac{\sin heta}{\Theta}rac{d}{d heta}\left(\sin hetarac{d\Theta}{d heta}
ight) = m^2 \end{aligned}$$

Now set

$$\mu = \cos \theta, \tag{12-11}$$

remembering that, for any function $f(\mu)$,

$$\frac{df}{d\theta} = \frac{df}{d\mu}\frac{d\mu}{d\theta} = -\sin\theta\frac{df}{d\mu} = -(1-\mu^2)^{1/2}\frac{df}{d\mu}.$$
 (12-12)

Then the Θ equation becomes Legendre's equation:

$$\frac{d}{d\mu}\left[(1-\mu^2)\frac{d\Theta}{d\mu}\right] + n(n+1)\Theta = 0.$$
(12-13)

When n is an integer, its solutions are the Legendre polynomials of Sec.

Explicit Forms of Vector Operations

Let \mathbf{e}_1 , \mathbf{e}_2 , \mathbf{e}_3 be orthogonal unit vectors associated with the coordinate directions specified in the headings on the left, and A_1 , A_2 , A_3 be the corresponding components of **A**. Then

$$\nabla \psi = \mathbf{e}_{1} \frac{\partial \psi}{\partial x_{1}} + \mathbf{e}_{2} \frac{\partial \psi}{\partial x_{2}} + \mathbf{e}_{3} \frac{\partial \psi}{\partial x_{3}}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_{1}}{\partial x_{1}} + \frac{\partial A_{2}}{\partial x_{2}} + \frac{\partial A_{3}}{\partial x_{3}}$$

$$\nabla \cdot \mathbf{A} = \mathbf{e}_{1} \left(\frac{\partial A_{3}}{\partial x_{2}} - \frac{\partial A_{2}}{\partial x_{3}} \right) + \mathbf{e}_{2} \left(\frac{\partial A_{1}}{\partial x_{3}} - \frac{\partial A_{3}}{\partial x_{1}} \right) + \mathbf{e}_{3} \left(\frac{\partial A_{2}}{\partial x_{1}} - \frac{\partial A_{1}}{\partial x_{2}} \right)$$

$$\nabla^{2} \psi = \frac{\partial^{2} \psi}{\partial x_{1}^{2}} + \frac{\partial^{2} \psi}{\partial x_{2}^{2}} + \frac{\partial^{2} \psi}{\partial x_{3}^{2}}$$

$$\nabla \psi = \mathbf{e}_{1} \frac{\partial \psi}{\partial \rho} + \mathbf{e}_{2} \frac{1}{\rho} \frac{\partial \psi}{\partial \phi} + \mathbf{e}_{3} \frac{\partial \psi}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho A_{1} \right) + \frac{1}{\rho} \frac{\partial A_{2}}{\partial \phi} + \frac{\partial A_{3}}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \mathbf{e}_{1} \left(\frac{1}{\rho} \frac{\partial A_{3}}{\partial \phi} - \frac{\partial A_{2}}{\partial z} \right) + \mathbf{e}_{2} \left(\frac{\partial A_{1}}{\partial z} - \frac{\partial A_{3}}{\partial \rho} \right) + \mathbf{e}_{3} \frac{1}{\rho} \left(\frac{\partial}{\partial \rho} \left(\rho A_{2} \right) - \frac{\partial A_{1}}{\partial \phi} \right)$$

$$\nabla^{2} \psi = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right) + \frac{1}{\rho^{2}} \frac{\partial^{2} \psi}{\partial \phi^{2}} + \frac{\partial^{2} \psi}{\partial z^{2}}$$

$$\nabla \psi = \mathbf{e}_{1} \frac{\partial \psi}{\partial \rho} + \mathbf{e}_{2} \frac{1}{r} \frac{\partial \psi}{\partial \theta} + \mathbf{e}_{3} \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{r^{2}} \frac{\partial}{\partial r} \left(r^{2} A_{1} \right) + \frac{1}{r^{2} \partial \phi^{2}} + \frac{\partial^{2} \psi}{\partial z^{2}}$$

$$\nabla \psi = \mathbf{e}_{1} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right) + \frac{1}{r^{2} \partial \phi^{2}} + \frac{\partial^{2} \psi}{\partial z^{2}}$$

$$\nabla \psi = \mathbf{e}_{1} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right) + \frac{1}{r^{2} \partial \phi} + \mathbf{e}_{3} \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi}$$

$$\nabla \cdot \mathbf{A} = \mathbf{e}_{1} \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} \left(\sin \theta A_{3} \right) - \frac{\partial A_{2}}{\partial \phi} \right]$$

$$+ \mathbf{e}_{2} \left[\frac{1}{r \sin \theta} \frac{\partial A_{1}}{\partial \phi} - \frac{1}{r \partial r} \left(rA_{3} \right) \right] + \mathbf{e}_{3} \frac{1}{r} \left[\frac{\partial}{\partial r} \left(rA_{2} \right) - \frac{\partial A_{1}}{\partial \phi} \right]$$

$$\nabla^{2} \psi = \frac{1}{r^{2}} \frac{\partial}{\partial r} \left(r^{2} \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^{2} \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^{2} \sin^{2} \theta} \frac{\partial^{2} \psi}{\partial \phi^{2}}$$

$$\left[\text{Note that } \frac{1}{r^{2}} \frac{\partial}{\partial r} \left(r^{2} \frac{\partial \psi}{\partial r} \right) = \frac{1}{r} \frac{\partial^{2}}{\partial r^{2}} \left(r\psi \right). \right]$$